

## ETH Electro Cylinder

Parker High Force Electro Thrust Cylinder



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Milan, Italy



Littlehampton, UK



Filderstadt, Germany



Dijon, France

# High Force Electro Thrust Cylinder - ETH

## Overview

### Description

The ETH electro cylinder closes the gap between pneumatic and hydraulic actuators; it can act as a suitable alternative to both in many applications and can have the added benefit of increasing the reliability of the production process. Taking the costs for air and oil into consideration, you will find that in most cases an electromechanical system such as the ETH electro cylinder offers the more economical solution. Combined with a wide choice of accessories, the ETH becomes a highly customisable solution, suitable for a variety of applications.

### Typical applications




- **Material handling and feed systems**
  - wood working and plastics industries
  - vertical actuators for loading machine tools
  - in the textile industry for tensioning / gripping textile fabrics
  - in the automotive industry for transporting and feeding components
- **Testing equipment and laboratory applications**
- **Valve and flap actuation**
- **Pressing**
- **Packaging machinery**
- **Process automation in the food and beverage industry**

### Features

- **Unrivaled power density - high forces and small frame sizes**
- **Cabling can be concealed in the profile**
- **Accessories with integrated force sensors help to spread and even to control forces precisely**
- **Optimized for safe handling and simple cleaning**
- **High service life**
- **Reduced maintenance costs thanks to lubricating access in the cylinder flange**
- **Easy replacement due to pneumatic ISO flange norm (DIN ISO 15552:2005-12) conformity**
- **Integrated anti-rotation device**
- **Reduced noise emission**
- **All from one source:**  
We offer the complete drive train: Drive controllers, motors and gearboxes to match the Electro Cylinder



### Technical Characteristics - Overview

Type	ETH Electro Cylinder
<b>Frame sizes</b>	ETH032 / ETH050 / ETH080 / ETH100 / ETH125
<b>Screw lead</b>	5, 10, 16, 20 mm
<b>Stroke</b>	up to 2000 mm
<b>Traction/thrust force</b>	up to 114 000 N
<b>Speed</b>	up to 1.3 m/s
<b>Acceleration</b>	up to 15 m/s <sup>2</sup>
<b>Equivalent dynamic axial force at a lifetime of 2500 km</b>	up to 49 600 N
<b>Efficiency</b>	up to 90 %
<b>Repeatability</b>	up to ± 0.03 mm
<b>Protection classes</b>	IP54 IP54 with stainless steel screws IP65
<b>Drive</b>	Inline: Axial drive or parallel drive with high performance toothed belt
<b>Directives</b>	2011/65/EC: Conform to RoHS  RoHS 2014/34/EU Equipment group II Category 2, authorized for gas atmospheres zone 1 and zone 2
<b>Classification</b>	ETH032, 050:  II 2G Ex h IIC T4 Gb ETH080*:  II 2G Ex h IIB T4 Gb Conformity certificate number: EPS 13 ATEX 2 592 X (X: there are special specification of use, please observe the intended use of the ATEX Cylinder)

\* ETH100,ETH125: on request only

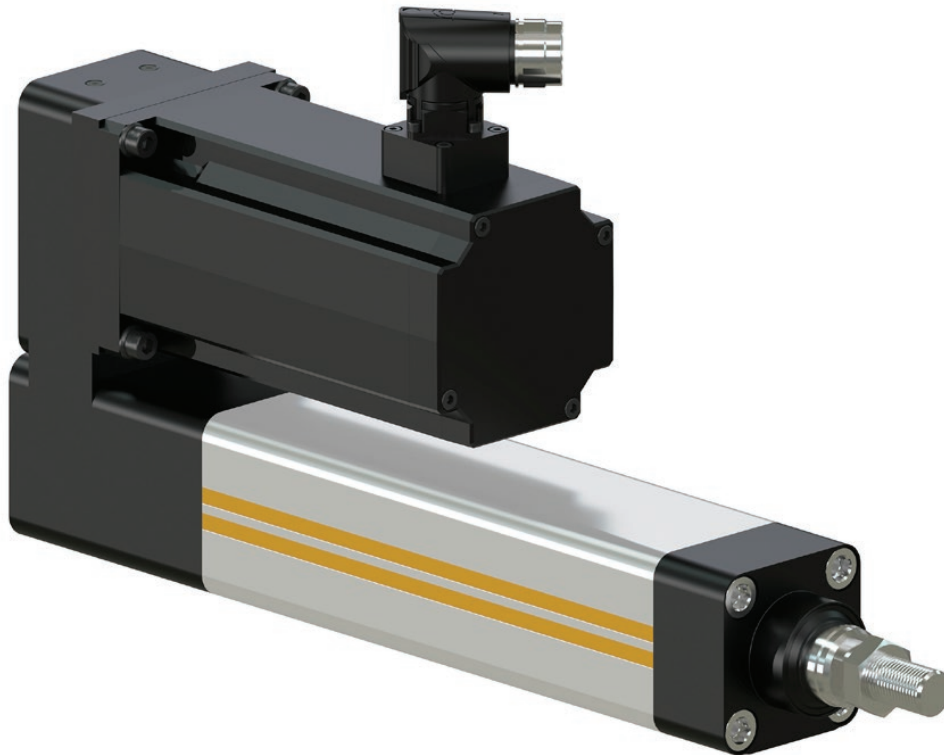
### We also offer customized solutions:

If your application requires a special version of the ETH cylinder, please contact your local Parker Sales Office.

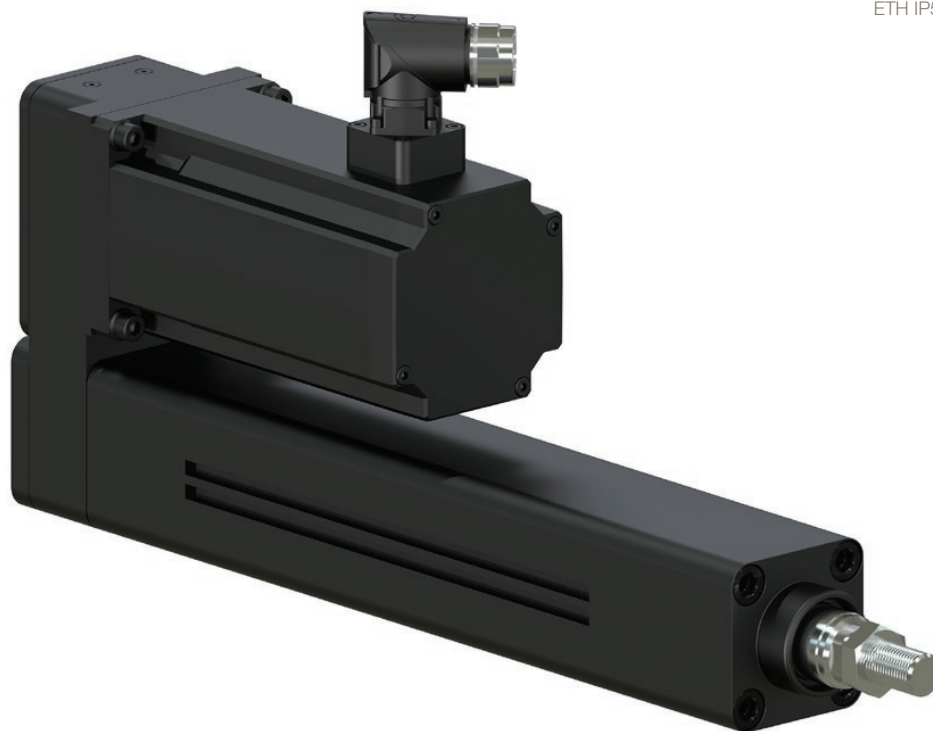
- Customized mountings and rod ends
- Mounting of customer motors
- Preparation of the cylinder for use under aggressive environmental conditions
- Overlong thrust rod
- Polished thrust rod
- Thrust rod hard-chrome plated

ETH - Electro Cylinder  
Overview

## Parker High Force Electro Thrust Cylinder



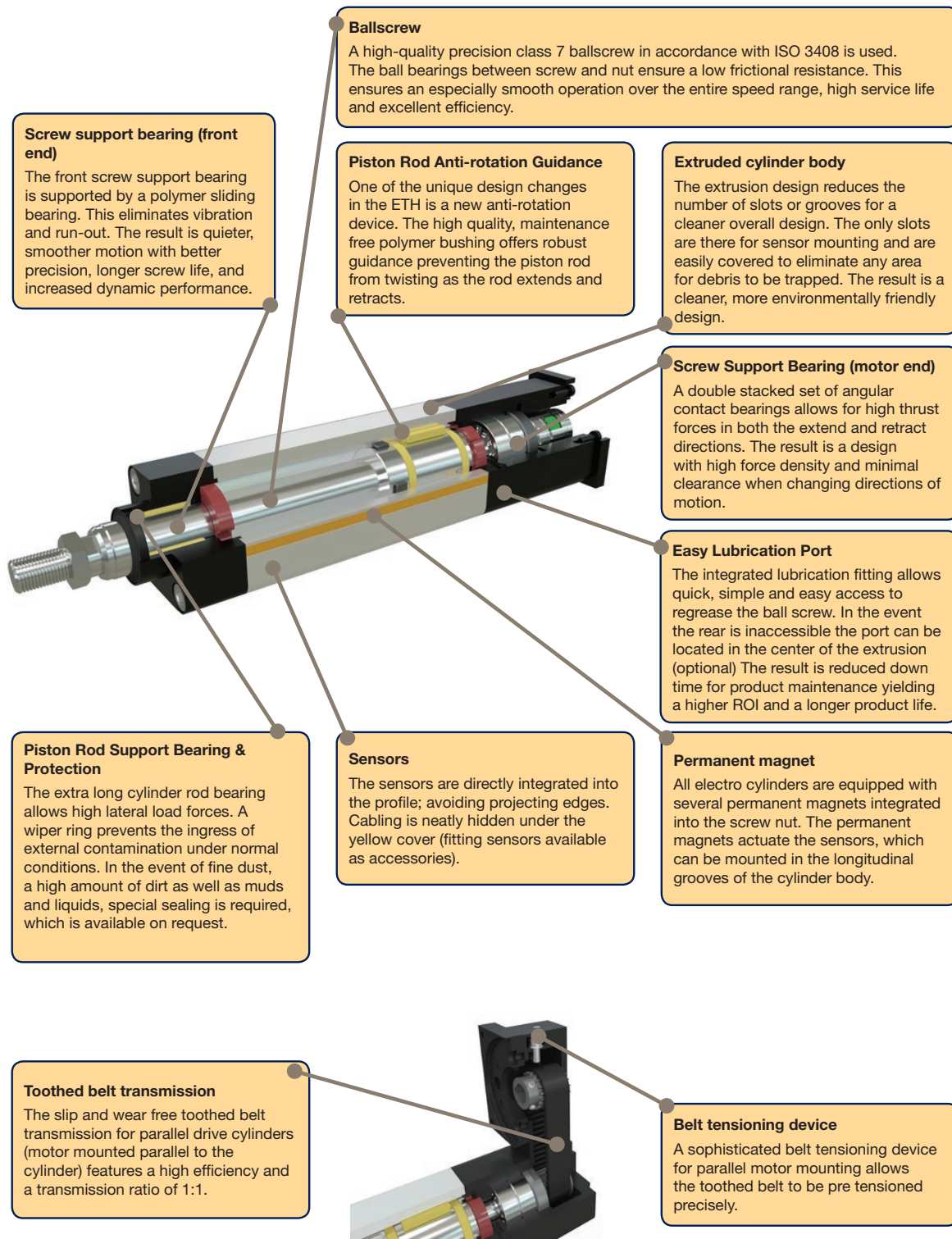
ETH IP54 (Standard)<sup>1)</sup>



<sup>1)</sup> ETH032/050/080 ATEX: End caps and drive housing are not anodized

ETH IP65

## Product Design



## Technical Characteristics

Cylinder size type	Unit	ETH032			ETH050			ETH080	
		M05	M10	M16 <sup>4)</sup>	M05	M10	M20 <sup>4)</sup>	M05	M10
Screw lead	[mm]	5	10	16	5	10	20	5	10
Screw diameter	[mm]	16			20			32	

### Travels, speeds and accelerations

Available strokes <sup>1) 2)</sup>	[mm]	continuous from 50-1000 & standard strokes			continuous from 50-1200 & standard strokes			continuous from 100-1600 & standard strokes	
Max. permissible speed at stroke =									
50-400 mm	[mm/s]	333	667	1067	333	667	1333	267	533
600 mm	[mm/s]	286	540	855	333	666	1318	267	533
800 mm	[mm/s]	196	373	592	238	462	917	267	533
1000 mm	[mm/s]	146	277	440	177	345	684	264	501
1200 mm	[mm/s]	-	-	-	139	270	536	207	394
1400 mm	[mm/s]	-	-	-	-	-	-	168	320
1600 mm	[mm/s]	-	-	-	-	-	-	140	267
Max. Acceleration	[m/s <sup>2</sup> ]	4	8	12	4	8	15	4	8

### Forces

Max. axial traction/thrust force motor inline	[N]		3700	2400		7000	4400		25 100
Max. axial traction/thrust force <sup>3)</sup> Motor parallel	[N]	3600	3280	2050	9300	4920	2460	17 800	11 620
Equivalent dynamic axial force at a lifetime of 2500 km	[N]	1130	1700	1610	2910	3250	2740	3140	7500

