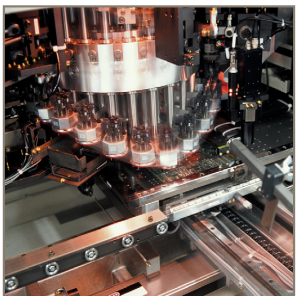




aerospace
climate control
electromechanical
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pneumatics
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PSD1 Parker Servo Drive

Standalone Servo Drive and Multi-axis Servo System



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Parker Servo Drive - PSD1

Parker Servo Drive

Overview

Description

The PSD1 is Parker Servo Drive family, available with different power rating from 2 to 30A and form factors. Today the offering contains:

The PSD1-S is a standalone drive which can be connected directly to the main supply.

The PSD1-M is a multi-axis servo system where each axis module can supply up to three servo motors. The base configuration consists of a common DC bus supply and multiple PSD1-M modules, connected through DC bus bars. The modules are available as one, two or three axis versions. This makes the system highly flexible.

PSD1-M servo system is particularly suitable for all centralized automation systems, such as those found in many packaging machines, where large numbers of drives are often required offering significant advantages.



PSD1-S unique features

- Single or three phases power supply
- Compact housing
- Particularly suitable for small machines

Standalone axis PSD1 S	Continuous current [A _{rms}]	Peak current A (≤ 2 s)
PSD1 SW1200	2	6
PSD1 SW1300	5	15

The PSD servo drive is available in two versions:

- **Basic:** Used as fieldbus slave
- **Programmable:**
 - Intelligent standalone drive
 - Runtime based on CODESYS V3
 - IEC 61131-3
 - PLCOpen function blocks

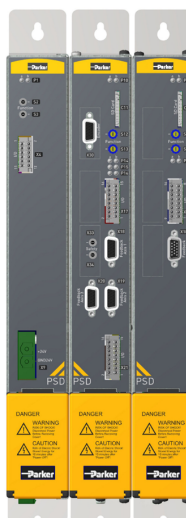
Common Features

The PSD servo drives support the following feedback systems (chosen by configuration):

- DSL (Single or Multiturn) Single cable solution
- Resolver
- 1 Vpp Rotary and Linear Encoders
- Incremental TTL Encoders
- EtherCAT / PROFINET / EtherNet/IP
- Quick and simple wiring
- Removable SD card
- Same software functionalities for standalone drive and multi-axis servo system

Applications

- Packaging machines
- Material forming machines
- Handling machines
- General automation



PSD1-M unique features

- The most compact multi-axis servo system on the market
- One, two or three axis versions combined in one housing
- Common DC bus connection for energy exchange between drives

Multi axis PSD1 M	Continuous current [A _{rms}]	Peak current A (≤ 2 s)
PSD1 MW1300	5	10
PSD1 MW1400	8	16
PSD1 MW1600	15	30
PSD1 MW1800	30	60
PSD1 MW2220	2 + 2	4 + 4
PSD1 MW2330	5 + 5	10 + 10
PSD1 MW2440	8 + 8	16 + 16
PSD1 MW3222	2 + 2 + 2	4 + 4 + 4
PSD1 MW3433	8 + 5 + 5	16 + 10 + 10

PSD1 Overview

Communications

The support of all common Fieldbus interfaces is an essential feature of open systems. The PSD is based on the modern Ethernet based interfaces such as EtherCAT, PROFINET and EtherNet IP.

Feedback Systems

The PSD servo drives support the following feedback systems:

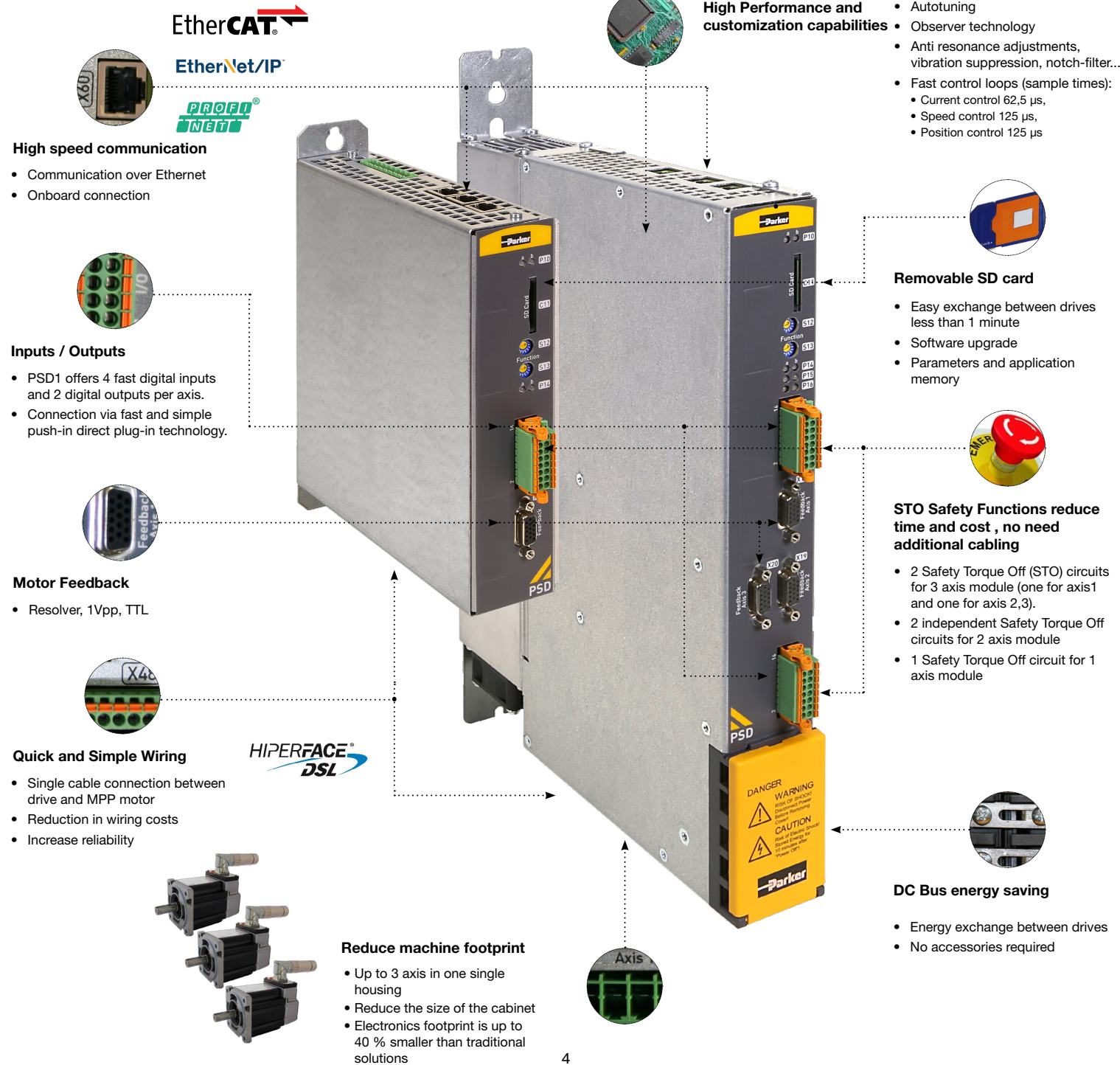
- DSL (Single or Multiturn) Single cable solution
- Resolver
- 1 Vpp Rotary and Linear Encoders
- Incremental TTL Encoders
- Analog hall

All different Feedbacks can be used on identical hardware, kind of feedback can be chosen using simple software configuration

Note: On all single axis devices the full set of feedback is possible, and can be chosen by configuration. On double and triple axis modules either DSL or resolver can be configured.

The PSD is available in two versions:
B: Basic
 The drive is used as slave on various field busses communicating via state machines

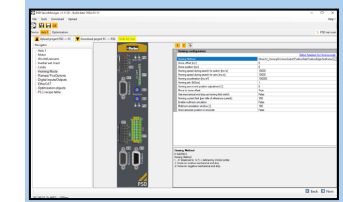
C: Programmable
 This drive version is fully programmable via IEC 61131 and offers the full set of programming languages and a complete set of function blocks including DS402 and Profidrive state machine



Parker Servo Drive Overview

Parker Servo Manager

The set-up and commissioning of the drive can be done easily using the wizard based configuration tool. Parker motors will be recognized by an electronic nameplate.




