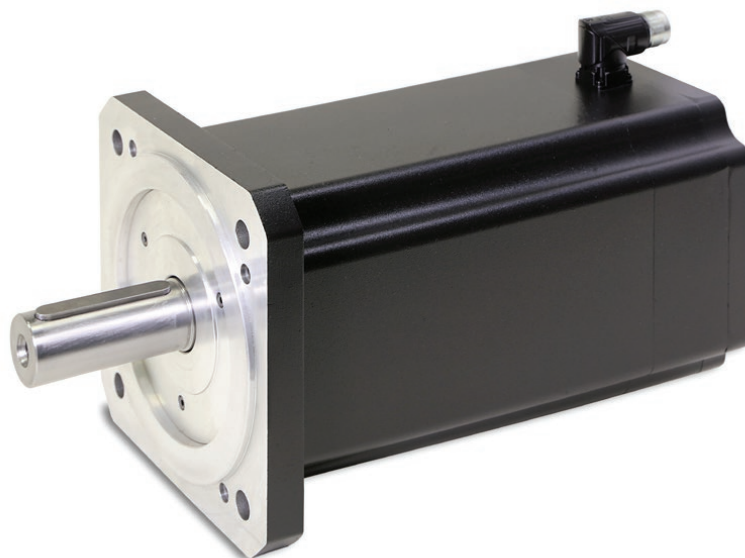
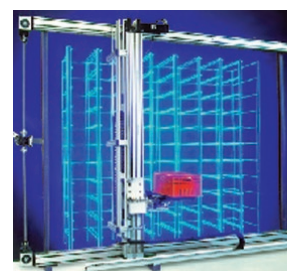


aerospace
climate control
electromechanical
filtration
fluid & gas handling
hydraulics
pneumatics
process control
sealing & shielding



SMH / SMB Series

Low Inertia Servo Motors



ENGINEERING YOUR SUCCESS.



WARNING – USER RESPONSIBILITY

FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

- This document and other information from Parker-Hannifin Corporation, its subsidiaries and authorized distributors provide product or system options for further investigation by users having technical expertise.
- The user, through its own analysis and testing, is solely responsible for making the final selection of the system and components and assuring that all performance, endurance, maintenance, safety and warning requirements of the application are met. The user must analyze all aspects of the application, follow applicable industry standards, and follow the information concerning the product in the current product catalog and in any other materials provided from Parker or its subsidiaries or authorized distributors.
- To the extent that Parker or its subsidiaries or authorized distributors provide component or system options based upon data or specifications provided by the user, the user is responsible for determining that such data and specifications are suitable and sufficient for all applications and reasonably foreseeable uses of the components or systems.

Low Inertia Servo Motors - SMH / SMB

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Parker Hannifin

The global leader in motion and control technologies

A world class player on a local stage

Global Product Design

Parker Hannifin has more than 40 years experience in the design and manufacturing of drives, controls, motors and mechanical products. With dedicated global product development teams, Parker draws on industry-leading technological leadership and experience from engineering teams in Europe, North America and Asia.

Local Application Expertise

Parker has local engineering resources committed to adapting and applying our current products and technologies to best fit our customers' needs.

Manufacturing to Meet Our Customers' Needs

Parker is committed to meeting the increasing service demands that our customers require to succeed in the global industrial market. Parker's manufacturing teams seek continuous improvement through the implementation of lean manufacturing methods throughout the process. We measure ourselves on meeting our customers' expectations of quality and delivery, not just our own. In order to meet these expectations, Parker operates and continues to invest in our manufacturing facilities in Europe, North America and Asia.

Electromechanical Worldwide Manufacturing Locations

Europe

Littlehampton, United Kingdom
Dijon, France
Offenburg, Germany
Filderstadt, Germany
Milan, Italy

Asia

Wuxi, China
Jangan, Korea
Chennai, India

North America

Rohnert Park, California
Irwin, Pennsylvania
Charlotte, North Carolina
New Ulm, Minnesota



Offenburg, Germany

Local Manufacturing and Support in Europe

Parker provides sales assistance and local technical support through a network of dedicated sales teams and authorized technical distributors throughout Europe.

For contact information, please refer to the Sales Offices on the back cover of this document or visit www.parker.com



Milan, Italy



Littlehampton, UK



Filderstadt, Germany



Dijon, France

Low Inertia Servo Motors - SMH / SMB

Overview

Description

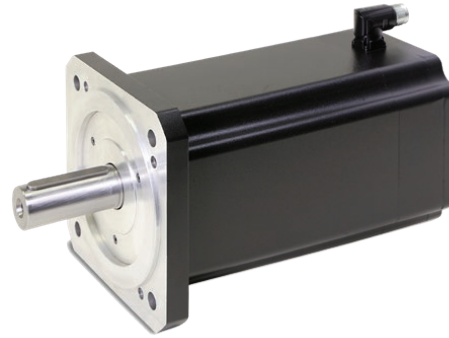
The SMH / SMB Series of highly-dynamic brushless servo motors have been design to combine the cutting-edge technology of Parker Hannifin products with an extremely high performance. Thanks to the innovative "salient pole" technology, the motor's dimensions are considerably reduced with significant advantages in terms of specific torque, overall dimensions and dynamic performance. Compared to traditional-technology brushless servo motors, the specific torque is approximately 30 % higher, overall dimensions are considerably reduced and, consequently rotor inertias are extremely low. Thanks to the high quality of Neodymium-Iron-Boron magnets, and also the encapsulation method used to fasten them to the shaft, the SMH/B motors can achieve very high acceleration and withstand high overloads without risk of demagnetisation or detachment of the magnets. Specific applications for the SMH/B Series include all types especially those for the packaging and handling industry, and all those applications where very high dynamic performances and very low inertias are required.

Features

- High number of feedback options
- Customised windings/voltages
- Increased Inertia option
- Multiple connection options

Application

- Food, Pharma & Beverage
- Packaging Machines
- Material Forming
- Material Handling
- Factory Automation
- Life Science Diagnostic
- Automotive Industry / In-Plant
- Printing Industry
- Textile Machines
- Robotics
- Servo Hydraulic Pumps



Technical Characteristics - Overview

Motor Type	Permanent magnets synchronous servomotor
Rotor Design	Rotor with surface rare earth magnets
Number of poles	8
Power Range	0.1 – 9.4 kW
Torque Range	0.19 – 60 Nm
Speed Range	0 – 7500 min ⁻¹
Mounting	Flange with smooth holes
Shaft End	Plain keyed shaft Plain smooth shaft (option)
Cooling	Natural ventilation
Protection Level (IEC60034-5)	IP64 IP65 (option/standard for SM_170)
Feedback sensor	Resolver Absolute Endat or Hiperface Incremental Encoder
Thermal protection	PTC for SMB and KTY compatible with SMH
Other options	Brake Second shaft Increased inertia
Marking	CE UL (SM_40 and SM_170 excluded)
Voltage Supply	80 / 230 / 400 VAC other voltage under request
Temperature Class	Class F
Connections	Rotatable connectors Flying cables Terminal Box (see table option for combination) Special connector (under request)