### Max. transmissible torque / force constant

Max. transmissible torque inline motor	[Nm]	3.2	6.5	6.8	8.2	12.4	15.6	15.7	44.4
Max. transmissible torque <sup>3)</sup> Motor parallel	[Nm]	3.5	6.4		9.1	9.3		17.5	22.8
Force constant motor inline <sup>5)</sup>	[N/Nm]	1131	565	353	1131	565	283	1131	565
Force constant motor parallel <sup>5)</sup>	[N/Nm]	1018	509	318	1018	509	254	1018	509

### Weight <sup>6)</sup>

Weight of base unit with zero stroke (incl. piston rod)	[kg]	1.2	1.2	1.4	2.2	2.2	2.4	7.1	7.5
Additional weight of inline unit	[kg]	0.7			1.0			3.2	
Additional weight of parallel unit	[kg]	0.8			1.0			3.1	
Mass of additional stroke (incl. piston rod)	[kg/m]	4.5			8.2			18.2	
Weight of piston rod with zero stroke	[kg]	0.06			0.15			0.59	
Weight of piston rod - additional length	[kg/m]	0.99			1.85			4.93	

### Mass moments of inertia

Motor parallel without stroke	[kgmm <sup>2</sup> ]	8.3	8.8	14.1	30.3	30.6	38.0	215.2	213.6
Motor inline without stroke	[kgmm <sup>2</sup> ]	7.1	7.6	12.9	25.3	25.7	33.1	166.2	164.5
Parallel/inline motor per meter	[kgmm <sup>2</sup> /m]	41.3	37.6	41.5	97.7	92.4	106.4	527.7	470.0

### Accuracy: Bidirectional Repeatability (ISO230-2)

Motor inline	[mm]	±0.03							
Motor parallel	[mm]	±0.05							

### Efficiency

Motor inline	the efficiency includes all friction torques	[%]	90						
Motor parallel		[%]	81						

### Ambient conditions

Operating Temperature	[°C]	-10...+70							
Ambient temperature	[°C]	-10...+40							
Storage temperature	[°C]	-20...+40							
Humidity	[%]	0...95 % (non-condensing)							
Location height range	[m]	max. 3000							

<sup>1)</sup> "Order Code" (page 52) & "Preferred Stroke Length" (page 54), <sup>2)</sup> Intermediate stroke lengths may be interpolated.

<sup>3)</sup> Applies only for motor speed < 100 min<sup>-1</sup>. Transmissible torque depending on the motor speed n Motor parallel see page 15.

<sup>4)</sup> ATEX on request only, <sup>5)</sup> The efficiency factors are included in the force constants.

<sup>6)</sup> Weight without rod-end and mounting option.

Cylinder size type	Unit	ETH100 <sup>4)</sup>		ETH125 <sup>4)</sup>	
		M10	M20	M10	M20
Screw lead	[mm]	10	20	10	20
Screw diameter	[mm]	50		63	

#### Travels, speeds and accelerations

Available strokes <sup>1) 2)</sup>	[mm]	continuous from 200-2000 & standard strokes		continuous from 200-2000 & standard strokes	
Max. permissible speed at stroke =					
100-400 mm	[mm/s]	400	800	417	833
500 mm	[mm/s]	400	747	417	807
600 mm	[mm/s]	333	622	395	684
800 mm	[mm/s]	241	457	290	514
1000 mm	[mm/s]	185	354	224	405
1200 mm	[mm/s]	148	284	180	329
1400 mm	[mm/s]	122	235	148	275
1600 mm	[mm/s]	102	198	125	234
2000 mm	[mm/s]	76	148	94	170
Max. Acceleration	[m/s <sup>2</sup> ]	8	10	8	10

#### Forces

Max. axial traction/thrust force motor inline	[N]		56 000	88 700	114 000
Max. axial traction/thrust. <sup>3)</sup> Motor parallel	[N]	54 800	50 800	76 300	81 400
Equivalent dynamic axial force at a lifetime of 2500 km	[N]	18 410	27 100	27 140	49 600

#### Max. transmissible torque / force constant

Max. transmissible torque inline motor	[Nm]	100	200	150	400
Max. transmissible torque. <sup>3)</sup> Motor parallel	[Nm]	108	200	150	320
Force constant motor inline <sup>5)</sup>	[N/Nm]	565	283	565	283
Force constant motor parallel <sup>5)</sup>	[N/Nm]	509	254	509	254

#### Weight <sup>6)</sup>

Weight of base unit with zero stroke (incl. piston rod)	[kg]	21	24	56	64
Additional weight of inline unit	[kg]	12		27	
Additional weight of parallel unit	[kg]	21		51	
Mass of additional stroke (incl. piston rod)	[kg/m]	38		62	
Weight of piston rod with zero stroke	[kg]	1.2		2.9	
Weight of piston rod - additional length	[kg/m]	7.7		14.4	

#### Mass moments of inertia

Motor parallel without stroke	[kgmm <sup>2</sup> ]	5860	6240	17 050	17 990
Motor inline without stroke	[kgmm <sup>2</sup> ]	2240	2620	12 960	13 400
Parallel/inline motor per meter	[kgmm <sup>2</sup> /m]	4270	4710	10 070	10 490

#### Accuracy: Bidirectional Repeatability (ISO230-2)

Motor inline	[mm]	±0.03			
Motor parallel	[mm]	±0.05			

#### Efficiency

Motor inline	the efficiency includes all friction torques	[%]	90		
Motor parallel		[%]	81		

#### Ambient conditions

Operating Temperature	[°C]	-10...+70			
Ambient temperature	[°C]	-10...+40			
Storage temperature	[°C]	-20...+40			
Humidity	[%]	0...95 % (non-condensing)			
Location height range	[m]	max. 3000			

<sup>1)</sup> "Order Code" (page 52), <sup>2)</sup> Intermediate stroke lengths may be interpolated.

<sup>3)</sup> Applies only for motor speed < 100 min<sup>-1</sup>. Transmissible torque depending on the motor speed n Motor parallel see page 15,

<sup>4)</sup> ATEX on request only, <sup>5)</sup> The efficiency factors are included in the force constants, <sup>6)</sup> Weight without rod-end and mounting option..

**Technical Data apply under normal conditions and only for the individual operating and load modes. In the case of compound loads, it is necessary to verify in accordance with normal physical laws and technical standards whether individual ratings should be reduced. In case of doubt please contact Parker.**

## Step by Step Selection Process

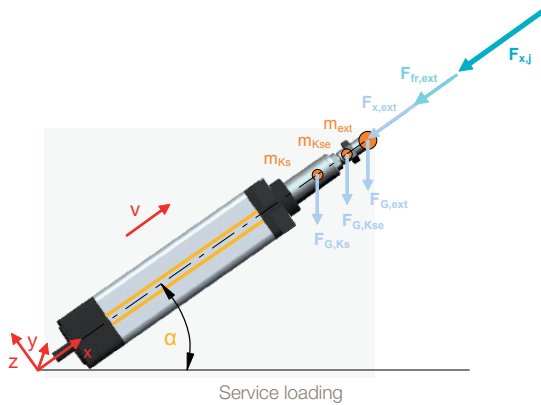
The following steps help you to specify the most suitable electro cylinder for your application. If your application's requirements exceed a maximum value, please choose a larger electro cylinder and recheck the maximum values. In some cases a smaller electro cylinder can also meet the requirements.

Step	Application data	Selection	With the aid of ...
1	ATEX or non-ATEX environment	If used in an ATEX environment, check if the ETH corresponds to the ATEX requirements of your application	"Electro Thrust Cylinder for ATEX Environment" (page 12)
2	Accuracy, ambient conditions	Check the basic conditions for the ETH in your application.	"Technical Characteristics" (page 8)
3	Required space	Check the space available in your application and select a motor mounting option: inline or parallel.	"Dimensions" (page 22)
4	Axial forces	Calculate the axial forces at different points in the application cycle.	"Calculating Required Axial Force" (page 11)
5	Maximum force required	Determine the maximum required axial force (traction and thrust force)	Determination of the maximum required axial force (page 12)
		Select the cylinder using the maximum axial traction/thrust force (please use the characteristics of your desired motor mounting option: inline or parallel).	"Technical Characteristics" (page 8)
6	Maximum speed	Select the screw lead for the desired cylinder.	"Technical Characteristics" (page 8)
7	Maximum Acceleration	Check if the maximum acceleration is sufficient.	"Technical Characteristics" (page 8)
8	Select stroke	Select the desired stroke: Determine required stroke from 'usable stroke and safety travels'. Select the desired stroke from the list of standard strokes or, if the desired stroke is not listed, define the length of the usable stroke in steps of one mm. Caution! Please respect the minimum and the maximum possible stroke.	"Stroke, Usable Stroke and Safety Travel" (page 20) "Order Code" (page 52) "Preferred Stroke Length" (page 54) "Technical Characteristics" (page 8)
9	Permissible thrust force taking the buckling risk into consideration	Check the maximum thrust force depending on the stroke and the mounting variant. Check if your application can also utilize a different mounting variant allowing to attain the maximum thrust force.	"Permissible Side Load" (page 18)
10	Service life	Determine the service life with the aid of an equivalent axial force, the operational environment (application factor) and the service life diagrams.	"Service Life" (page 13)
11	Permissible side load	Determine the lateral forces of your application and compare them to the permissible lateral forces (depending on the stroke).	Side load (page 18) Diagrams (page 18)
12	Relubricating cycle	Check if the required relubricating cycle is suitable for your production environment.	"Relubrication" (page 21)
13	Motor / gearbox	Calculate the necessary torque to generate the required force at the ETH. Select a suitable motor.	"Motor and Gearbox Selection" (page 26)
14	Motor mounting flange	Select a suitable motor mounting flange.	"Motor Mounting Options" (page 23)
15	Mounting type	Select the electro cylinder mounting method.	"Mounting Methods" (page 27)
16	Cylinder rods	Select the cylinder rod end for load mounting.	"Cylinder Rod Version" (page 33)

## Calculating Required Axial Force

Formulas 1 & 2 below give the mathematical equation for calculating the thrust required to extend or retract the piston rod.

With the aid of the axial forces, it is possible to check if the electro cylinder is able to provide the required forces and if the maximum buckling load is respected. The axial forces are also used as the calculation basis for the service life.



### Formula symbols (Formula 1-2)

$F_{x,a,j}$	= Axial forces during extension in N
$F_{x,e,j}$	= Axial forces during retraction in N
$F_{x,ext}$	= External axial force in N
$F_{G,ext}$	= Weight force caused by an additional mass in N
$F_{G,Kse}$	= Weight force caused by the cylinder rod end in N
$F_{G,Ks}$	= Weight force caused by the cylinder rod in N
$m_{ext}$	= Additional mass in kg
$m_{Kse}$	= Mass of the cylinder rod end in kg (see "Cylinder Rod Version" page 33)
$m_{Ks,0}$	= Mass of the cylinder rod at zero stroke in kg (see table "Technical Data" page 8)
$m_{Ks,stroke}$	= Mass of the cylinder rod per mm of stroke in kg (see table "Technical Data" page 8)
Stroke	= Selected stroke in m
$a_{K,j}$	= Acceleration at the cylinder rod in $m/s^2$
$\alpha$	= Alignment angle in $^\circ$
$F_{x,max}$	= Maximum permissible axial force in N
$F_{fr,ext}$	= External friction force in N

Index "j" for the individual segments of the application cycle

### Calculation of axial forces

Determine the axial forces occurring during each individual segment of the application cycle.