- Wizard-guided configuration and parametrization
- Graphical diagnostics / maintenance / service
 - Setup mode (absolute / relative movements, homing, jog, ...)
 - Adjustable four channel oscilloscope (single / normal / auto / roll)
 - Export as image or table (CSV format)
 - Autotuning via automated inertia identification
 - Enhanced optimization possibilities
 - Configurable status overview

Parker Servo Drive PSD1
Technical Characteristics


Technical Characteristics


Technical Data


PSD1 SW Standalone Axis

	Type		Standalone Axis	
	Input voltage	VAC	3*230 VAC ±10 % 50...60 Hz 1*230 VAC ±10 % 50...60 Hz 30...253 VAC	
	PWM Frequency nom.	kHz	8	8
	Possible PWM frequency	kHz	4 / 8 / 16	4 / 8 / 16
	Continuous current	A	2	5
	Peak current (≤ 2 s)	A	6	15

PSD1 MW Multi-Axis Module

	Type		Single Axis			
	DC Bus voltage	VDC	325...680 VDC ±10 % (Rated voltage 560 VDC)			
	PWM Frequency nom.	kHz	8	8	4	4
	Possible PWM frequency	kHz	4 / 8 / 16	4 / 8 / 16	4 / 8 / 16	4 / 8 / 16
	Continuous current	A	5	8	15	30
	Peak current (≤ 2 s)	A	10	16	30	60

	Type		Twin Axis		
	DC Bus voltage	VDC	325...680 VDC ±10 % (Rated voltage 560 VDC)		
	PWM Frequency nom.	kHz	8	8	8
	Possible PWM frequency	kHz	4 / 8 / 16	4 / 8 / 16	4 / 8 / 16
	Continuous current*	A	2 + 2	5 + 5	8 + 8
	Peak current (≤ 2 s)	A	4 + 4	10 + 10	16 + 16

	Type		Triple Axis		
	DC Bus voltage	VDC	325...680 VDC ±10 % (Rated voltage 560 VDC)		
	PWM Frequency nom.	kHz	8	8	
	Possible PWM frequency	kHz	4 / 8 / 16	4 / 8 / 16	
	Continuous current*	A	2 + 2 + 2	8 + 5 + 5	
	Peak current (≤ 2 s)	A	4 + 4 + 4	16 + 10 + 10	

*with an continuous limit current at 16A max. by module

PSD1-MW-P - Power Supply Unit

Mains Supply

Power Supply Type	Unit	PSD1 MW P010			with IND-0001-02*			PSD1 MW P020			with IND-0002-0x*		
Input Voltage		3*230 ... 480 VAC ±10 % 50...60 Hz (Rated voltage 3*400 VAC)											
Output Voltage		325...680 VDC ±10 % (Rated voltage 560 VDC)											
Supplied Voltage	[VAC]	230	400	480	230	400	480	230	400	480	230	400	480
Output Power	[kVA]	6	10	10	9	15	15	12	20	20	19	30	30
Peak Output Power (<5 s)	[kVA]	12	20	20	18	30	30	24	40	40	36	60	60

Control Supply

Rated Input Voltage		24 VDC ±10 %											
Maximum Ripple		1 V _{pkpk}											
Supply Current	[A]	0.2 A			0.8 A			0.3 A			0.3 A		

*) Operation of the P010 and P020 power supplies with additional line choke (to be ordered separately).

Environmental Characteristics

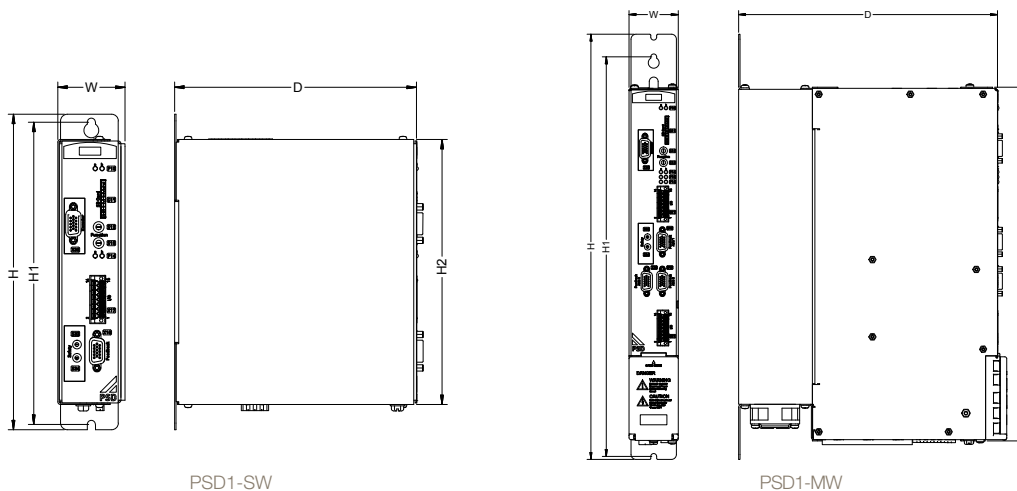
Operating Temperature	0...+40 °C
Storage Temperature	-25 °C...+70 °C
Shipping Temperature	-25 °C...+70 °C
Product Enclosure Rating	IP20 (only in closed electrical cabinet) UL open type equipment
Altitude	1000 m ASL. Derate output current by 1.0 % per 100 m to a maximum of 2000 m
Operating Humidity	Class 3K3 - Maximum 85 % non-condensing
Storage Humidity	Class 1K3 - Maximum 95 % non-condensing
Shipping Humidity	Class 2K3 - Maximum 95 % at 40 °C
Operating Vibration	IEC60068-2-6 10...57 Hz width 0.075 mm 57...150 Hz accel. 9.81 m/s ²