Brushless servo motors SMH / SMB
Technical Characteristics

Technical Characteristics

Technical Data

230 VAC supply voltage

Model	Size	Stall ⁽¹⁾		Nominal ⁽¹⁾			Peak ⁽¹⁾ Torque	Inertia		Ke ^{(2) (3)}	Kt ^{(2) (3)}
		Torque	Current	Torque	Speed	Current		No brake	With brake		
		T ₀₆₅ (T ₁₀₅) [Nm]	I ₀₆₅ [A]	T _{n065} [Nm]	n [min ⁻¹]	I _{n065} [A]	T _{max} [Nm]	J [kgmm ²]	J [kgmm ²]	Ke [Vs]	Kt [Nm/A _{max}]
SM_40 60 0,19	40	0.19	0.78	0.16	6000	0.66	0.6	3.7	-	0.14	0.242
SM_40 60 0,38		0.38	1.2	0.27	6000	0.86	1.17	6.1		0.181	0.31
SM_60 30 0,55	60	0.55 (0.68)	0.7	0.50	3000	0.66	1.7	18	30.5	0.44	0.76
SM_60 45 0,55			1.0	0.39	4500	0.74				0.30	0.53
SM_60 60 0,55		1.4	0.24	6000	0.60	0.23	0.40				
SM_60 16 1,4		1.4 (1.7)	0.95	1.35	1600	0.91	4.4	30	42.5	0.85	1.48
SM_60 30 1,4			1.73	1.20	3000	1.50				0.47	0.81
SM_60 45 1,4			2.37	1.00	4500	1.69				0.34	0.59
SM_60 60 1,4			2.98	0.80	6000	1.70				0.27	0.47
SM_60 75 1,4			3.85	0.15	7500	0.41				0.21	0.36
SM_82 10 03	82	3 (3.7)	1.2	2.9	1000	1.2	9	140	183	1.43	2.48
SM_82 16 03			1.8	2.9	1600	1.7				0.96	1.66
SM_82 30 03			3.1	2.7	3000	2.8				0.55	0.96
SM_82 33 03			3.5	2.4	3300	2.8				0.49	0.85
SM_82 45 03			4.7	2.2	4500	3.4				0.37	0.64
SM_82 60 03			6.1	1.5	6000	3.1				0.28	0.49
SM_82 75 03	7.5	0.6	7500	1.6	0.23	0.40					
SM_100 16 06	100	6 (9)	3.7	5.8	1600	3.6	18	336	440	0.92	1.60
SM_100 30 06			5.9	5.0	3000	4.9				0.59	1.02
SM_100 45 06			9.4	3.5	4500	5.5				0.37	0.64
SM_100 55 06			11.8	2.6	5500	5.1				0.29	0.51
SM_100 75 06	14.7	0.6	7500	1.5	0.24	0.41					
SM_115 16 10	115	10 (12.5)	6.0	9.0	1600	5.4	32	900	1000	0.96	1.66
SM_115 30 10			10.5	8.0	3000	8.4				0.55	0.95
SM_115 40 10			14.7	7.6	4000	11.2				0.39	0.68
SM_115 54 10			18.2	7.1	5400	12.9				0.32	0.55
SM_142 18 15	142	15 (19)	9.7	13.3	1800	8.6	47	1400	1600	0.89	1.54
SM_142 30 15			16.0	12.5	3000	13.4				0.54	0.94
SM_170 11 35	170	35	13.3	30	1100	11.4	111	2900	4500	1.52	2.6
SM_170 16 35			20	28	1600	16.0				1.03	1.8
SM_170 25 35			29	26	2500	22.0				0.69	1.2

⁽¹⁾ Data referred to motor mounted on a steel flange in horizontal position with resolver and without brake. Stall torques refer to motor turning at 100 min⁻¹

⁽²⁾ Data measured at 20 °C. When "hot" consider -0.09 %/K derating

⁽³⁾ Manufacturing tolerance ±10 %

400 VAC power supply

Model	Size	Stall ⁽¹⁾		Nominal ⁽¹⁾			Peak ⁽¹⁾	Inertia		Ke ^{(2) (3)}	Kt ^{(2) (3)}
		Torque	Current	Torque	Speed	Current	Torque	No brake	With brake		
		T ₀₆₅ (T ₁₀₅) [Nm]	I ₀₆₅ [A]	T _{n065} [Nm]	n [min ⁻¹]	I _{n065} [A]	T _{max} [Nm]	J [kgmm ²]	J [kgmm ²]	Ke [Vs]	Kt [Nm/A _{rms}]
SM_60 30 1,4	60	1.4 (1.7)	0.95	1.2	3000	0.81	4.4	30	42.5	0.81	1.48
SM_60 45 1,4			1.37	1.0	4500	0.98				0.59	1.02
SM_60 60 1,4			1.73	0.8	6000	0.99				0.68	0.81
SM_60 75 1,4	82	3 (3.7)	2.15	0.15	7500	0.23	9	140	183	0.38	0.65
SM_82 30 03			1.8	2.7	3000	1.6				0.96	1.66
SM_82 45 03			2.7	2.2	4500	2.0				0.64	1.11
SM_82 56 03			3.1	1.6	5600	1.7				0.55	0.96
SM_82 60 03			3.5	1.7	6000	2.0				0.49	0.85
SM_82 75 03	100	6 (9)	4.4	0.6	7500	0.9	18	336	440	0.39	0.68
SM_100 30 06			3.7	5.0	3000	3.1				0.92	1.60
SM_100 45 06			5.6	3.5	4500	3.3				0.62	1.07
SM_100 56 06			5.9	2.5	5600	2.4				0.59	1.02
SM_100 75 06	115	10 (12.5)	9.4	0.6	7500	0.9	32	900	1000	0.37	0.64
SM_115 20 10			4.5	9.0	2000	4.06				1.28	2.22
SM_115 30 10			6.0	8.0	3000	4.82				0.96	1.66
SM_115 40 10			8.0	7.6	4000	6.05				0.73	1.26
SM_115 56 10	142	15 (19)	10.5	6.0	5600	6.30	47	1400	1600	0.55	0.95
SM_142 20 15			6.4	13.0	2000	5.5				1.36	2.35
SM_142 30 15			9.7	12.5	3000	8.1				0.89	1.54
SM_142 45 15			14.4	10.9	4500	10.5				0.60	1.04
SM_142 56 15			16.0	9.2	5600	9.8				0.54	0.94
SM_142 10 17			3.5	16.4	1000	3.4				2.83	4.90
SM_142 30 17			9.6	14.0	3000	8.1				1.02	1.77
SM_142 56 17	15.8	10.6	5600	9.8	0.62	1.08					
SM_170 10 35	170	35	6.8	31	1000	6.1	111	2900	4500	2.95	5.1
SM_170 20 35			13.3	27	2000	10.3				1.52	2.6
SM_170 27 35			18	22	2700					1.15	2.0
SM_170 30 35			20	19	3000	11				1.03	1.8
SM_170 10 60			11.7	53	1000	10.4				2.95	5.1
SM_170 20 60	60	60	22.6	44	2000	16.6	190	5800	7400	1.53	2.7
SM_170 30 60			35.7	30	3000	17.9				0.97	1.7

⁽¹⁾ Data referred to motor mounted on a steel flange in horizontal position with resolver and without brake. Stall torques refer to motor turning at 100 min⁻¹

⁽²⁾ Data measured at 20 °C. When "hot" consider -0.09 %/K derating

⁽³⁾ Manufacturing tolerance data ±10 %

STANDARDS

In compliance with: 2006/95 EC

- EN60034-1
- EN60034-5
- EN60034-5/A1

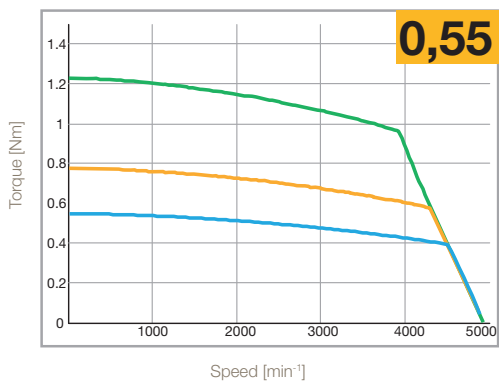
Marked Marked (except SM_40 and SM_170)