#### Cylinder rod extending:

$$F_{x,a,j} = F_{x,ext} + F_{fr,ext} + (m_{ext} + m_{Kse} + m_{Ks,0} + m_{Ks,Stroke} \cdot \text{Stroke}) \cdot (a_{K,j} + \sin\alpha \cdot 9.81 \frac{m}{s^2}) \quad \text{Formula 1}$$

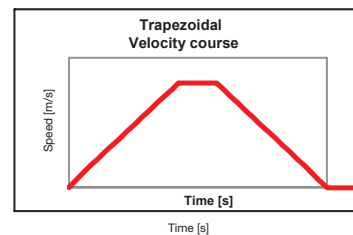
#### Cylinder rod retracting:

$$F_{x,e,j} = F_{x,ext} - F_{fr,ext} + (m_{ext} + m_{Kse} + m_{Ks,0} + m_{Ks,Stroke} \cdot \text{Stroke}) \cdot (-a_{K,j} + \sin\alpha \cdot 9.81 \frac{m}{s^2}) \quad \text{Formula 2}$$

#### Sample calculation:

##### Vertical mounting

- ETH050
- Stroke = 500 mm = 0.5 m
- Pitch = 5 mm
- Rod End: External thread
- Trapezoidal velocity course
- Acceleration  $a_k = 4 \text{ m/s}^2$
- $m_{ext} = 150 \text{ kg}$
- $F_{x,ext} = 1000 \text{ N}$
- $m_{Kse} = 0.15 \text{ kg}$
- $m_{Ks,0} = 0.15 \text{ kg}$
- $m_{Ks,Stroke} = 1.85 \text{ kg/m}$
- Alignment angle  $\alpha = -90^\circ$
- External friction force = 30 N



##### Thrust rod moving forth: Mass is moved downwards

Load case: Acceleration

$$F_{x,a,1} = 1000 \text{ N} + 30 \text{ N} + \left(150 \text{ kg} + 0.15 \text{ kg} + 0.15 \text{ kg} + 1.85 \frac{\text{kg}}{\text{m}} \cdot 0.5 \text{ m}\right) \cdot \left(4 \frac{\text{m}}{\text{s}^2} + \sin(-90^\circ) \cdot 9.81 \frac{\text{m}}{\text{s}^2}\right) = 151 \text{ N}$$

Load case: Constant Velocity

$$F_{x,a,2} = 1000 \text{ N} + 30 \text{ N} + \left(150 \text{ kg} + 0.15 \text{ kg} + 0.15 \text{ kg} + 1.85 \frac{\text{kg}}{\text{m}} \cdot 0.5 \text{ m}\right) \cdot \left(0 \frac{\text{m}}{\text{s}^2} + \sin(-90^\circ) \cdot 9.81 \frac{\text{m}}{\text{s}^2}\right) = -454 \text{ N}$$

Load case: Deceleration

$$F_{x,a,3} = 1000 \text{ N} + 30 \text{ N} + \left(150 \text{ kg} + 0.15 \text{ kg} + 0.15 \text{ kg} + 1.85 \frac{\text{kg}}{\text{m}} \cdot 0.5 \text{ m}\right) \cdot \left(-4 \frac{\text{m}}{\text{s}^2} + \sin(-90^\circ) \cdot 9.81 \frac{\text{m}}{\text{s}^2}\right) = -1058 \text{ N}$$

##### Thrust rod moving back: Mass is moved upwards

Load case: Acceleration

$$F_{x,e,4} = 1000 \text{ N} - 30 \text{ N} + \left(150 \text{ kg} + 0.15 \text{ kg} + 0.15 \text{ kg} + 1.85 \frac{\text{kg}}{\text{m}} \cdot 0.5 \text{ m}\right) \cdot \left(-4 \frac{\text{m}}{\text{s}^2} + \sin(-90^\circ) \cdot 9.81 \frac{\text{m}}{\text{s}^2}\right) = -1118 \text{ N}$$

Load case: Constant Velocity

$$F_{x,e,5} = 1000 \text{ N} - 30 \text{ N} + \left(150 \text{ kg} + 0.15 \text{ kg} + 0.15 \text{ kg} + 1.85 \frac{\text{kg}}{\text{m}} \cdot 0.5 \text{ m}\right) \cdot \left(0 \frac{\text{m}}{\text{s}^2} + \sin(-90^\circ) \cdot 9.81 \frac{\text{m}}{\text{s}^2}\right) = -514 \text{ N}$$

Load case: Deceleration

$$F_{x,e,6} = 1000 \text{ N} - 30 \text{ N} + \left(150 \text{ kg} + 0.15 \text{ kg} + 0.15 \text{ kg} + 1.85 \frac{\text{kg}}{\text{m}} \cdot 0.5 \text{ m}\right) \cdot \left(4 \frac{\text{m}}{\text{s}^2} + \sin(-90^\circ) \cdot 9.81 \frac{\text{m}}{\text{s}^2}\right) = 91 \text{ N}$$

ETH - Electro Cylinder  
Selection of the Size and Screw Lead

## Selection of the Size and Screw Lead

### Required maximum axial force

Determine the maximum axial force (page 11) that the electro cylinder must provide.

### Preselection of the electro cylinder

Using the calculated force required, compare the actual electro cylinder specifications (page 8) to determine which profile size will produce enough force.

Once you have determined a profile size, determine that the unit will physically fit in the space allowed by the application (including parallel or inline motor mounts).

### Required maximum velocity

The maximum velocity of the electro cylinder depends on the stroke.

With the profile size selected, refer to the critical speed information (page 8) to determine which screw lead works best for the application at the needed stroke length.

When the precise stroke is defined, the velocity must again be verified.

### Required maximum acceleration

The maximum acceleration depends on the screw lead and serves as an additional selection criterion for the suitable electro cylinder. It is listed in the "Technical Data" (page 8).

## ETH - Electro Thrust Cylinder for ATEX Environment

Parker Hannifin has extended its well known ETH - High Force Electro Thrust Cylinder for the use in explosive atmospheres (ATEX). The new ETH ATEX offers all advantages of the well know ETH Electro Thrust Cylinder and offers even in explosive atmospheres precise motion, positioning, setting and actuating.

The ETH ATEX range is ATEX certified for device group II, category 2 in explosive gas atmospheres. In conjunction with the ATEX certified EX series servomotors, Parker Hannifin offers a complete drive package for such applications.



### Target Market / Applications

An ATEX environment contains a mixture of air and flammable substances such as gas, vapor or fluids which are potentially explosive under atmospheric conditions. ATEX certificated devices are essential for the use under this conditions.

#### Typical applications:

- Oil & Gas Industry
- Chemical and pharmaceutical industries
- Food processing (distillery)
- Printing & Plastic Industry
- Energy (Generation of Bio gas, gas turbines)
- Automotive industry (Paint finish)
- Waste processing plants

### How to proceed when projecting a ATEX Cylinder

- Project an ETH - Electro Thrust Cylinder by means of this catalogue
- Check by means of the document "ETH ATEX frame conditions for applications" [192-550006] (order code position 9: "A" and position 12: "000") whether the selected ETH - Electro Thrust Cylinder corresponds to all ATEX demands in your application.
- In case the conditions cannot be fulfilled, please choose a larger electro cylinder and recheck the application data (e.g. changed cycle times).
- A application specific release by measuring the self-heating with your application data in our company is possible, please contact us. (see "ETH ATEX frame conditions for applications" [192-550006] ).

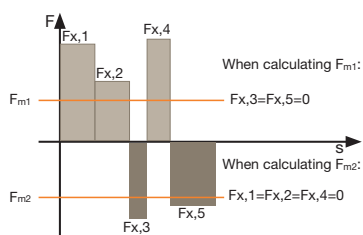
## Service Life

### Nominal service life<sup>1,2</sup>

The nominal service life of the electro cylinder can be determined with the aid of the diagrams page 14.

The forces calculated for each individual segment of the application cycle must be summarized into an equivalent axial force  $F_m$  "Calculating Required Axial Force" (page 11). If axial forces with different signs apply, two equivalent axial forces must be calculated:

- $F_{m1}$  for all positive forces. The negative forces will convert to zero.
- $F_{m2}$  for all negative forces. The positive forces will convert to zero.



### Calculation

$$F_{m1,2} = \sqrt[3]{\frac{1}{s_{total}} (F_{x,1}^3 \cdot s_1 + F_{x,2}^3 \cdot s_2 + F_{x,3}^3 \cdot s_3 + \dots)}$$
 Formula 3

With the equivalent axial forces, the nominal service life  $L$  in km can be read off the diagrams on page 14.

With **load on both sides**, the nominal service life is:

$$L = (L_1^{-1.11} + L_2^{-1.11})^{-0.9}$$
 Formula 3.1

### Actual service life

The actual service life can only be approximated due to a variety of different effects. The nominal service life  $L$  calculation does, for instance, not take insufficient lubrication, impacts and vibrations or critical side loads into consideration. These effects can however be estimated with the aid of the application factor  $f_w$ .

The actual service life is calculated as follows:

$$L_{f_w} = \frac{L}{f_w^3}$$
 Formula 4

### Application factor $f_w$

Movement cycle	Shocks/vibrations			
	none	light	medium	heavy
More than 2.5 screw rotations	1.0	1.2	1.4	1.7
1.0 to 2.5 screw rotations <sup>3)</sup> (short stroke applications)	1.8	2.1	2.5	3.0

<sup>3)</sup>After max. 10 000 movement cycles, a lubrication run must be performed (see lubrication run intervals for short stroke applications)

#### Boundary conditions for application factor $f_w$ :

- Externally guided electro cylinders
- Accelerations  $< 10 \text{ m/s}^2$

If your application factor is  $< 1.5$ , please contact Parker.

The same applies for detailed calculations or for special boundary conditions.

### Lubrication run lengths for short stroke applications

Lengths of lubrication runs [mm]	ETH032			ETH050			ETH080		ETH100		ETH125	
	M05	M10	M16	M05	M10	M20	M05	M10	M10	M20	M10	M20
>45	>54	>58	>40	>46	>58	>47	>65	>102	>140	>122	>210	

### Abbreviations used (formula 3-4)

- $F_m$  = Equivalent axial force in N
- $F_{x,j}$  = Resulting axial force in N (see formula 1 & formula 2, page 11)
- $s_j$  = Travel given a defined force  $F_{x,a,j}$  in mm
- $s_{total}$  = Total travel in mm
- $L$  = Nominal service life in km (see "Service Life" diagrams page 14)
- $L_{f_w}$  = Service life respecting the application factor in km
- $f_w$  = Application factor (see table "Application factor" page 13)

Index "j" for the individual segments of the application cycle

If you need the service life as the number of possible cycles, just divide the service life in kilometers by twice the stroke traveled. i.e. Standstill times are not taken into consideration when determining the equivalent axial force ( $F_m$ ), as  $s_j=0$ . Caution, do always consider the stroke as well as the return stroke.

<sup>1)</sup>The nominal service life is the service life reached by 90 % of a sufficient number of similar electro cylinders until the first signs of material fatigue occur.

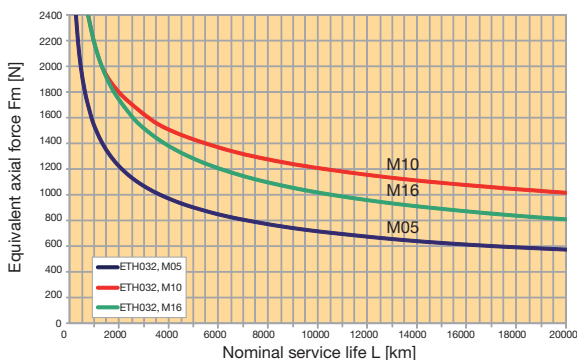
<sup>2)</sup>ATEX cylinders feature a reduced service life. Please note the brochure on "intended use" (192-550004).

## ETH - Electro Cylinder Lifetime

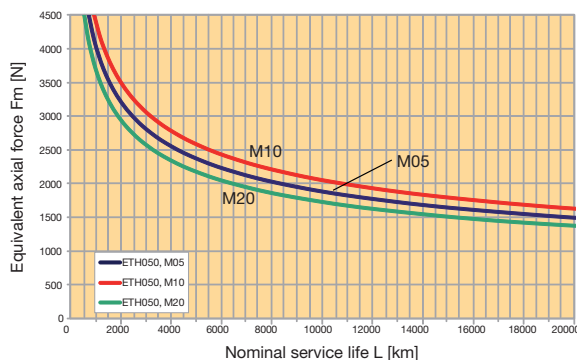
### Diagrams <sup>2</sup>

The given values apply when adhering to the recommended lubrication intervals (see relubrication). The diagrams were established in accordance with DIN ISO 3408-5

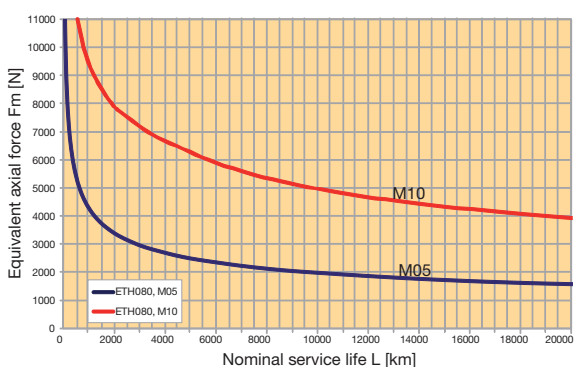
#### ETH032



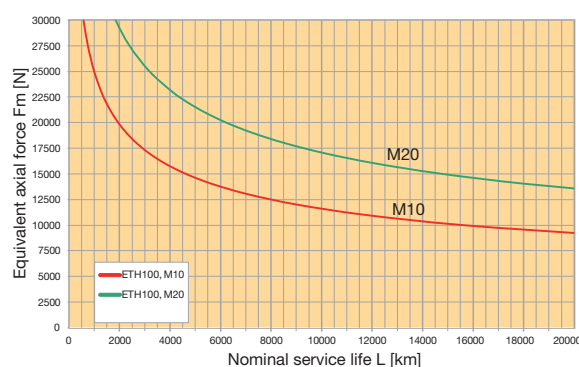
#### ETH050



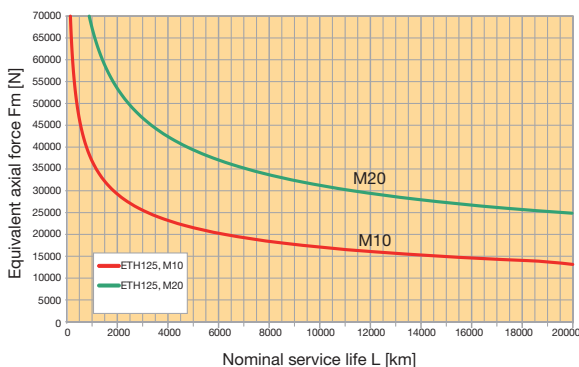
#### ETH080



#### ETH100



#### ETH125



#### Prerequisites for nominal service life

- Bearing and screw temperature between 20 °C and 40 °C.
- No impairment of the lubrication, for example by external particles.
- Relubrication in accordance with the specifications.
- The given values for thrust force, speed and acceleration must be adhered to at any rate.
- No approaching the mechanical end stops (external or internal), no other abrupt loads, as the given maximum force of the cylinder may never be exceeded.
- No external side loads
- Application factor  $f_w = 1$ . In order to calculate the real service life and the corresponding application factor, please refer to chapter "Service Life" see page 13
- No high exploitation of several power features at a time (for example maximum speed or thrust force).
- No regulating oscillation at standstill.