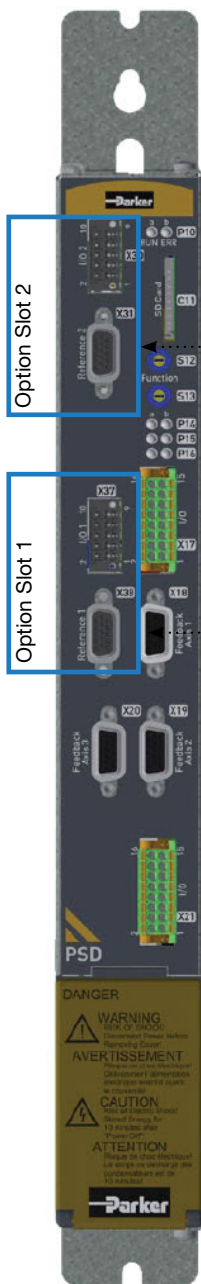
Standards & Conformance

2006/95/EC	Low voltage directive
EN 60204-1	Safety of machinery - Electrical equipment of machines - Part 1: General requirements
EN 61800-5-1	Adjustable speed electrical power drive systems - safety requirements, thermal and energy
UL	Power Conversion Equipment UL508C
2004/108/EC	EMC directive
EN 61800-3	Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test method
STO	Performance Level PL=e according to EN ISO 13849

Dimensions

Type	H [mm]	H1 [mm]	H2 [mm]	W [mm]	D [mm]	Weight [kg]
PSD1-SW	235	225	200	50	180	1.8
PSD1-MW 1/2/3 axes	432	405	360	50	263	4.3
PSD1-MW Single axis 30 A	432	405	360	100	263	8.6
PSD1-MW-P-010	432	405	360	50	263	3.6
PSD1-MW-P-020	432	405	360	100	263	5.4





Encoder Interface

- Encoder Input
 - Physical layer RS422
 - Supported protocols
 - RS422 A/B Encoder with Index
 - RS 422 Step/Direction
- Power Supply for the external Encoder
 - 5V / 150mA
 - 24V (70mA)
- Update rate for load control $T_a \leq 125\mu s$
- Encoder Emulation
 - Max Frequency 400kHz (1460rpm@16384imp/U)
 - RS422 as physical layer
 - Supported types:
 - A/B Encoder signal with Zero pulse
 - Step/Direction
- Bypass function

1 or 2 option boards are possible per device.

Benefits:

- **Flexible & Cost-effective:** Wider choice of sensors. Saving costs by using sensors with standard interface instead of usually more expensive sensors with fieldbus interface.
- **Fast operation:** Achieving faster cycle times and less delay with direct connected sensors results in better performance of the closed loop controls.
- **Smart:** Small applications can be realized without external PLC
- **Support** for outdated technologies like PLCs with analog interface as setpoint channel to servo drives.