Brushless servo motors SMH / SMB
Curves

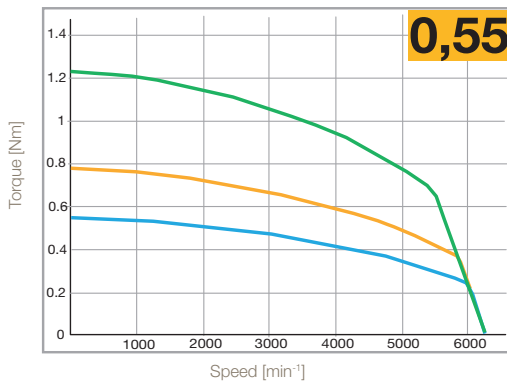
Speed Torque Curves

SMH/B60

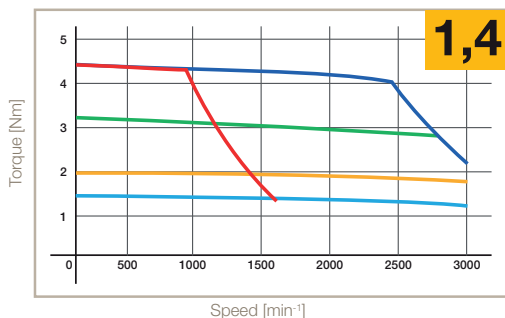
4500 min⁻¹ 230 V



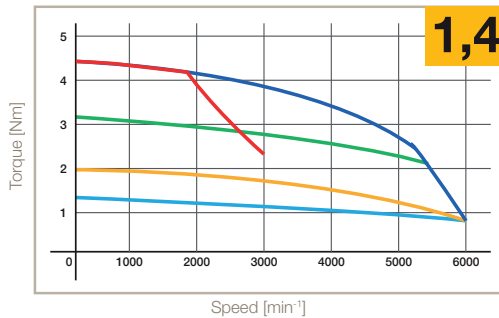
6000 min⁻¹ 230 V



1600 min⁻¹ 230 V - 3000 min⁻¹ 400 V



3000 min⁻¹ 230 V - 6000 min⁻¹ 400 V

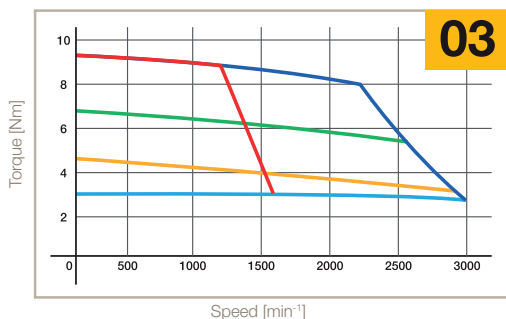


- S1 65 K, ΔT
- S3 10 %, 5 min, 400 V
- S3 50 %, 5 min
- S3 10 %, 5 min, 230 V
- S3 50 %, 5 min
- S3 20 %, 5 min

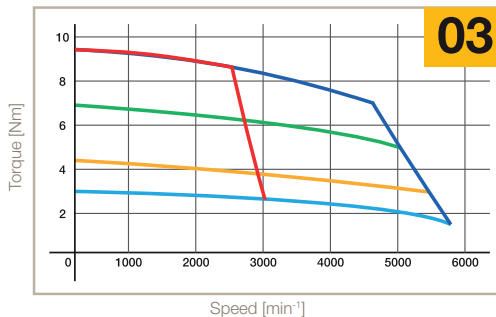
Brushless servo motors SMH / SMB
Curves

SMH/B82

1600 min⁻¹ 230 V - 3000 min⁻¹ 400 V

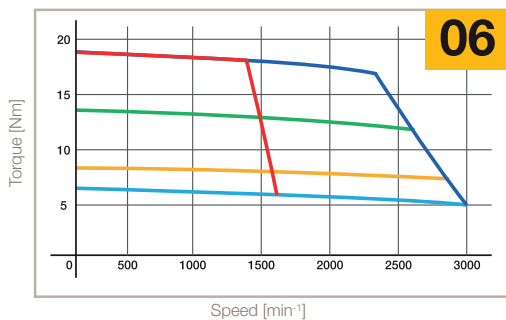


3000 min⁻¹ 230 V - 5600 min⁻¹ 400 V

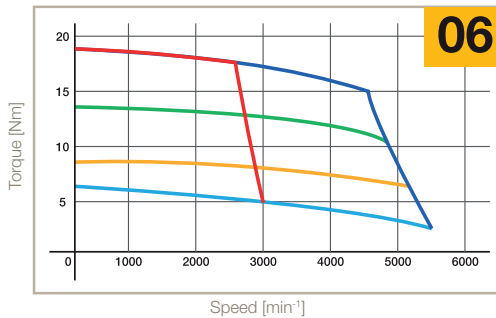


SMH/B100

1600 min⁻¹ 230 V - 3000 min⁻¹ 400 V

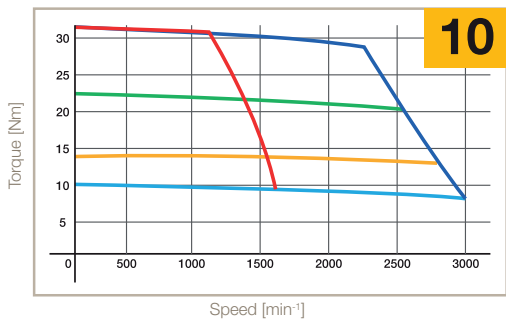


3000 min⁻¹ 230 V - 5600 min⁻¹ 400 V

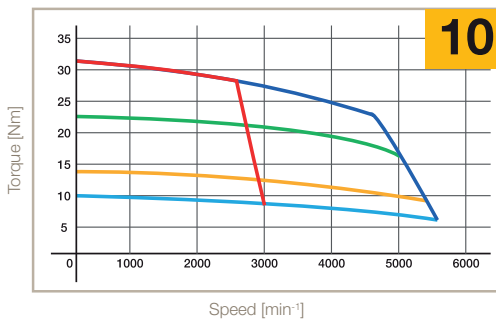


SMH/B115

1600 min⁻¹ 230 V - 3000 min⁻¹ 400 V



3000 min⁻¹ 230 V - 5600 min⁻¹ 400 V

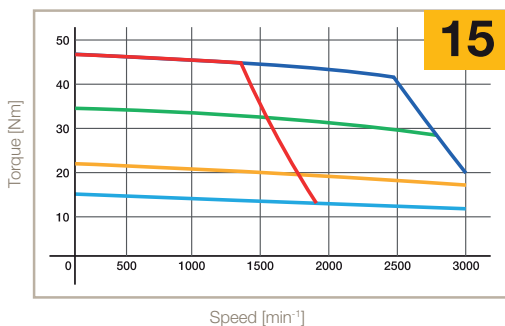


- S1 65 K, ΔT
- S3 10 %, 5 min, 400 V
- S3 10 %, 5 min, 230 V
- S3 50 %, 5 min
- S3 50 %, 5 min
- S3 20 %, 5 min