<sup>2</sup>ATEX cylinders feature a reduced the service life. Please note the brochure on "intended use" (192-550004).

## Permissible Torque with motor in parallel

The transmittable torque with parallel motor mounting is restricted by the belt transmission depending on the motor speed<sup>1)</sup> or on the screw pitch selected.

### Conversion

The conversion from transmittable torque to the resulting axial tensile force / compressive force to the axial speed can be calculated using formulas 9 and 10.

$$F_{x,j} = M_{\text{motor}} \cdot \text{Force constant} \quad \text{Formula 9}$$

$$v_{\text{ETH}} = \frac{n_{\text{motor}}}{60} \cdot P_{\text{ETH}} \quad \text{Formula 10}$$

#### Abbreviations used (formula 9-10)

$F_{x,j}$  = Axial tensile force / compressive force

$P_{\text{ETH}}$  = Lead screw pitch in mm

$v_{\text{ETH}}$  = Travel speed in mm / s

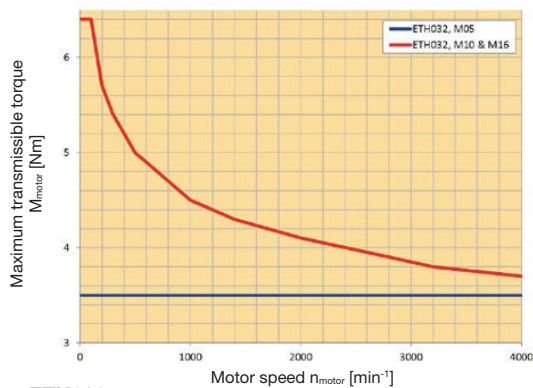
$M_{\text{motor}}$  = Motor torque in Nm

$n_{\text{motor}}$  = Motor speed in  $\text{min}^{-1}$

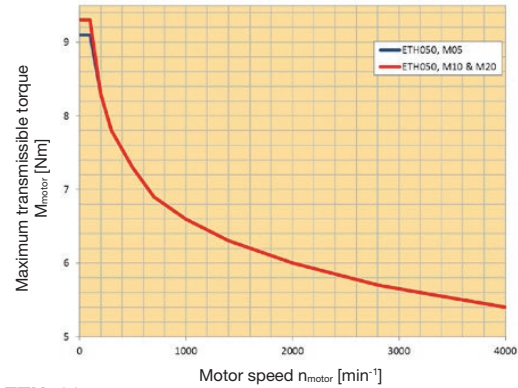
Force constant: Force constant, parallel motor mounting N/Nm (Technical data; page 8, 9)

### Diagrams

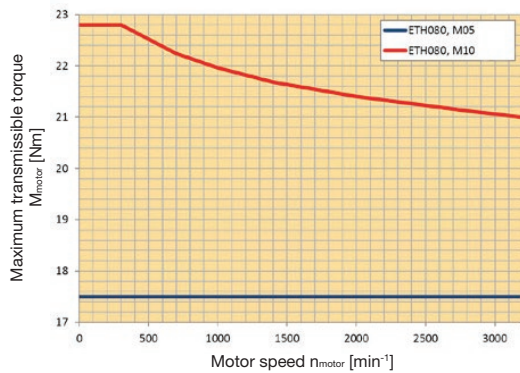
#### ETH032



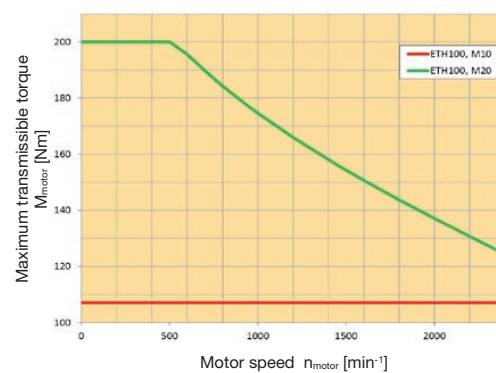
#### ETH050



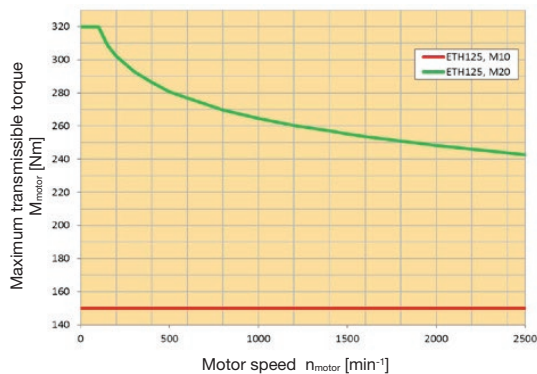
#### ETH080



#### ETH100



#### ETH125



<sup>1)</sup> Please observe the maximum permitted, stroke-dependent speed of the cylinder selected (page 8, 9).

ETH - Electro Cylinder  
Permissible Axial Thrust Forces

## Permissible Axial Thrust Forces

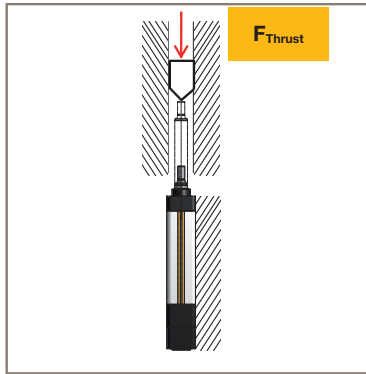
Limited by the risk of buckling, depending on the stroke and the mounting method; traction forces do not pose any buckling risk.

Please check if the maximum axial force ((page 11)) is possible with the planned mounting method and for the desired stroke

### Diagrams

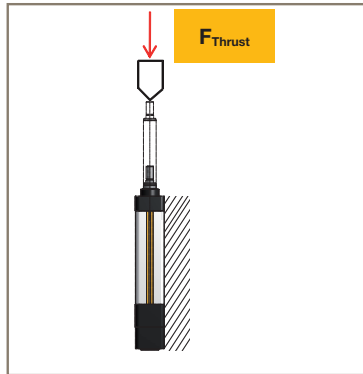
#### Case 1

Cylinders fixed with mounting flanges, foot mounting or mounting plates.  
Cylinder always fixed at the front end as well.  
Thrust rod with axial guiding.



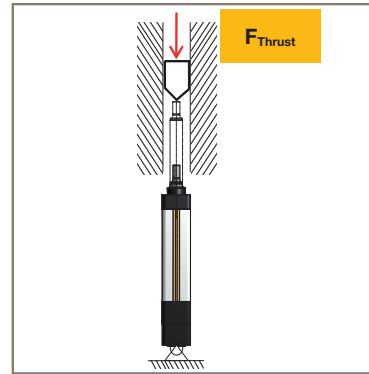
#### Case 2

Cylinders fixed with mounting flanges, foot mounting or mounting plates.  
Cylinder always fixed at the front end as well.  
Thrust rod without axial guiding. External force applied axially with respect to cylinder axis.

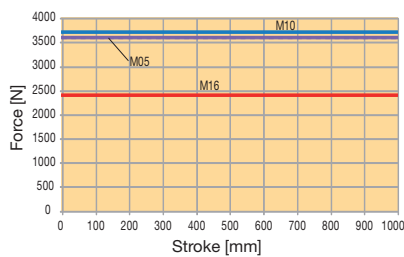


#### Case 3

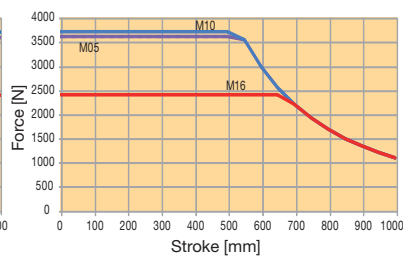
Cylinder mounted with center trunnion, rear clevis or any other rear fixing material (e.g. rear mounting plate).  
Thrust rod with axial guiding.



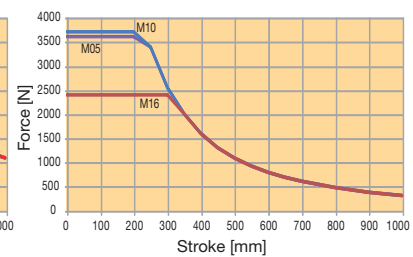
ETH032 - Case 1



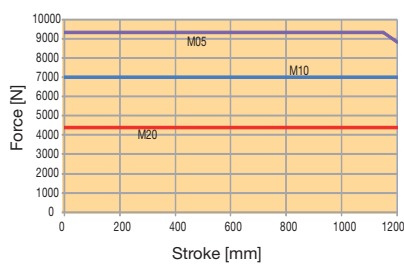
ETH032 - Case 2



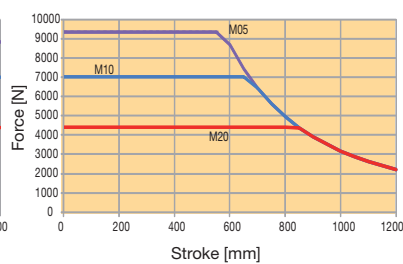
ETH032 - Case 3



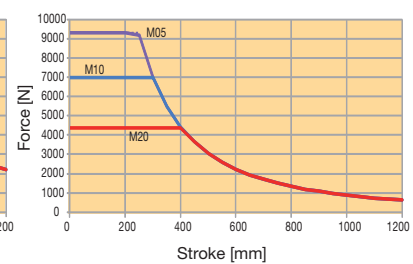
ETH050 - Case 1



ETH050 - Case 2



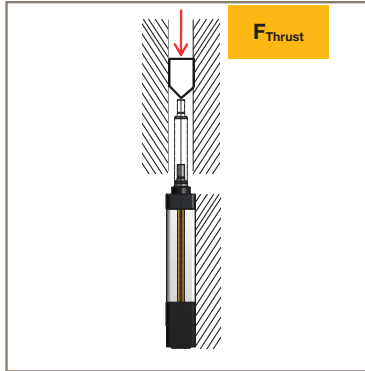
ETH050 - Case 3



## ETH - Electro Cylinder Permissible Axial Thrust Forces

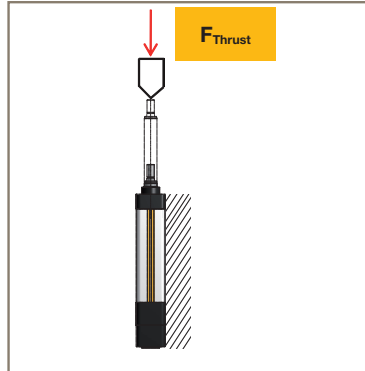
### Case 1

Cylinders fixed with mounting flanges, foot mounting or mounting plates. Cylinder always fixed at the front end as well. Thrust rod with axial guiding.



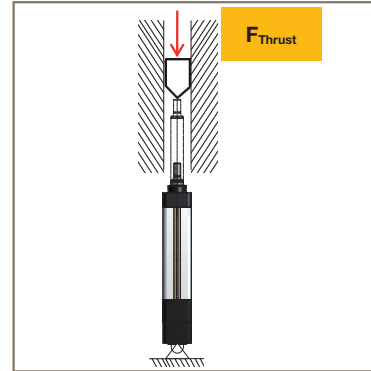
### Case 2

Cylinders fixed with mounting flanges, foot mounting or mounting plates. Cylinder always fixed at the front end as well. Thrust rod without axial guiding. External force applied axially with respect to cylinder axis.

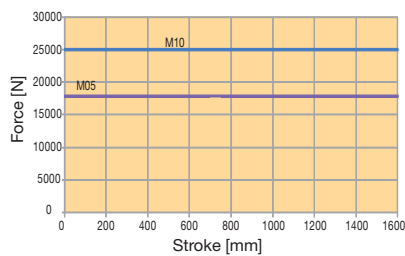


### Case 3

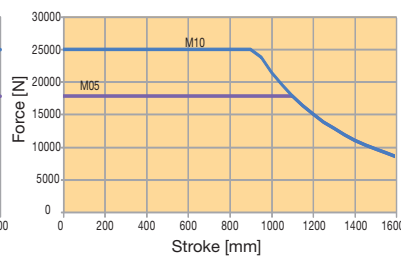
Cylinder mounted with center trunnion, rear clevis or any other rear fixing material (e.g. rear mounting plate). Thrust rod with axial guiding.