Parker Servo Drive PSD1
Programmable Version

Programmable Version

Programming

- According to IEC 61131-3
- Using at least CODESYS 3.5.15
- PLC Project management with Parker Servo Manager (Drive cloning, import & export)
- Profile State Machine Function block (Called up in IEC cycle)

Technical Specifications

- Up to 3 PLC Tasks + one fast PLC Task (500µs)
- 500 * 16 Bit Variables / BOOL, INT, WORD
- 150 * 32 Bit Variables / DINT, DWORD, TIME, REAL
- 352 Recipe Variables (axis specific) / 32 columns and 11 rows (3 x LREAL, 4 x DINT, 2 x INT, 1xLINT, 1xSTRING)

IEC 61131-3 standard modules

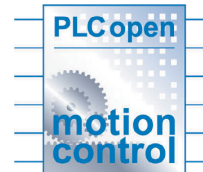
- Up to 8 timers (TON, TOF, TP)
- Triggers (R_TRIG, F_TRIG)
- Flip-flops (RS, SR)
- Counters (CTU, CTD, CTUD)

Device specific functions modules

- PSD_Input: Generates an input process image
- PSD_Output: Generates an output process image
- PSD_RecipeTable: Access to recipe table

PLCopen function modules

- Positioning: absolute, relative, additive, continuous
- Machine zero
- Stop, energizing the powerstage, reset error
- Position, device status, read axis error
- Electronic gearing (MC_Gearin)
- Digital I/O control (4I/2O per axis)



Programming language

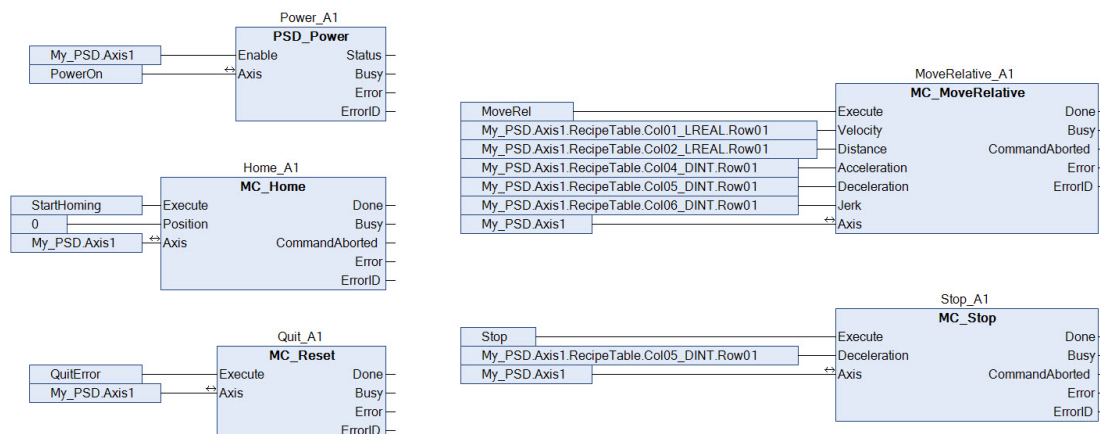
Text languages

- Structured text (ST)
- Instruction List (IL)

Graphical languages

- Ladder Diagram (LD)
- Function Block Diagram (FBD)
- Sequential Function Chart (SFC)
- Continuous Function Chart (CFC)

IEC Program example in CFC



Order Code

Parker Servo Drive PSD

	1	2	3	4	5	6	7	8	9	10
Order example	PSD1	M	W	3	433	B	2	2	00	000

1 Drive Family

PSD1 Parker Servo Drive

2 Device Type

S Standalone 230VAC

M Multi-axis 480VAC

3 Mounting Type

W Wall mounting

4 Device Type

1 One powerstage

2 Two powerstages

3 Three powerstages

P Power module

5 Device Type

PSD1SW1 Standalone

200 2 Amp

300 5 Amp

PSD1MW1 One powerstage

300 5 Amp

400 8 Amp

600 15 Amp

800 30 Amp

PSD1MW2 Two powerstages

220 2 + 2 Amp

330 5 + 5 Amp

440 8 + 8 Amp

PSD1MW3 Three powerstages

222 2 + 2 + 2 Amp

433 8 + 5 + 5 Amp

PSD1MWP Passive power supply

010 10 kVA

020 20 kVA

6 Technology

B Basic

C Programmable¹⁾

7 Interface

1 EtherCAT Only

2 EtherCAT, PROFINET, EtherNet/IP

8 Feedback

1 DSL® Only

2 DSL®, Resolver, Encoder (1 Vss)¹⁾,
Encoder A/B (TTL)¹⁾,
Analog Hall (1 Vss)¹⁾,

9 Options

00 No option

02 1 x I/O Option Board

22 2 x I/O Option Board

10 Customization

000 Non customized

¹⁾ Only for PSD1-S and first power stage of multi-axis unit PSD1MW

²⁾ Available with 22 (Multi Fieldbus, Multi Feedback)



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