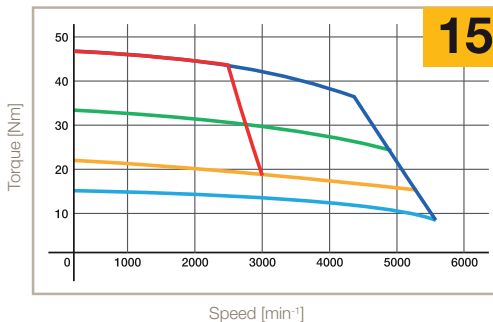
Brushless servo motors SMH / SMB
Curves

SMH/B142

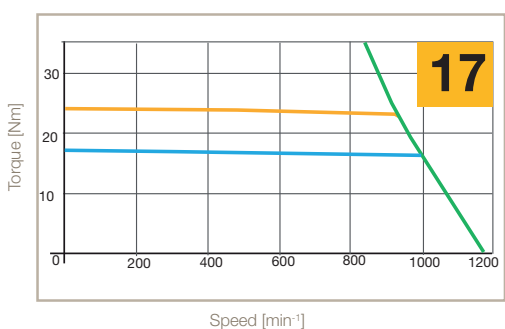
1800 min⁻¹ 230 V - 3000 min⁻¹ 400 V



3000 min⁻¹ 230 V - 5600 min⁻¹ 400 V

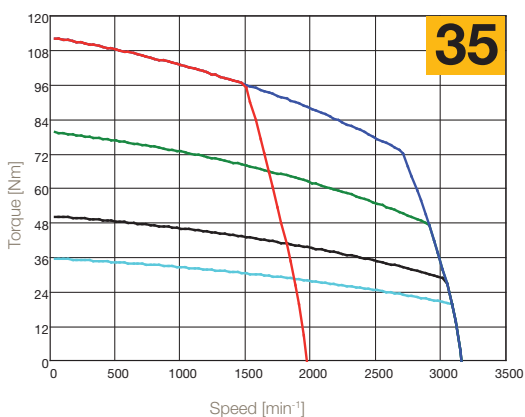


1000 min⁻¹ 400 V

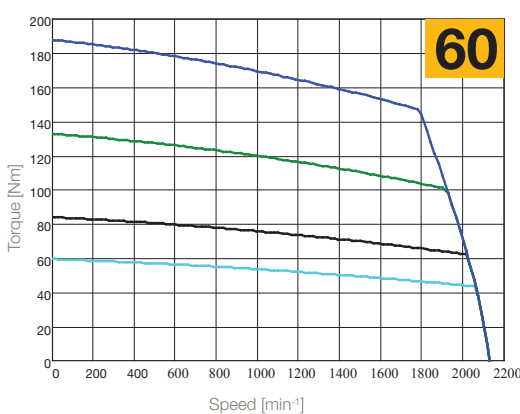


SMH/B170

1600 min⁻¹ 230 V - 3000 min⁻¹ 400 V

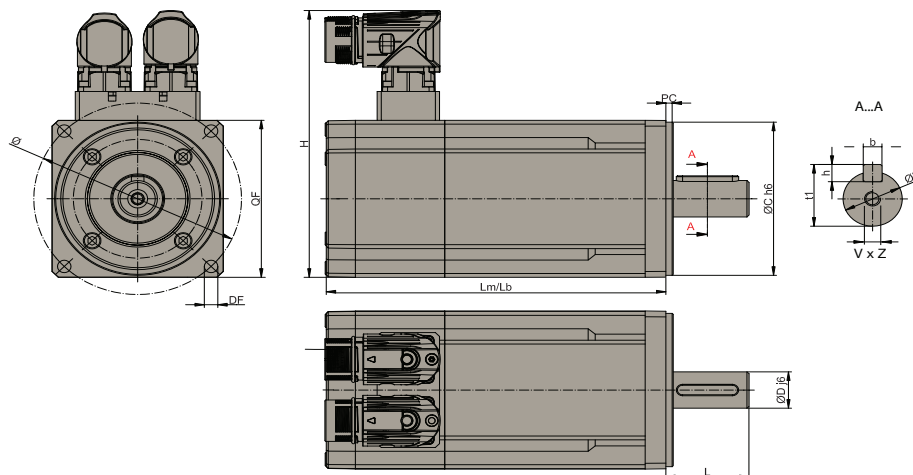


2000 min⁻¹ 400 V



- S1 65 K, ΔT
- S3 10 %, 5 min, 400 V
- S3 50 %, 5 min
- S3 10 %, 5 min, 230 V
- S3 50 %, 5 min
- S3 20 %, 5 min

Dimensions of Standard Motors with Resolver Feedback



Dimensions [mm]

Motors Size		LM	Weight	DxL	b _{xh}	t ₁	VxZ	H	C	Ø	DF	PC	QF	Order Code QF	
		LB	[kg]												
SMH / B	40	0,19	87.5 119.5	0.53 n.a.	8x20	3x3	9.2	n.a.	60 Layout 2Y	30	50	4.3	2.5	40	5
		0,38	105.5 137.5	0.68 n.a.	8x20	3x3	9.2	n.a.	60 Layout 2Y	30	50	4.3	2.5	40	5
	60	0,55	91.2 137	1 1.3	9x20 11x23	3x3 4x4	10.2 12.5	- M4x10	118 Layout 2I	40	63	5.5	2.5	60	8
		1,4	129.5 161	1.5 1.8	9x20 11x23	3x3 4x4	10.2 12.5	- M4x10		40	63	5.5	2.5	60	8
	82	03	159 202	3.6 4.3	11x23 ⁽²⁾ 14x30	4x4 5x5	12.5 16	M4x10 M5x12.5	140 Layout 2I	60	75	6	2.5	70	7
			163.5 206.5	3.6 4.3	11x23 ⁽²⁾ 14x30 19x40 ⁽¹⁾	4x4 5x5 6x6	12.5 16 21.5	M4x10 M5x12.5 M6x16		80	100	6.5	3.5	82	8
		06	191.5 238.5	4.7 5.3	19x40 24x50	6x6 8x7	21.5 27	M6x16 M8x19		95	115	9	3.5	100	5
	115	10	220 265	7.7 9.7	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22	157.5 Layout 2I	80	100	7	3.5	100	8
										95	115	9	3.5	100	5
										95	115	9	3.5	115	9
	142	15	243 293	13 16	19x40 24x50 28x60	6x6 8x7 8x7	21.5 27 31	M6x16 M8x19 M10x22	185 Layout 2I	95	130	9	3.5	115	8
										110	130	9	3.5	130	7
										130	165	11	3.5	145	5
	170	35	306	30	38x80	10x8	41	M12x32	212.3 Layout 2I	180	215	14	4	205	5
60										409	50	38x80	10x8	41	M12x32

LM: Motor's length without brake and with resolver
LB: Motor's length with brake and resolver
DxL: Shaft diameter x shaft length
b_{xh}: Key dimension
t₁: Overall shaft height
VxZ: Shaft hole depth
C: Centering

H: Height
DF: Fixing holes
Ø: Interaxis hole
QF: Mounting flange
PC: Centre Depth

¹⁾ not available with flange 7
²⁾ only for torque <2 Nm

Brushless servo motors SMH / SMB
Accessories and Options

Options

Parker SMH / SMB family motors are available with standard and custom options to adapt motor on your application. If the option for your application is not listed, please consult our technical department.