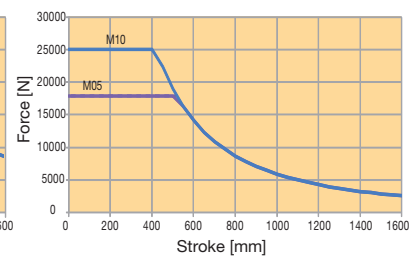
**ETH080 - Case 1**



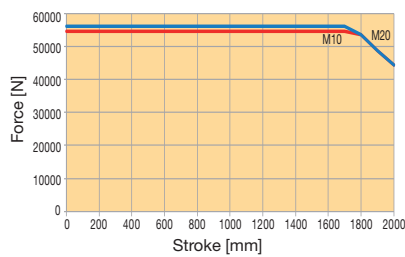
**ETH080 - Case 2**



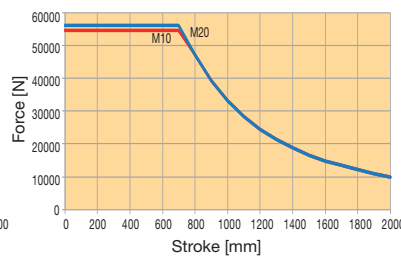
**ETH080 - Case 3**



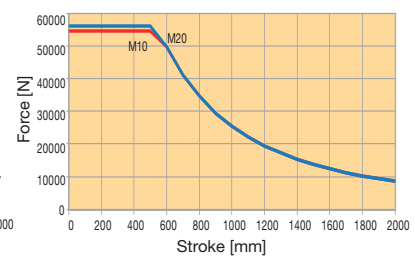
**ETH100 - Case 1**



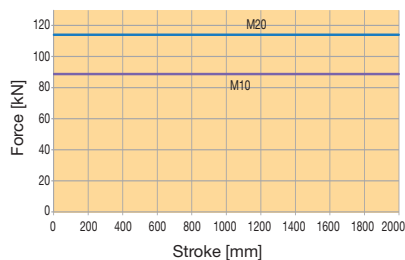
**ETH100 - Case 2**



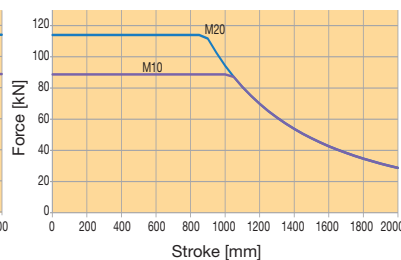
**ETH100 - Case 3**



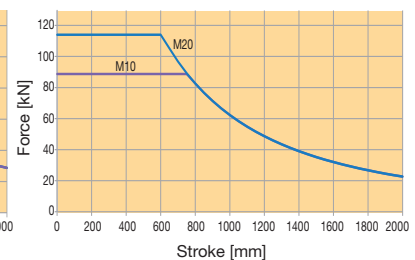
**ETH125 - Case 1**



**ETH125 - Case 2**



**ETH125 - Case 3**



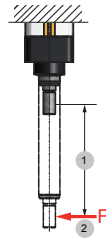
ETH - Electro Cylinder  
Permissible Side Load

## Permissible Side Load <sup>1)</sup>

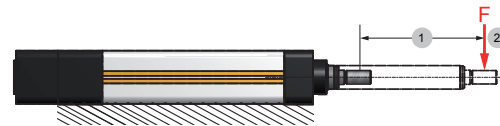
The electro cylinder features a generously dimensioned cylinder rod and screw nut bearing in the form of high-quality plastic sliding elements to absorb the side load. Please note that electro cylinders with a longer stroke permit a higher lateral force at the same extension length. It may therefore be useful to choose a longer stroke

than required for the application in order to increase the permissible lateral force. If the permissible lateral forces are exceeded or if the maximum axial force occurs at the same time, the optional outrigger bearing (option R) must be used.

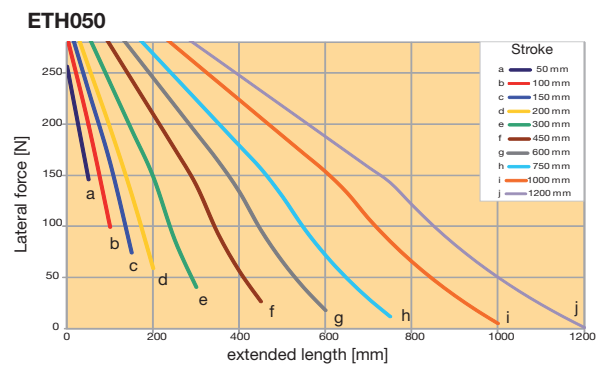
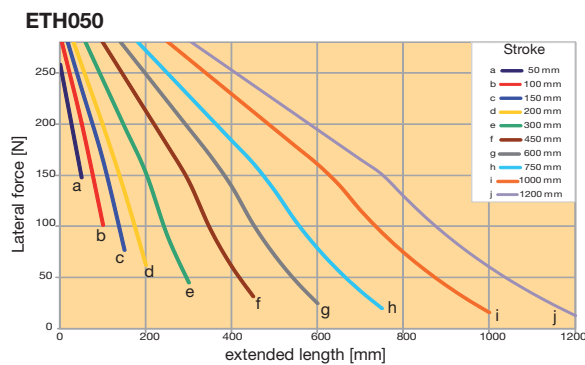
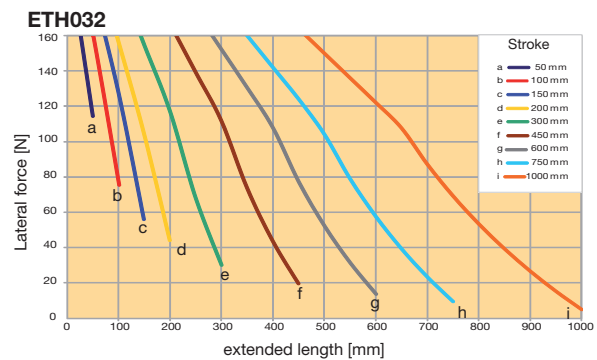
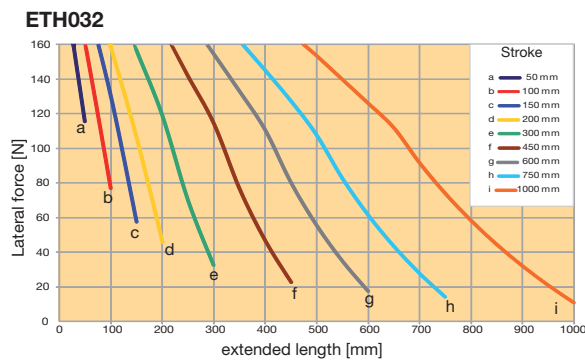
### Permissible lateral forces in vertical mounting position



### Permissible lateral forces in horizontal mounting position



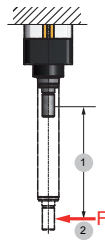
1: Extended length  
2: Force application - at the middle of the cylinder rod thread



The diagrams apply for an ambient temperature of 20 °C, for all housing orientations and a medium travel speed of 0.5 m/s, (ETH032, ETH050, ETH080) or 0.25 m/s (ETH100, ETH125).

<sup>1)</sup> For ATEX cylinders, side loads are not permitted!

**Permissible lateral forces in vertical mounting position**

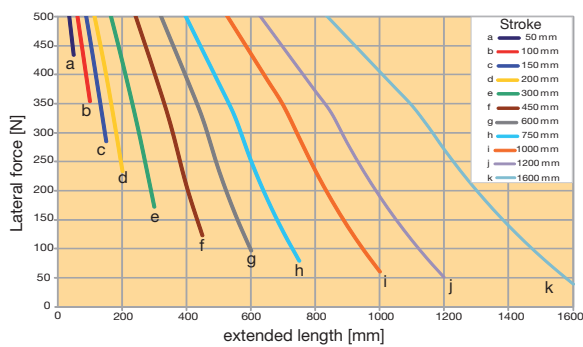


**Permissible lateral forces in horizontal mounting position**

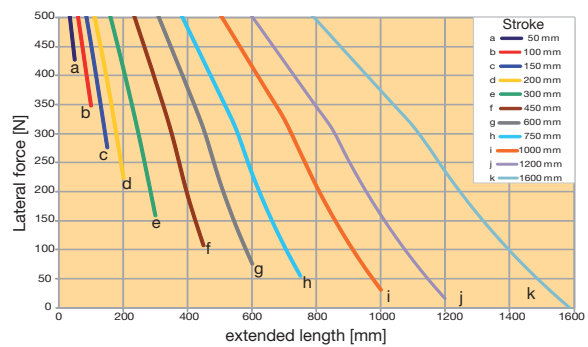


1: Extended length  
2: Force application - at the middle of the cylinder rod thread

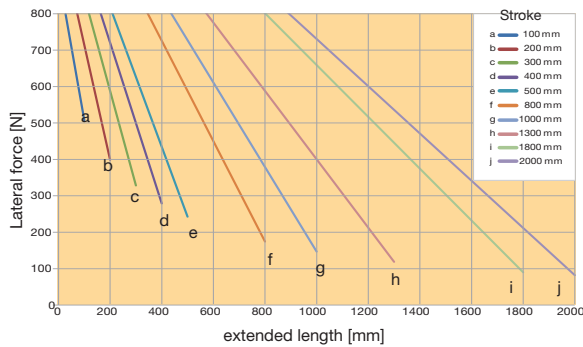
**ETH080**



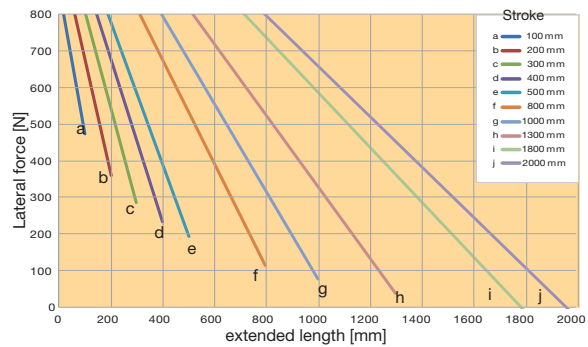
**ETH080**



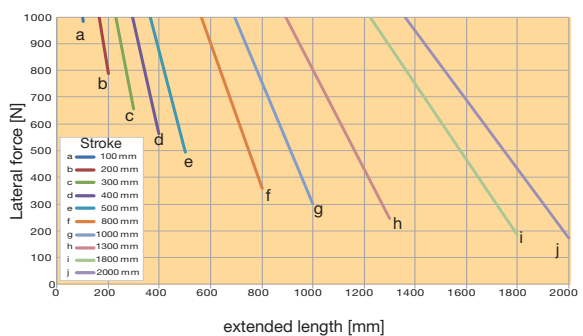
**ETH100**



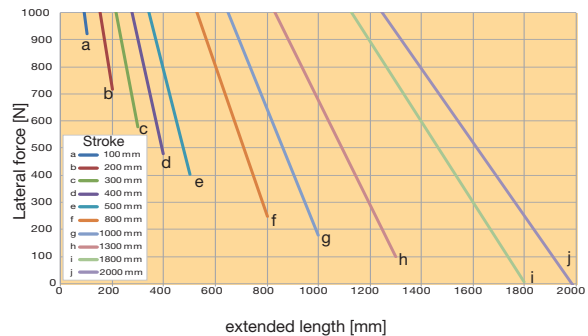
**ETH100**



**ETH125**



**ETH125**



The diagrams apply for an ambient temperature of 20 °C, for all housing orientations and a medium travel speed of 0.5 m/s, (ETH032, ETH050, ETH080) or 0.25 m/s (ETH100, ETH125).

<sup>1)</sup> For ATEX cylinders, side loads are not permitted!

ETH - Electro Cylinder  
Stroke, Usable Stroke and Safety Travel

## Stroke, Usable Stroke and Safety Travel

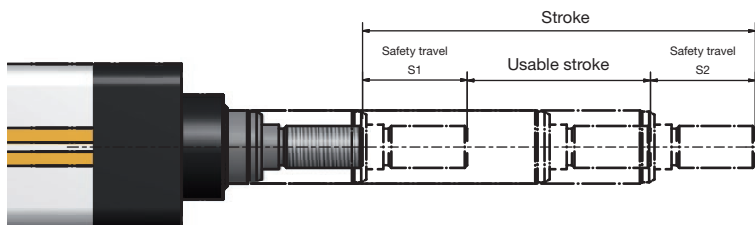
### Calculation

#### Stroke:

The stroke to be indicated in the order code is the mechanically maximal possible stroke between the internal end stops.

#### Usable stroke:

The usable stroke is the distance which you need to move in your application. It is always shorter than the stroke.



#### Safety travel (S1 & S2):

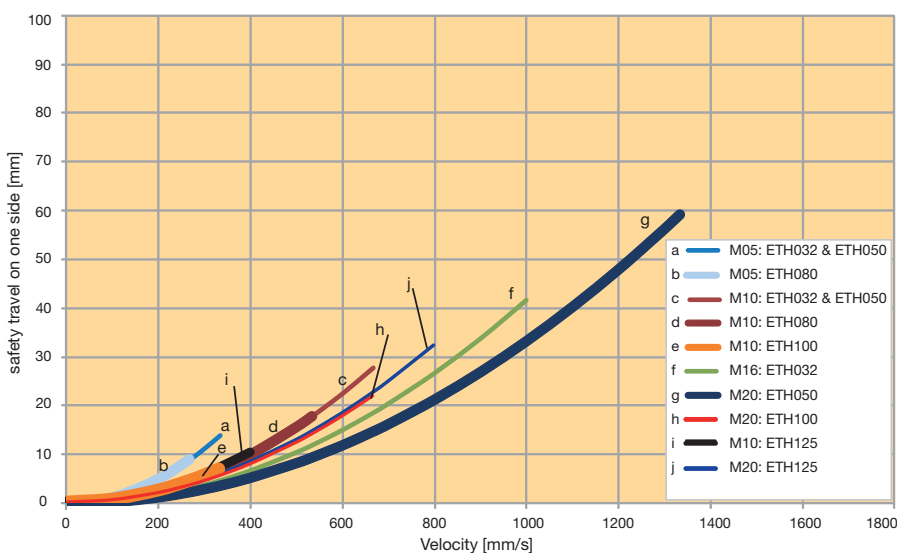
The safety travels are required to slow down the cylinder after it has passed a limit switch, Emergency stop in order to avoid contact with the mechanical limit stops.

Depending on the screw lead and the maximum speed, the following diagram recommends a minimum

safety travel, which is sufficient for most applications according to experience.

With demanding applications (great masses and high dynamic), the safety travel has to be calculated and enlarged accordingly (dimensioning on demand).

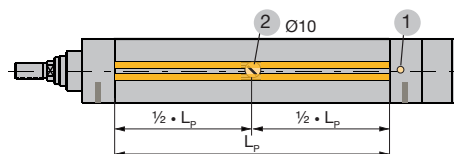
### Diagram



**Information:** The safety travel taken from the diagram applies for one side. I.e. the diagram value must be multiplied by factor 2 in order to get the total safety travel. The diagram is based on the maximum screw acceleration / deceleration

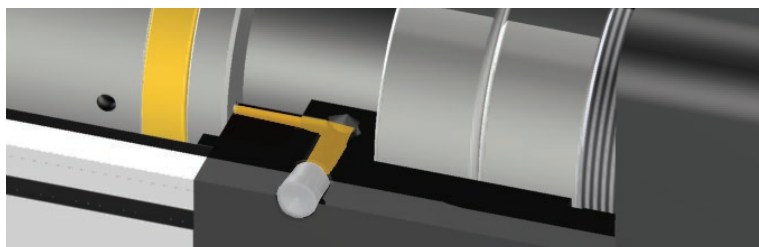
## Relubrication

All frame sizes include a standard Easy lubrication port for lubricating the screw nut (designation "1" in the order code page 52).



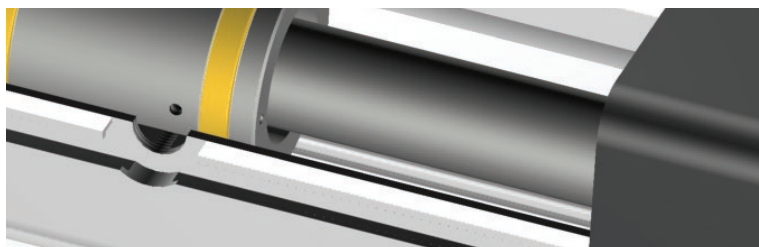
- 1: Central lubrication (standard)
- 2: Optional lubrication (possible on all 4 sides).
- $L_p$ : Length of profile

### Option 1: Central lubrication (standard)



Relubrication is simple using the easy access port. Users simply perform a controlled retract of the cylinder approaching the end stop under slow speed and grease the cylinder. Central relubrication orientation is always envisaged in a 3 o'clock position.

### Option 2...5: Middle lubrication via an opening in the profile



If a space constraint does not allow easy access to the standard lubrication port, other options are available. Free access to this bore, even after integration of the cylinder into a system, can be ensured by choosing the corresponding profile orientation (see order code page 52). The bore is located in the middle of the aluminum profile.

In case of actuators with very short strokes, the position of the lubrication port in the center of the profile may not be possible. In this case, the relubrication position is located centrally in the stroke range. For more information see mounting instructions manual. ([www.parker.com/eme/eth](http://www.parker.com/eme/eth))

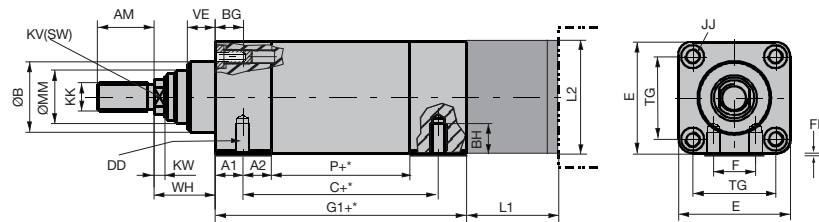
Use a suitable pipe for the funnel type lubricating nipple, Type D1a4 DIN3405:Beaked nozzle Item No.: 180-006043 (connection thread 1/8 ")

ETH - Electro Cylinder  
Dimensions

## Dimensions

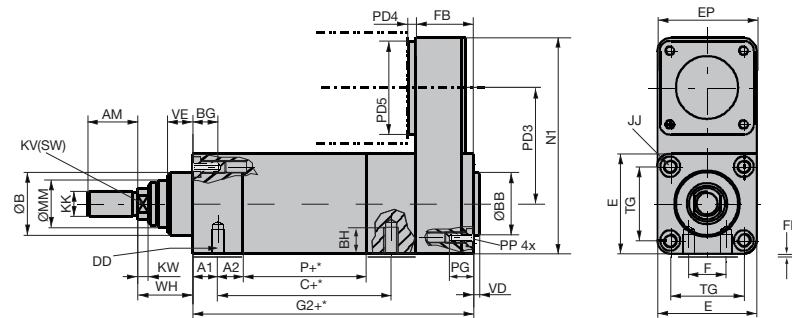
### Electro Cylinder

prepared for inline motor mounting



### Electro Cylinder

prepared for parallel motor mounting



+\* = Measure + length of desired stroke

### Dimensions Standard & ATEX (IP-Version)

Cylinder size	Unit	ETH032			ETH050			ETH080		ETH100		ETH125	
		M05	M10	M16	M05	M10	M20	M05	M10	M10	M20	M10	M20
Screw lead													
C	[mm]	93.6 (93.6)	102.6 (102.6)	106.6 (106.6)	99.5 (100.5)	105.5 (106.5)	117.5 (118.5)	141.5 (142.5)	159.5 (160.5)	- 2)		- 2)	
G1	[mm]	133 (180.5)	142 (189.5)	146 (193.5)	154 (198.5)	160 (204.5)	172 (216.5)	197 (259.5)	215 (277.5)	323 (349.5)	361 (387.5)	461 (487.5)	549 (575.5)
G2	[mm]	180.5 (228.5)	189.5 (237.5)	193.5 (241.5)	194 (239)	200 (245)	212 (257)	257 (320)	275 (338)	451 (478.0)	489 (516.0)	624 (651.0)	712 (739.0)
P	[mm]	66	75	79	67	73	85	89	107	162	200	192	280
A1	[mm]	14 (60)			15.5 (58.5)			21 (82)		- 2)		- 2)	
A2	[mm]	17			18.5			32		- 2)		- 2)	
AM	[mm]	22			32			40		70		96	
BG (=BN+BS)	[mm]	16			25			26		32		44	
BN Usable length of thread	[mm]	11			20			20		22		33	
BS Depth of width across flat (without thread)	[mm]	5			5			6		10		11	
BH	[mm]	9			12.7			18.5		- 2)		- 2)	
DD mount thread <sup>1)</sup>	[mm]	M6x1.0			M8x1.25			M12x1.75		- 2)		- 2)	
E	[mm]	46.5			63.5			95		120		150	
EP	[mm]	46.5			63.5			95		175		220	
F	[mm]	16			24			30		- 2)		- 2)	
FF	[mm]	0.5			0.5			1.0		0		0	
JJ	[mm]	M6x1.0			M8x1.25			M10x1.5		M16x2		M20x2.5	
PP	[mm]	M6x1.0			M8x1.25			M10x1.5		M16x2		M20x2.5	
PG (Thread depth on the PA housing)	[mm]	BG (=BN+BS)			BG (=BN+BS)			BG (=BN+BS)		26		35	
KK	[mm]	M10x1.25			M16x1.5			M20x1.5		M42x2		M48x2	
KV	[mm]	10			17			22		46		55	
ØMM h9	[mm]	22			28			45		70		85	
TG	[mm]	32.5			46.5			72		89		105	
KW	[mm]	5			6.5			10		10		10	
N1	[mm]	126			160			233.5		347		450	
FB	[mm]	47.5 (48)			40 (40.5)			60 (60.5)		128 (128.5)		163 (163.5)	
VD	[mm]	4			4			4		4		5	
ØBB	[mm]	30 d11			40 d11			45 d11		90 d9		110 d8	
VE	[mm]	12			16			20		20		20	
WH	[mm]	26			37			46		51		53	
ØB	[mm]	30 d11			40 d11			60 d11		90 d8		110 d8	

<sup>1)</sup> Thread "DD" is only mandatory for mounting method "F".

<sup>2)</sup> ETH100, ETH125 does not have a mounting thread on the underside.

# Motor Mounting Options <sup>1)</sup>

Dimensions [mm]

		Motor Dimensions					Motor mounting options			
inline		Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	L1	L2	
ETH032		K1B	SMH60-B5/11	60	75	11	23	60.0	70.0	X
		K1B	NX3, EX3	60	75	11	23	60.0	70.0	
		K1C	SMH82-B8/14	80	100	14	30	67.0	82.0	
		P1A	--	50	70	16	40	77.0	63.5	
		P1G	PE3	40	52	14	35	72.0	63.5	
parallel		Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	PD3	PD4	PD5
ETH032		K1B	SMH60-B5/11	60	75	11	23	67.5	9.0	70.0
		K1B	NX3	60	75	11	23		9.0	70.0
		K1B	EX3	60	75	11	23		72.5	70.0
		K1C	SMH82-B8/14	80	100	14	30		14.0	82.0
		P1A	--	50	70	16	40		22.0	63.5
		P1G	PE3	40	52	14	35		16.0	63.5

		Motor dimensions					Motor mounting options				
inline		Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	L1	L2		
ETH050		K1B	SMH60-B5/11	60	75	11	23	59	70	X	
		K1B	NX3	60	75	11	23	59	70		
		K1C	SMH82-B8/14	80	100	14	30	63	82		
		K1E	SMH82-B5/19	95	115	19	40	84	100		
		K1E	SMH100-B5/19	95	115	19	40	84	100		
		K1E	MH105-B5/19	95	115	19	40	84	105		
		K1D	MH105-B9/19	80	100	19	40	84	105		
		K1D	SMH82-B8/19	80	100	19	40	84	82		
		K1D	NX4, EX4	80	100	19	40	84	82		
		P1A	--	50	70	16	40	74	63.5		
		P1G	PE3	40	52	14	35	69	63.5		
		parallel		Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length		PD3
ETH050		K1B	SMH60-B5/11	60	75	11	23	87.5	9	70	
		K1B	NX3	60	75	11	23		9	70	
		K1C	SMH82-B8/14	80	100	14	30		13	82	
		K1D	EX4	80	100	19	40		92	92	
		K1F	SMH100-B5/14 <sup>2)</sup>	95	115	14	30		13	100	
		P1A	--	50	70	16	40		24	63.5	
		P1G	PE3	40	52	14	35		16	63.5	

<sup>1)</sup> For ETH ATEX version use only ATEX certified motors/gearboxes (e.g. EX motor series)

<sup>2)</sup> Order Code SMH100-B5/14: "SMH100...ET..." (the motor shaft diameter is replaced by the term "ET")

(not in the motors catalog) only with feedback: Resolver, A7

ETH032/ETH050/ETH080: Motors always with key groove on the output shaft.

Additional motor mounting options on request.

Before mounting a motor not listed above, please consult the Parker support team at em-motion@parker.com.

**Details on the Internet:**

**Motors**

[www.parker.com/eme/smh](http://www.parker.com/eme/smh), [www.parker.com/eme/mh](http://www.parker.com/eme/mh)  
[www.parker.com/eme/nx](http://www.parker.com/eme/nx), [www.parker.com/eme/ex](http://www.parker.com/eme/ex)

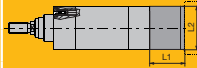
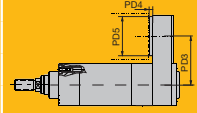
**Gearboxes**


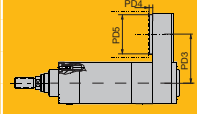
[www.parker.com/eme/gear](http://www.parker.com/eme/gear)



## ETH - Electro Cylinder Motor Mounting Options

Dimensions [mm]

			Motor Dimensions				Motor mounting options				
			Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	L1	L2	
ETH100	inline		K1J	SMH115-B7/24, NX6, EX6	110	130	24	50	155	140	
		K1K	SMH142-B5/24	130	165	24	50	155	145		
		K1K	MH145-B5/24	130	165	24	50	155	145		
		K1L	MH205-B5/38	180	215	38	80	185	205		
		K1L	SMH170-B5/38	180	215	38	80	185	205		
		P1C	--	110	130	32	68	175	140		
		P1D	--	130	165	40	102	207	142		
		P1J	PE5	110	130	25	55	160	140		
	parallel		Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	PD3	PD4	PD5
		K1J	SMH115-B7/24, NX6, EX6	110	130	24	50		23	155	
		K1K	SMH142-B5/24	130	165	24	50		22	155	
		K1K	MH145-B5/24	130	165	24	50		22	155	
		K1L	MH205-B5/38	180	215	38	80		27	205	
		K1L	SMH170-B5/38	180	215	38	80		27	205	
P1C	--	110	130	32	68		38	155			
P1D	--	130	165	40	102		45	155			
P1J	PE5	110	130	25	55		23	155			

			Motor Dimensions				Motor mounting options					
			Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	L1	L2		
ETH125	inline		K1L	SMH170	180	215	38	80	209.5	205		
		K1L	MH205	180	215	38	80	209.5	205			
		K1M	MH265	250	300	48	110	239.5	264			
		P1C	--	110	130	32	68	197.5	170			
		P1D	--	130	165	40	102	231.5	170			
		P1K	PE7	120	140	40	97	226.5	205			
		parallel		Code	Motor / gearbox	Pilot	Bolt circle	∅ Shaft	Shaft length	PD3	PD4	PD5
			K1L	SMH170	180	215	38	80		25	205	
	K1L		MH205	180	215	38	80		25	205		
	K1M		MH265	250	300	48	110		45	264		
	P1C		--	110	130	32	68		32	185		
	P1D		--	130	165	40	102		45	185		
	P1K	PE7	120	140	40	97		42	205			

ETH100/ETH125: Motors always without key groove on the output shaft.