Holding Brake

All SMH / SMB motors are available with option holding brake. The fail-safe (supply voltage 24 VDC $\pm 10\%$) holding brake is incorporated in the motor at the opposite side of the front flange (SM_170 front side) and is applied when there is no voltage present. Because of the power loss caused by the brake, torque values must be reduced by 5 %. The holding brakes shall be used with the motor at a standstill and not for dynamic braking. For maintenance, please refer to technical manual

Motor	Voltage [V]	Current [A]	Torque @20 °C [Nm]	Added Length with resolver [mm]	Added Weight [kg]	Added Inertia [kgmm ²]
SMH / SMB40	24	0.25	0.4	32	0.15	-
SMH / SMB60		0.34	2.2	31.5	0.3	12.5
SMH / SMB82		0.5	4.5	43	0.7	43
SMH / SMB100		0.67	9	47	0.6	104
SMH / SMB115		0.67	9	45	2	100
SMH / SMB142		0.75	22	50	3	200
SMH / SMB170		1.67	72	-	2.9	1600

Medium Inertia

Where the application needs different values of inertia, SMH / SMB can provide a standard adder.

Motor	Added inertia [kgmm ²]	Added length with resolver [mm]	Added weight [kg]
SMH / SMB60	29	31.5	0.32
SMH / SMB82	270	43	0.91
SMH / SMB100	284	47	0.68
SMH / SMB115	900	45	2.28
SMH / SMB142	690	50	2.49
SMH / SMB170	consult Parker	consult Parker	consult Parker

Feedback

Motors may be equipped with various feedback types in order to meet the different requirements for precision, signal that the application needs. The standard motor includes the resolver feedback. Hiperface Encoder, DSL Encoder, EnDat Encoder, Incremental Encoder are available like the following tables.

Resolver

Poles	2
Transformation ratio	0.5
Operating temperature	-50...+150 °C
SM_ associations	All Sizes

Incremental Encoder with Hall Sensor

Code	A1	A2	A3	B3	C4	D3
Resolution [C/T]	2000	2048	4096	2048	5000	5000
Poles	8					
System accuracy	$\pm 32''$	$\pm 32''$	$\pm 16''$	$\pm 32''$	$\pm 13''$	$\pm 13''$
Voltage	+5 VDC $\pm 5\%$ - 200 mA					
Reference mark	Yes					
Max speed [min ⁻¹]	6000					
Output circuit	Line drive differential mode 20 mA					
Operating temperature	-20 °C...+100 °C	-20 °C...+85 °C	-20 °C...+100 °C	-20 °C...+85 °C	-20 °C...+85 °C	-20 °C...+85 °C
SM_ motors associations						
SM_40	N	N	N	N	N	N
SM_60	N	N	N	Y (+17 mm length)	N	Y (+17 mm length)
SM_82	Y	Y	Y	N	Y	N
SM_100	Y	Y	Y	N	Y	N
SM_115	Y	Y	Y	N	Y	N
SM_142	Y	Y	Y	N	Y	N
SM_170	Y	Y	Y	N	Y	N

12

Brushless servo motors SMH / SMB
Accessories and Options

Hiperface Absolute Encoder

Code	S1	S2	S3	S4	S5	S6
Type	Optical					
Turn	Single	Multi	Single	Multi	Single	Multi
Incremental signals	1 V _{PP}					
Line count	1024			128		
Resolution	32768 (15 bit)			4096 (12 bit)		
Absolute rotation	1	4096	1	4096	1	4096
System accuracy	±45"			±320"		
Power supply	8 VDC				7...12 VDC	
Max speed [min ⁻¹]	6000		12000	9000		
Temperature	-20 °C...+115 °C			-20 °C...+110 °C		
Safety integrity level	SIL2 (IEC 61508), SILCL2 (IEC 62061)				SIL2 (IEC 61508), SILCL2 (IEC 62061)	
SM_ motors associations						
SM_40	N	N	N	N	N	N
SM_60	N		Y (+17 mm length without brake) (+30 mm length with brake)		Y (+17 mm length without brake) (+30 mm length with brake)	
SM_82	Y (+17 mm length without brake) (+30 mm length with brake)		Y	Y	Y	Y
SM_100	Y (+20 mm length)				Y (+20 mm length)	
SM_115	Y	Y	Y	Y	Y	Y
SM_142	Y	Y	Y	Y	Y	Y
SM_170	Y	Y	Y	Y	Y	Y

Code	A6	A7	C6	C7
Type	Optical			
Turn	Single	Multi	Single	Multi
Incremental signals	1 V _{PP}			
Line count	1024		128	
Resolution	32768 (15 bit)		4096 (12 bit)	
Absolute rotation	1	4096	1	4096
System accuracy	±45"		±320"	
Power supply	8 VDC			
Max speed [min ⁻¹]	6000		12000	9000
Temperature	-20 °C...+115 °C		-20 °C...+110 °C	
Safety integrity level	Not Available		Not Available	
SM_ motors associations				
SM_40	N	N	N	N
SM_60	N		Y (+17 mm length without brake) (+30 mm length with brake)	
SM_82	Y (+17 mm length without brake) (+30 mm length with brake)		Y	Y
SM_100	Y (+20 mm length)			
SM_115	Y	Y	Y	Y
SM_142	Y	Y	Y	Y
SM_170	Y	Y	Y	Y

Brushless servo motors SMH / SMB
Accessories and Options

EnDat Absolute Encoder

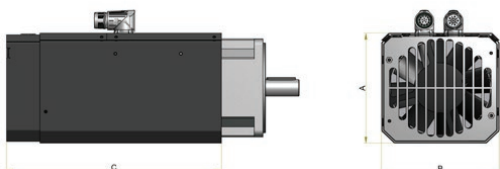
Code	B9	D5	F2	F4
Type	Inductive		Optical	Inductive
Turn			Multi	
Incremental signals			1 V _{PP}	
Line count	32		512	16
Positions per revolutions	131 072 (17 bit)		8192 (13 bit)	262 144 (18 bit)
Distinguishable revolutions	4096		4096	
System accuracy	±400"		±60"	±480"
Power supply			5 VDC	
Max speed [min ⁻¹]	12 000	7000		12 000
Temperature	-20 °C...+115 °C	-30 °C...+115 °C	-40 °C...+115 °C	-20 °C...+115 °C
Absolute position values	EnDat 2.1		EnDat 2.2	EnDat 2.1
Safety integrity level			Not Available	
SM_motors associations				
SM_40	N	N	N	N
SM_60	N	N	Y (+17 mm length without brake) (+9 mm length with brake)	
SM_82	Y (+22.5 mm length without brake) (+18 mm length with brake)		N	N
SM_100	Y (+20 mm length)		N	N
SM_115	Y	Y	N	N
SM_142	Y	Y	N	N
SM_170	Y	Y	N	N

Servofan kit

Designed for the SMH/SMB servo motors family, the new Servofan kit allows extra performances over and above the specified motor torque rating.

Brushless servo motors are meant for high dynamic applications and where the functionality is un-constant (S3 Cycle). In this conditions the new Servofan kit increases by 25% the motor torque and it also permits the use in continuous duty (S1) improving the performances.

Suitable for 100-115, 142 and 170mm frames sizes within the SMB/SMH ranges, the kit is available with an IP20 rating and is ideal for deployment in applications within food/ packaging, hydraulic servo pump application, material forming, factory automation and material handling sectors. For customers who already have motors in the specified frame sizes and would like more torque the new Servofan kit can be purchased separately and added.