Additional motor mounting options on request.

Before mounting a motor not listed above, please consult the Parker support team at [em-motion@parker.com](mailto:em-motion@parker.com).

### Details on the Internet:

#### Motors

[www.parker.com/eme/smh](http://www.parker.com/eme/smh)  
[www.parker.com/eme/mh](http://www.parker.com/eme/mh)  
[www.parker.com/eme/nx](http://www.parker.com/eme/nx)  
[www.parker.com/eme/ex](http://www.parker.com/eme/ex)

#### Gearboxes

[www.parker.com/eme/gear](http://www.parker.com/eme/gear)

## Motor and Gearbox Selection

### Drive torque calculation

The torques to be produced by the motor result from the acceleration, the load and the friction torque. The drive torques must be calculated for all segments of the application cycle (represented by index "j")

Calculation of the **acceleration torque** with respect to the rotary moments of inertia:

$$M_{B,j} = \left( J_{i/p,0} + J_{i/p,Stroke} \cdot Stroke \right) \cdot \frac{1}{\eta_{ETH}} \cdot \frac{1}{i_G^2 \cdot \eta_G + J_G + J_M} \cdot 10^{-3} \cdot \frac{6.28 \cdot a_{K,j}}{P_h}$$

**only with gearbox**

Formula 5

The acceleration forces due to the translatory moved masses are taken into consideration in the calculation of the axial forces on (page 11).

The **load torques** result from the occurring axial forces:

$$M_{L,j} = \frac{F_{x,a/e,j}}{\text{Thrust force factor}} \cdot \frac{1}{i_G \cdot \eta_G}$$

**only with gearbox**

Formula 6

The motor must therefore generate the following drive torques:

$$M_{M,j} = M_{B,j} + M_{L,j}$$

Formula 7

The **effective torque** can be deduced from the drive torques for all segments of the application cycle (formula 7):

$$M_{eff} = \sqrt[2]{\frac{1}{t_{total}} \cdot (M_{M1}^2 \cdot t_1 + M_{M2}^2 \cdot t_2 + \dots)}$$

Formula 8

### Motor dimensioning

- The nominal torque of the motor must exceed the calculated effective torque (formula 8).
- The peak torque of the motor must exceed the maximum occurring drive torque (formula 7).

With the aid of the "motor mounting options" chart you can check if the respective motor is mechanically compatible to the corresponding electro cylinder.

#### Abbreviations used (formula 5-8)

$M_{B,j}$	= Variable acceleration torque in Nm
$J_{i/p,0}$	= Red. rot. mass moment of inertia at zero stroke for inline/parallel motor configuration in kgmm <sup>2</sup> see "Technical Data" page 8
$J_{i/p, Stroke}$	= Red. rot. mass moment of inertia per mm of stroke for inline/parallel motor configuration in kgmm <sup>2</sup> see "Technical Data" page 8
Stroke	= Selected stroke in mm
$\eta_{ETH}$	= Efficiency of the electro cylinder      0.9 (inline drive configuration) 0.81 (parallel motor)
$i_G$	= Gearbox ratio
$\eta_G$	= Efficiency of the gearbox (see gearbox manufacturer specifications)
$J_M$	= Motor mass moment of inertia in kgmm <sup>2</sup> /mm (see motor manufacturer specifications)
$J_G$	= Gearbox mass moment of inertia in kgmm <sup>2</sup> /mm (see gearbox manufacturer specifications)
$a_{K,j}$	= Acceleration at the cylinder rod in m/s <sup>2</sup>
$P_h$	= Screw pitch in mm
$M_{L,j}$	= Load torque in Nm
$F_{x,a/e,j}$	= Loads in x direction in N (see page 11)
$M_{M,j}$	= Drive torque in Nm
$M_{eff}$	= Effective value - motor in Nm
$t_{total}$	= Total cycle time in s
$t_j$	= Amount of time in the cycle in s

Force constant: "Technical Characteristics" see page 8.

Index "j" for the individual segments of the application cycle

## Mounting Methods

Please respect the notes in the ETH Manual (19x-550002) on the permissible screws and tightening torques.

### Standard



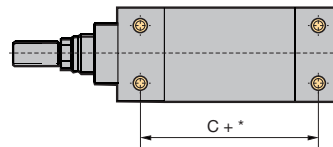
ETH032-ETH125



Example for parallel motor configuration

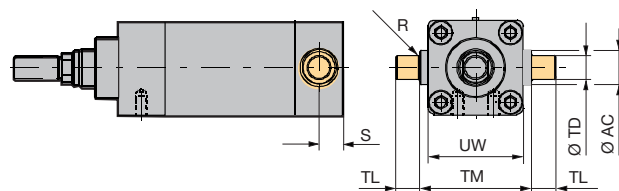
Mounting via thread on the cylinder front or end side with parallel motor configuration (ETH032-ETH125).  
("Dimensions" see page 22)

ETH032-ETH080



Mounting with 4 mounting threads on the underside of the profile.  
(ETH032-ETH080).  
("Dimensions" see page 22)

### Center Trunnion Mounting



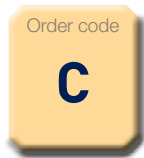
	UW	ØTD (h8)	R	TL	TM	ØAC	S
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETH032</b>	46.5	12	1	12	50	18	25.5
<b>ETH050</b>	63.5	16	1	16	75	25	39
<b>ETH080</b>	95.3	25	2	25	110	35	34.5
<b>ETH100</b>	120	40	4	40	140	70	57
<b>ETH125</b>	150	50	10	52	160	90	100

+\* = Measure + Length of desired stroke ("Dimensions" see page 22).

Note: For relubrication option "1" (central lubrication port) please see mounting method with option "D" center trunnion always on 6 o'clock!

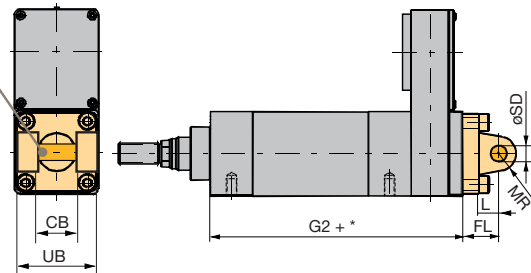
ETH - Electro Cylinder  
Mounting types

Rear Clevis



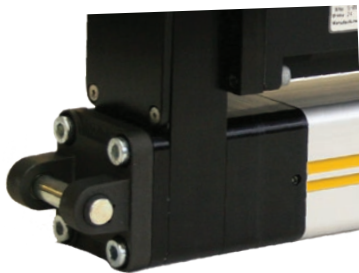
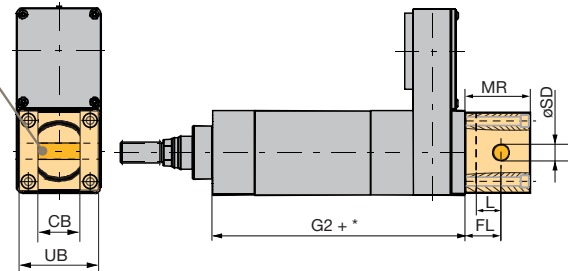
ETH032-ETH080

Stainless  
screws &  
bolts



ETH100 & ETH125

Stainless  
screws &  
bolts



	Order no.	UB	CB	ØSD	MR	L	FL ±0.2
		[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETH032</b>	0112.031	46.5	26	10 h9	9.5	13	22
<b>ETH050</b>	0122.031	63.5	32	12 h9	12.5	16	27
<b>ETH080</b>	0132.031	95	50	16 h9	17.5	22	36
<b>ETH100</b>	0142.031	120	60.5	30 f7	100	40	65
<b>ETH125</b>	0152.031	150	70.5	50 f7	145	55	90

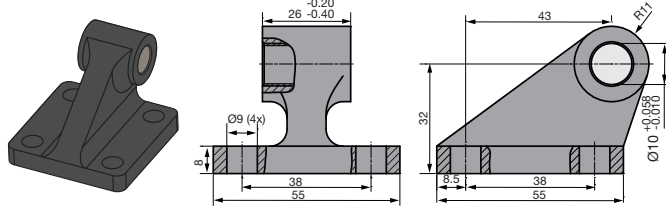
+\* = Measure + length of desired stroke ("Dimensions" see page 22).  
Listed in the order code of the cylinder; the order number applies only for ordering spare parts. Spare parts delivery is including screws for cylinder mounting.

### Bearing Block

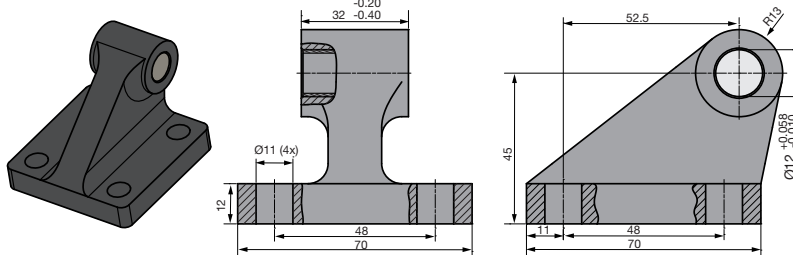
Counter piece of rear clevis. Please order separately with order no., if required

Dimensions [mm]

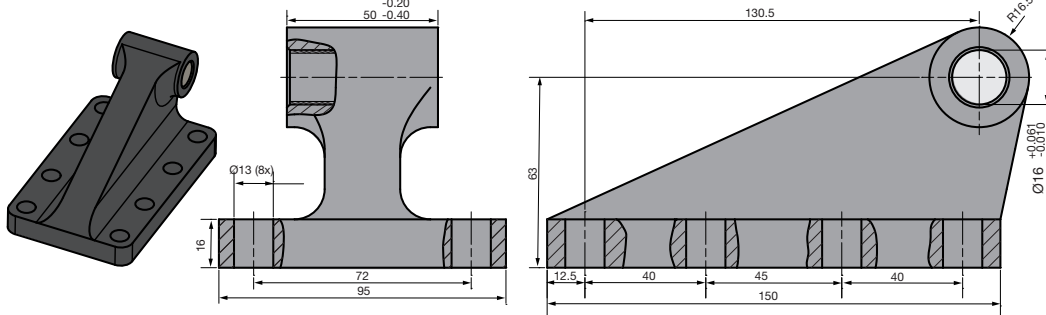
**Bearing block for ETH032, Part No. 0112.039**



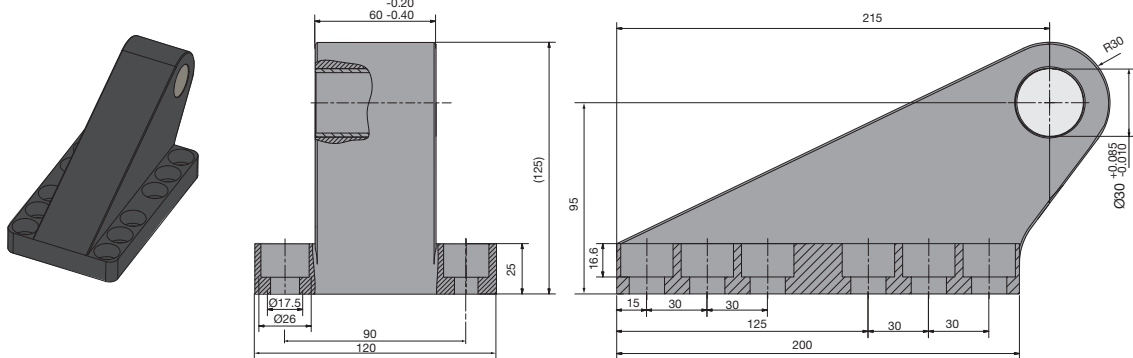
**Bearing block for ETH050, Part No. 0122.039**



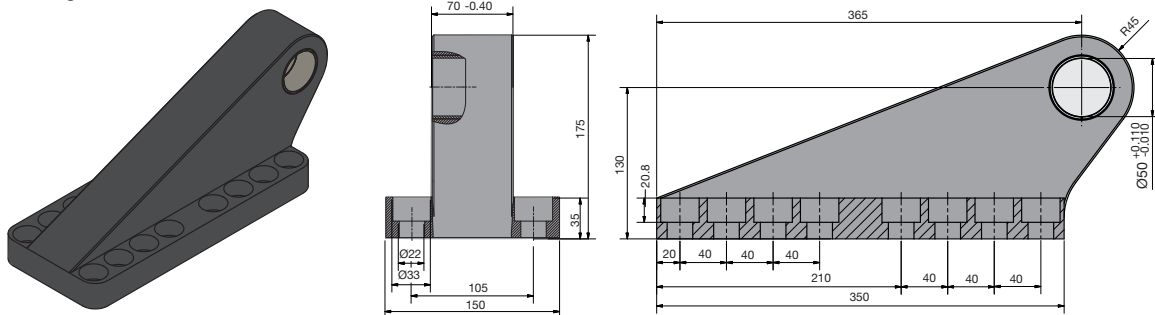
**Bearing block for ETH080, Part No. 0132.039**



**Bearing block for ETH100, Part No. 0142.039**

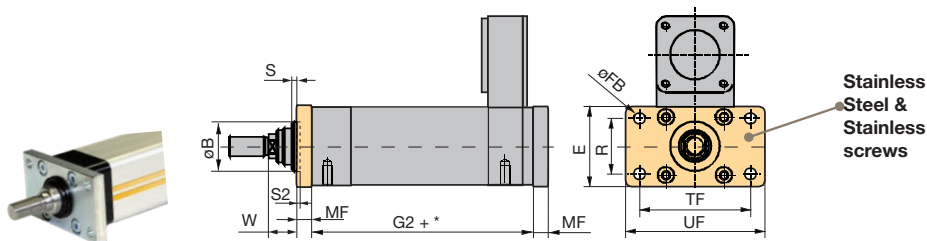
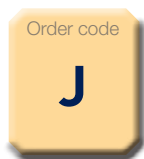


**Bearing block for ETH125, Part No. 0152.039**



ETH - Electro Cylinder  
Mounting types

Front Plate



Front plate (J) dimensions

	Order no. (1 piece)	UF	E	TF	ØFB	R	W	MF	ØB Rear Plate	ØB Front plate	S	S2
		[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETH032</b>	0112.918	80	48	64	7	32	16	10	30		2	-
<b>ETH050</b>	0122.918	110	65	90	9	45	25	12	40		4	-
<b>ETH080</b>	0132.919 <sup>(1)</sup>	150	95	126	12	63	30	16	45	60	4	-
<b>ETH100</b>	0142.918	258	120	220	17.5	80	26	25	90		-	5
<b>ETH125</b>	0152.918	320	150	270	21.5	100	13	40	110		-	20

+\* = Measure + Length of desired stroke ("Dimensions" see page 22).