Dimensions

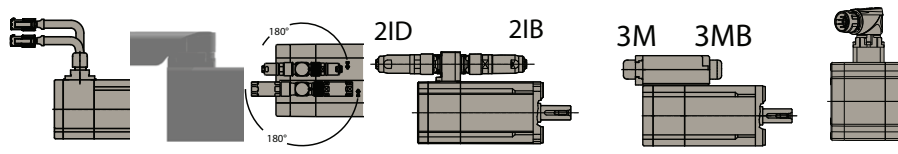
Model	A	B	C
SF-1000-00	131,7	128	271
SF-1420-00	162	159	296
SF-1701-00	184	186	365
SF-1702-00			465

Order code

	1	2	3	4		
Order example	SF	-	100	00	-	00
1 Servofan kit						
SF	Servofan kit					
2 SMH-SMB motor size						
100	For SMH-SMB size 100 or 115					
142	For SMH-SMB size 142					
170	For SMH-SMB size 170					
3 Motor length						
0	Standard for all size except size 170					
1	Only for 170 size - Length 1 - 35Nm					
2	Only for 170 size - Length 2 - 60Nm					
4 Special execution						
00	Standard version					
01	Special version without connectors					

Brushless servo motors SMH / SMB
Layout and Connectors

Layout and Connectors



	200 mm Flying leads with molex plugs 0V	Y-Tech rotatable connector 2Y	2x Parallel upright connectors 2I	2x Forward facing connectors 2IB	2x Rear facing connectors 2ID	Terminal box rear facing 3M	Terminal box forward facing 3MB	Hiperface DSL® Connector (IZ)
SMH_40	N	Y	N	N	N	N	N	N
SMH_60	Y	Y	Y	Y	N	N	N	Y
SMH_82	N	N	Y	Y	N	N	N	Y
SMH_100	N	N	Y	Y	N	N	N	Y
SMH_115	N	N	Y	Y	N	N	N	Y
SMH_142	N	N	Y	Y	N	N	N	Y
SMH_170	N	N	Y	N	N	N	N	Y
SMB_40	N	Y	N	N	N	N	N	N
SMB_60	Y	Y	Y	Y	Y	Y	Y	N
SMB_82	N	N	Y	Y	Y	Y	Y	N
SMB_100	N	N	Y	Y	Y	Y	Y	N
SMB_115	N	N	Y	Y	Y	Y	Y	N
SMB_142	N	N	Y	Y	Y	Y	Y	N
SMB_170	N	N	Y	N	N	N	N	N
SME_60	N	Y	N	Y	Y	N	N	Y
SME_82	N	N	N	Y	Y	N	N	Y
SME_100	N	N	N	Y	Y	N	N	Y
SME_115	N	N	Y	N	N	N	N	Y
SME_142	N	N	Y	N	N	N	N	Y
SME_170	N	N	Y	N	N	N	N	Y

Power connector (0V)

6	5	4
3	2	1

Pin	Description
1	GND - shield
2	Brake 0 VDC
3	Brake +24 VDC
4	W
5	V
6	U

Part number	
CONMOT6M	Female Connector

Resolver connector (0V)

12	11	10	9	8	7
6	5	4	3	2	1

Pin	Description
1	n.c.
2	n.c.
3	n.c.
4	PTC
5	PTC
6	GND - shield
7	SIN +
8	SIN -
9	COS +
10	COS -
11	EXTC -
12	EXTC +

Part number	
CONRES12M	Female Connector

Hiperface connector (0V)

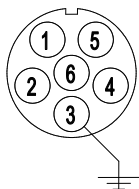
12	11	10	9	8	7
6	5	4	3	2	1

Pin	Description
1	SIN +
2	SIN -
3	RS485 +
4	0 V
5	PTC
6	PTC
7	VDC +
8	COS +
9	COS -
10	RS485 -
11	GND - shield
12	n.c.

Part number	
CONRES12M	Female Connector

Brushless servo motors SMH / SMB
Layout and Connectors

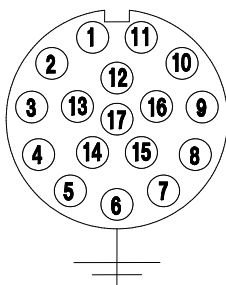
Power connector (2I, 2IB, 2ID)



Pin	Description
1	U
2	V
3	GND - shield
4	Brake +24 VDC
5	Brake 0 VDC
6	W

Part number
CONMOT82F Female Connector

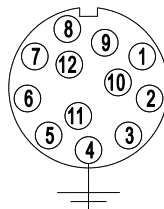
Incremental encoder connector (2I, 2IB, 2ID)



Pin	Description	
1	5 V	
2	0 V	
3	A +	
4	A -	
5	B +	
6	B -	
7	Z +	
8	PTC	KTY -
6	PTC	KTY +
10	Z -	
11	Hall A +	
12	Hall A -	
13	Hall B +	
14	Hall B -	
15	Hall C +	
16	Hall C -	
17	n.c.	

Part number
CONENCF Female Connector

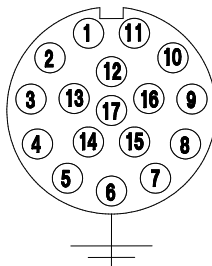
Resolver connector (2I, 2IB, 2ID)



Pin	Description	
1	SIN -	
2	SIN +	
3	n.c.	
4	GND - shield	
5	n.c.	
6	n.c.	
7	EXCT -	
8	PTC	KTY -
9	PTC	KTY +
10	EXCT +	
11	COS +	
12	COS -	

Part number
CONRES82F Female Connector

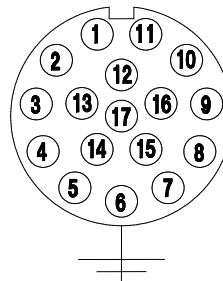
Absolute encoder SINCOS - EnDat (2I, 2IB, 2ID)



Pin	Description	
1	UP Sensor	
2	n.c.	
3	n.c.	
4	0 V Sensor	
5	PTC	KTY -
6	PTC	KTY +
7	UP	
8	CK +	
9	CK -	
10	0 V	
11	GND - shield	
12	B +	
13	B -	
14	Data +	
15	A +	
16	A -	
17	Data -	

Part number
CONENCF Female Connector

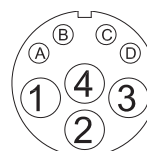
Absolute encoder SINCOS - Hiperface (2I, 2IB, 2ID)



Pin	Description	
1	SIN +	
2	SIN -	
3	RS485 +	
4	n.c.	
5	n.c.	
6	n.c.	
7	GND - shield	
8	PTC	KTY -
9	PTC	KTY +
10	+ VDC	
11	COS +	
12	COS -	
13	RS485 -	
14	n.c.	
15	n.c.	
16	n.c.	
17	n.c.	

Part number
CONRES82F Female Connector

Hiperface DSL® Connector (IZ)



Pin	Description
1	U
2	GND
3	V
4	W
A	Brake +
B	Brake -
C	Signal +
D	Signal -

Part number
CONMOT2IZF Female Connector

Associated Drives

Motor	Rated Speed [min ⁻¹]	Stall Current [A]	PSD1S	PSD1M
230 VAC supply voltage				
SM_40_60_0,19	6000	0.78	PSD1S_1200	PSD1M_1222
SM_40_60_0,38	6000	1.2	PSD1S_1200	PSD1M_1222
SM_60_30_0,55	3000	0.7	PSD1S_1200	PSD1M_1222
SM_60_45_0,55	4500	1	PSD1S_1200	PSD1M_1222
SM_60_60_0,55	6000	1.4	PSD1S_1200	PSD1M_1222
SM_60_16_1,4	1600	0.95	PSD1S_1200	PSD1M_1222
SM_60_30_1,4	3000	1.73	PSD1S_1200	PSD1M_1222
SM_60_45_1,4	4500	2.37	PSD1S_1300	PSD1M_1433
SM_60_60_1,4	6000	2.98	PSD1S_1300	PSD1M_1433
SM_60_75_1,4	7500	3.85	PSD1S_1300	PSD1M_1433
SM_82_10_03	1000	1.2	PSD1S_1200	PSD1M_1222
SM_82_16_03	1600	1.8	PSD1S_1200	PSD1M_1222
SM_82_30_03	3000	3.1	PSD1S_1300	PSD1M_1433
SM_82_33_03	3300	3.5	PSD1S_1300	PSD1M_1433
SM_82_45_03	4500	4.7	PSD1S_1300	PSD1M_1433
SM_82_60_03	6000	6.1	n.a.	PSD1M_1433
SM_82_75_03	7500	7.5	n.a.	PSD1M_1433
SM_100_16_06	1600	3.7	PSD1S_1300	PSD1M_1433
SM_100_30_06	3000	5.9	n.a.	PSD1M_1433
SM_100_45_06	4500	9.4	n.a.	PSD1M_1630
SM_100_55_06	5500	11.8	n.a.	PSD1M_1630
SM_100_75_06	7500	14.7	n.a.	PSD1M_1630
SM_115_16_10	1600	6	n.a.	PSD1M_1433
SM_115_30_10	3000	10.5	n.a.	PSD1M_1630
SM_115_40_10	4000	14.7	n.a.	PSD1M_1630
SM_115_54_10	5400	18.2	n.a.	PSD1M_1800
SM_142_18_15	1800	9.7	n.a.	PSD1M_1630
SM_142_30_15	3000	16	n.a.	PSD1M_1800
SM_170_11_35	1100	13.3	n.a.	PSD1M_1630
SM_170_16_35	1600	20	n.a.	PSD1M_1800
SM_170_25_35	2500	29	n.a.	PSD1M_1800
400 VAC supply voltage				
SM_60_30_1,4	3000	0.95	n.a.	PSD1M_1222
SM_60_45_1,4	4500	1.37	n.a.	PSD1M_1222
SM_60_60_1,4	6000	1.73	n.a.	PSD1M_1222
SM_60_75_1,4	7500	2.15	n.a.	PSD1M_1433
SM_82_30_03	3000	1.8	n.a.	PSD1M_1222
SM_82_45_03	4500	2.7	n.a.	PSD1M_1433
SM_82_56_03	5600	3.1	n.a.	PSD1M_1433
SM_82_60_03	6000	3.5	n.a.	PSD1M_1433
SM_82_75_03	7500	4.4	n.a.	PSD1M_1433
SM_100_30_06	3000	3.7	n.a.	PSD1M_1433
SM_100_45_06	4500	5.6	n.a.	PSD1M_1433
SM_100_56_06	5600	5.9	n.a.	PSD1M_1433
SM_100_75_06	7500	9.4	n.a.	PSD1M_1630
SM_115_20_10	2000	4.5	n.a.	PSD1M_1433
SM_115_30_10	3000	6.0	n.a.	PSD1M_1433
SM_115_40_10	4000	8.0	n.a.	PSD1M_1433
SM_115_56_10	5600	10.5	n.a.	PSD1M_1630
SM_142_20_15	2000	6.4	n.a.	PSD1M_1433
SM_142_30_15	3000	9.7	n.a.	PSD1M_1630
SM_142_45_15	4500	14.4	n.a.	PSD1M_1630
SM_142_56_15	5600	16	n.a.	PSD1M_1800
SM_170_10_35	1000	6.8	n.a.	PSD1M_1630
SM_170_20_35	2000	13.3	n.a.	PSD1M_1630
SM_170_27_35	2700	18	n.a.	PSD1M_1800
SM_170_30_35	3000	20	n.a.	PSD1M_1800
SM_170_10_60	1000	11.7	n.a.	PSD1M_1630
SM_170_20_60	2000	22.6	n.a.	PSD1M_1800
SM_170_30_60	3000	35.7	n.a.	n.a.

Brushless servo motors SMH / SMB
Order Code SMH / SMB

Order Code

Serie SMH / SMB / SME

	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Order example	SMH	A	60	30	1,4	5	9		2I		64	A6	M	2

1 Type Of Motor (mandatory field)	SMH Motor with Resolver for PSD/C3	SMB Motor with Resolver for TPDM/SLVDN	SME Motor with Encoder for TPDM/SLVDN
2 Brake Option	empty field No Brake Option	A Motor with Holding Brake	
3 Motor Frame Size (mandatory field)	40 Torque range 0.19 Nm or 0.35 Nm	60 Torque range 0.55 or 1.4 Nm	82 Torque range 3 Nm
	100 Torque range 6 Nm	115 Torque range 10 Nm	142 Torque range 15 or 17 Nm
	170 Torque range 35 or 60 Nm		
4 Winding (mandatory field)	nn min ⁻¹ (x100) see "Technical Data" (page 6)		
5 Motor Torque (mandatory field)	nn Torque [Nm] see "Technical Data" (page 6)		
6 Flange (mandatory field)	5 All sizes	7 Only for Size 82 and 115	8 Only for Size 60, 82, 100 and 115
	9 Only for Size 115		
7 Shaft (mandatory field)	8 8x20 mm for size 40	9 9x20 mm for size 60	11 11x23 mm for size 60
	14 14x30 mm for size 82	19 19x40 mm for size 82/100/115/142	24 24x50 mm for size 100/115/142
	28 28x60 mm for size 115/142	38 38x80 mm for size 170	
8 Key Shaft option	Empty field Shaft with Key	S Shaft without key	
9 Layout - Connectors (mandatory field)	0V Cable exit and Molex Flying connectors - 200 mm above	2I Rotatable Interconnectron receptacles	2IB 90° Interconnectron receptacles - forward facing
	2ID 90° Interconnectron receptacles - rear facing	3M Terminal box rear facing	3MB Terminal box forward facing
	2Y Y-Tech connectors	IZ DSL® connectore (not for size 40)	
10 Female connectors option (only for SMB/SME)	Empty field With Female / flying connectors	W Without Female / flying connectors	
11 Protection Degree (mandatory field)	64 IP64	65 IP65 (standard for SMB170)	
12 Feedback	Empty field Standard Resolver	A1 Encoder 2000 ppr + Hall - TAMAGAWA OIH48	A2 Encoder 2048 ppr + Hall - TAMAGAWA OIH48
	A3 Encoder 4096 ppr + Hall - TAMAGAWA OIH48	A6 SinCos Hiperface Encoder Single-Turn - STEGMANN SRS50/52	A7 SinCos Hiperface Encoder Multi-Turn - STEGMANN SRS50/52
	B3 Encoder 2048 ppr + Hall - TAMAGAWA OIH35	B9 SinCos EnDat Encoder Multi-Turn - HEIDENHAIN EQI1331	C4 Encoder 5000 ppr + Hall - TAMAGAWA OIH48
	C6 SinCos Hiperface Encoder Single-Turn - STEGMANN SKS36	C7 SinCos Hiperface Encoder Multi-Turn - STEGMANN SKM36	D3 Encoder 5000ppr + Hall - TAMAGAWA OIH35
	D5 SinCos EnDat Encoder Multi-Turn - HEIDENHAIN EQN1325	F2 SinCos EnDat Encoder Multi-Turn - HEIDENHAIN EQN1125	F4 SinCos EnDat Encoder Multi-Turn - HEIDENHAIN EQI1130
	S1 SinCos Hiperface Encoder Single-Turn - STEGMANN SRS50S, SIL2	S2 SinCos Hiperface Encoder Multi-Turn - STEGMANN SRS50S, SIL2	S3 SinCos Hiperface Encoder Single-Turn - STEGMANN SKS36S, SIL2
	S4 SinCos Hiperface Encoder Multi-Turn - STEGMANN SKM36S, SIL2	S5 Hiperface DSL® Encoder Feedback SIL2 32768 steps/rev Single Turn	S6 Hiperface DSL® Encoder Feedback SIL2 32768 steps/rev x 4096 Multi Turn

Brushless servo motors SMH / SMB
Order Code SMH / SMB

13	Option Inertia
Empty field	Standard Inertia
M	Medium Inertia
14	Voltage
0	80 V
2	220-230 V (Standard)
4	380-400 V (Standard)

Brushless servo motors SMH / SMB
Order Code for Cables for SMH / SMB Motors

Order Code

Motor Power Cable for SMH / SMB Motors

	1	2	3	4	5	6	7	8				
Order example	CBM	005	H	D	-	M15	-	PSX	-	0010	-	00

1	Power Cable Drive
CBM	Power cable drive
2	Section [mm²]
005	0.5 mm ²
007	0.7 mm ²
010	1 mm ²
015	1.5 mm ²
025	2.5 mm ²
3	Cable
S	Standard
H	High Flex
4	Brake
0	Power cable standard - without brake
B	Power cable standard - with brake
D	DSL® Power cable with brake
5	Motor Connector
M15	M15 Interconnectron connector
M23	M23 Interconnectron connector
M40	M40 Interconnectron connector
6	Drive
PSX	Parker PSD1-S
PMX	Parker PSD1-M
SDX	Parker Servonet DC
7	Length
0000	Cable length 4 digits (example 50 m = 0500)*
8	Special Execution
00	Standard

* Available length in meter: 1; 2.5; 5; 7.5; 10; 15; 20; 25; 30; 35; 40; 45; 50

Brushless servo motors SMH / SMB
Order Code for Cables for SMH / SMB Motors

Motor Feedback Cable for SMH / SMB Motors

	1	2	3	4		5		6		7		8
Order example	CBF	RE0	H	0	-	M15	-	PSX	-	0010	-	00

1	Power Cable Drive	
	CBF	Feedback cable drive
2	Feedback	
	RE0	Resolver
3	Cable	
	H	High Flex
4	Brake	
	0	Power cable standard - without brake
5	Motor Connector	
	M15	M15 Interconnectron connector
	M23	M23 Interconnectron connector
	M40	M40 Interconnectron connector
6	Drive	
	PSX	Parker PSD1-S
	PMX	Parker PSD1-M
	SDX	Parker Servonet DC
7	Length	
	0000	Cable length 4 digits (example 50 m = 0500)*
8	Special Execution	
	00	Standard

* Available length in meter: 1; 2.5; 5; 7.5; 10; 15; 20; 25; 30; 35; 40; 45; 50



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 Fuel systems & components
 Fuel tank inerting systems
 Hydraulic systems & components
 Thermal management
 Wheels & brakes



Climate Control

Key Markets
 Agriculture
 Air conditioning
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 Food & beverage
 Industrial machinery
 Life sciences
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 Precision cooling
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 Refrigeration
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Key Products

Accumulators
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 Filter driers
 Hand shut-off valves
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 Hose & fittings
 Pressure regulating valves
 Refrigerant distributors
 Safety relief valves
 Smart pumps
 Solenoid valves
 Thermostatic expansion valves



Electromechanical

Key Markets
 Aerospace
 Factory automation
 Life science & medical
 Machine tools
 Packaging machinery
 Paper machinery
 Plastics machinery & converting
 Primary metals
 Process
 Semiconductor & electronics
 Textile
 Wire & cable

Key Products

AC/DC drives & systems
 Electric actuators, gantry robots & slides
 Electrohydraulic actuation systems
 Electromechanical actuation systems
 Human machine interface
 Linear motors
 Stepper motors, servo motors, drives & controls
 Structural extrusions



Filtration

Key Markets
 Aerospace
 Food & beverage
 Industrial plant & equipment
 Life sciences
 Marine
 Mobile equipment
 Oil & gas
 Power generation & renewable energy
 Process
 Transportation
 Water Purification

Key Products

Analytical gas generators
 Compressed air filters & dryers
 Engine air, coolant, fuel & oil filtration systems
 Fluid condition monitoring systems
 Hydraulic & lubrication filters
 Hydrogen, nitrogen & zero air generators
 Instrumentation filters
 Membrane & fiber filters
 Microfiltration
 Sterile air filtration
 Water desalination & purification filters & systems



Fluid & Gas Handling

Key Markets
 Aerial lift
 Agriculture
 Bulk chemical handling
 Construction machinery
 Food & beverage
 Fuel & gas delivery
 Industrial machinery
 Life sciences
 Marine
 Mining
 Mobile
 Oil & gas
 Renewable energy
 Transportation

Key Products

Check valves
 Connectors for low pressure fluid conveyance
 Deep sea umbilicals
 Diagnostic equipment
 Hose couplings
 Industrial hose
 Mooring systems & power cables
 PTFE hose & tubing
 Quick couplings
 Rubber & thermoplastic hose
 Tube fittings & adapters
 Tubing & plastic fittings



Hydraulics

Key Markets
 Aerial lift
 Agriculture
 Alternative energy
 Construction machinery
 Forestry
 Industrial machinery
 Machine tools
 Marine
 Material handling
 Mining
 Oil & gas
 Power generation
 Refuse vehicles
 Renewable energy
 Truck hydraulics
 Turf equipment

Key Products

Accumulators
 Cartridge valves
 Electrohydraulic actuators
 Human machine interfaces
 Hybrid drives
 Hydraulic cylinders
 Hydraulic motors & pumps
 Hydraulic systems
 Hydraulic valves & controls
 Hydrostatic steering
 Integrated hydraulic circuits
 Power take-offs
 Power units
 Rotary actuators
 Sensors



Pneumatics

Key Markets
 Aerospace
 Conveyor & material handling
 Factory automation
 Life science & medical
 Machine tools
 Packaging machinery
 Transportation & automotive

Key Products

Air preparation
 Brass fittings & valves
 Manifolds
 Pneumatic accessories
 Pneumatic actuators & grippers
 Pneumatic valves & controls
 Quick disconnects
 Rotary actuators
 Rubber & thermoplastic hose & couplings
 Structural extrusions
 Thermoplastic tubing & fittings
 Vacuum generators, cups & sensors



Process Control

Key Markets
 Alternative fuels
 Biopharmaceuticals
 Chemical & refining
 Food & beverage
 Marine & shipbuilding
 Medical & dental
 Microelectronics
 Nuclear Power
 Offshore oil exploration
 Oil & gas
 Pharmaceuticals
 Power generation
 Pulp & paper
 Steel
 Water/wastewater

Key Products

Analytical Instruments
 Analytical sample conditioning products & systems
 Chemical injection fittings & valves
 Fluoropolymer chemical delivery fittings, valves & pumps
 High purity gas delivery fittings, valves, regulators & digital flow controllers
 Industrial mass flow meters/controllers
 Permanent no-weld tube fittings
 Precision industrial regulators & flow controllers
 Process control double block & bleeds
 Process control fittings, valves, regulators & manifold valves



Sealing & Shielding

Key Markets
 Aerospace
 Chemical processing
 Consumer
 Fluid power
 General industrial
 Information technology
 Life sciences
 Microelectronics
 Military
 Oil & gas
 Power generation
 Renewable energy
 Telecommunications
 Transportation

Key Products

Dynamic seals
 Elastomeric o-rings
 Electro-medical instrument design & assembly
 EMI shielding
 Extruded & precision-cut, fabricated elastomeric seals
 High temperature metal seals
 Homogeneous & inserted elastomeric shapes
 Medical device fabrication & assembly
 Metal & plastic retained composite seals
 Shielded optical windows
 Silicone tubing & extrusions
 Thermal management
 Vibration dampening

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