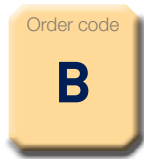
Listed in the order code of the cylinder; the order number applies only for ordering spare parts.

Spare parts delivery is including screws for cylinder mounting.

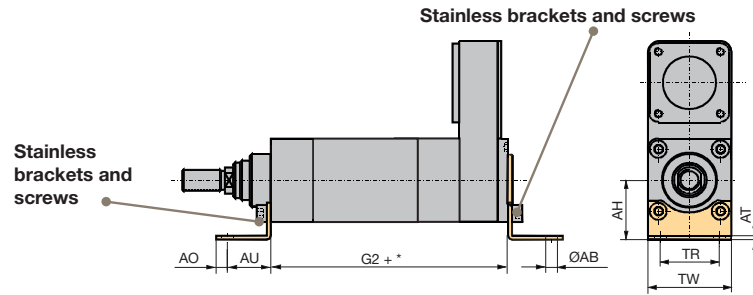
Stainless components only available for ETH032-ETH100.

<sup>(1)</sup> Note: This plate is not useable as rear plate

### Foot Mounting

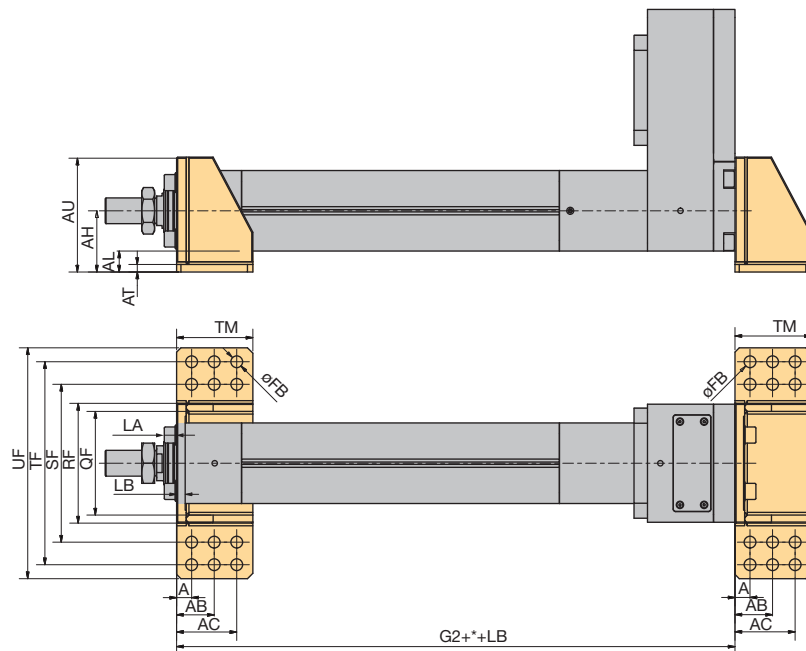
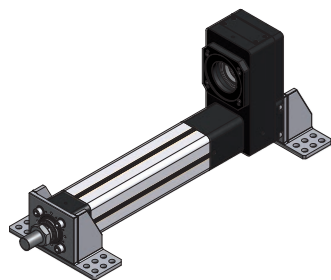


ETH032-ETH080



	Order no. Front & Terminal bracket	AH	AT	TR	ØAB (H14)	AO	AU	TW
		[mm]						
<b>ETH032</b>	0112.916	32	4	32	7	8	24	46.5
<b>ETH050</b>	0122.916	45	4	45	9	12	32	63.5
<b>ETH080</b>	0132.916	63	6	63	13.5	15	41	95

### ETH100 & ETH125



	Order no. Front & Terminal bracket	AU	AH	AL	AT	UF	TF	SF	RF	QF	LA	LB	ØFB	TM	A	AB	AC
		[mm]															
<b>ETH100</b>	0142.916	164	94	34	14	290	-	246	200	170	19	13	17.5	99	16.5	49.5	81.5
<b>ETH125</b>	0152.916	214	114	39	14	430	378	294	223	193	23	16	22	142	28	70	112

+\* = Measure + Length of desired stroke ("Dimensions" see page 22).

Listed in the order code of the cylinder; the order number applies only for ordering spare parts. Spare parts delivery is including screws for cylinder mounting.

Stainless components only available for ETH032-ETH080.

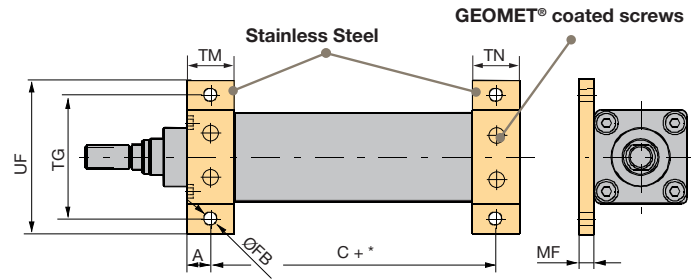
\* For protection classes "B" and "C", we recommend GEOMET® coated screws (thin layer corrosion protection).

ETH - Electro Cylinder  
Mounting types

### Mounting Flanges

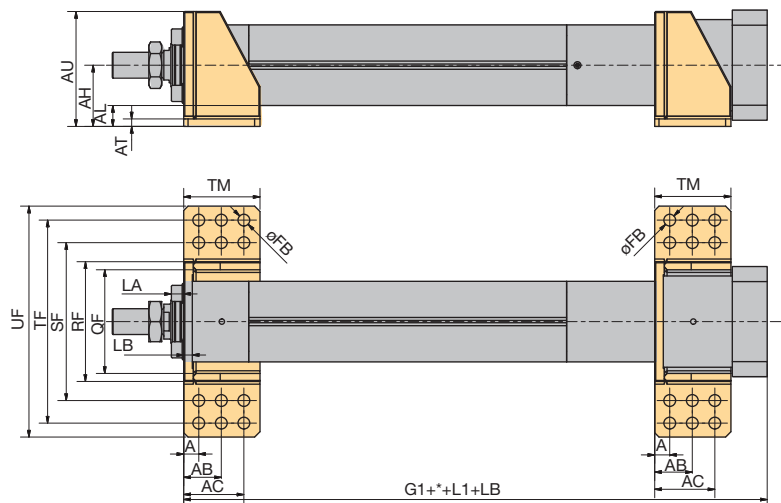
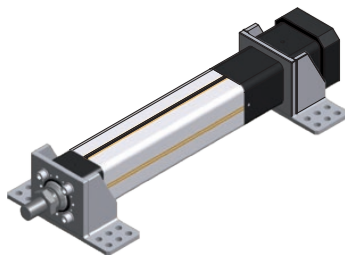


**ETH032-ETH080**  
Mounting Flanges



	Order no. (2 pieces)	TG	UF	ØFB	TM	MF	A	AB	TN	B	BB	BC
		[mm]										
<b>ETH032</b>	0112.917	62	78	6.6	25	8	12.5	-	25	-	-	-
<b>ETH050</b>	0122.917	84	104	9	30	10	15	-	30	-	-	-
<b>ETH080</b>	0132.917	120	144	13.5	40	12	20	-	40	-	-	-

### ETH100 & ETH125



	Order no.	AU	AH	AL	AT	UF	TF	SF	RF	QF	LA	LB	ØFB	TM	A	AB	AC	
		[mm]																
<b>ETH100</b>	- <sup>1)</sup>	164	94	34	14	290	-	246	200	170	19	13	17.5	99	16.5	49.5	81.5	
<b>ETH125</b>	- <sup>1)</sup>	214	114	39	14	430	378	294	223	193	23	16	22	142	28	70	112	

+\* = Measure + Length of desired stroke ("Dimensions" see page 22).

Listed in the order code of the cylinder; the order number applies only for ordering spare parts (of ETH032-ETH080 only). Spare parts delivery is including screws for cylinder mounting.

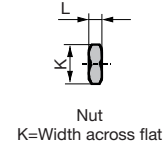
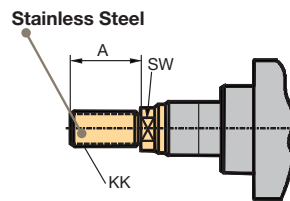
Stainless components only available for ETH032-ETH080.

<sup>1)</sup> Subsequent conversion can only be made in our factory.

\* For protection classes "B" and "C", we recommend GEOMET® coated screws (thin layer corrosion protection).

## Cylinder Rod Version

### External thread



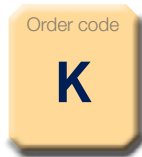
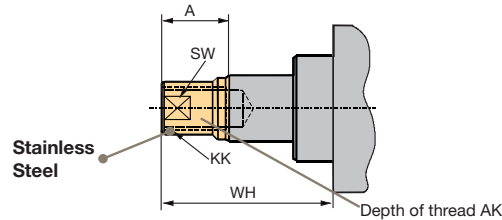
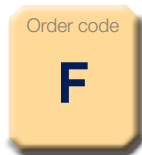
External Thread (upon delivery)				
	Weight	A	KK	SW <sup>1)</sup>
	[kg]	[mm]	[mm]	[mm]
<b>ETH032</b>	0.06	22	M10x1.25	10
<b>ETH050</b>	0.15	32	M16x1.5	17
<b>ETH080</b>	0.48	40	M20x1.5	22
<b>ETH100</b>	2.4	70	M42x2	46
<b>ETH125</b>	3.7	96	M48x2	55

<sup>1)</sup> SW: Width across flat (position of the flat is not fixed)

Nut				
	Weight	M	L	K <sup>1)</sup>
	[kg]	[mm]	[mm]	[mm]
<b>ETH032</b>	0.01	M10x1.25	5	17
<b>ETH050</b>	0.02	M16x1.5	8	24
<b>ETH080</b>	0.04	M20x1.5	10	30
<b>ETH100</b>	0.27	M42x2	16	65
<b>ETH125</b>	0.60	M48x2	24	75

<sup>1)</sup> K: Width across flat  
The nut is included in the delivery.

### Internal Thread

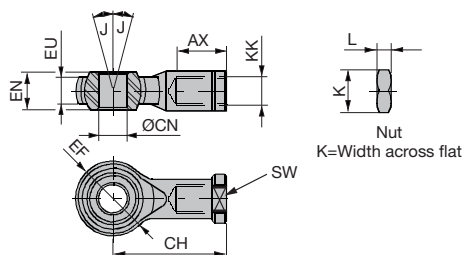


Internal Thread							
	Weight	A	KK (Option F)	KK (Option K)	AK	WH	SW <sup>1)</sup>
	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETH032</b>	0.04	14	M10x1.25		20	32	12
<b>ETH050</b>	0.14	24	M16x1.5		25	50	20
<b>ETH080</b>	0.42	29	M20x1.5		35	59	26
<b>ETH100</b>	2.2	60	M42x2	M45x3	50	92	60
<b>ETH125</b>	4.3	90	M48x2	M45x3	60	123	70

<sup>1)</sup> SW: Width across flat (position of the flat is not fixed)

## ETH - Electro Cylinder Cylinder Rod Version

### Spherical Rod Eye



	Order no.		Weight	KK	SW <sup>1)</sup>	ØCN	EN	EU	AX	CH	ØEF	J	K	L
	Standard	Stainless												
			[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[°]	[mm]	[mm]
<b>ETH032</b>	4078-10	P1S-4JRT	0.07	M10x1.25	17	10 H9	14	10.5	20	43	28	13	17	5
<b>ETH050</b>	4078-16	P1S-4MRT	0.23	M16x1.5	22	16 H9	21	15.0	28	64	42	15	24	8
<b>ETH080</b>	4078-20	P1S-4PRT	0.41	M20x1.5	32	20 H9	25	18.0	33	77	50	14	30	10
<b>ETH100</b>	0142.920-01	0142.920-02	2.8	M42x2	60	40 H7	49	7	60	142	90	16	65	15
<b>ETH125</b>	0152.920-01	not available	5.0	M48x2	65	50 H7	60	45	65	160	116	14	75	24

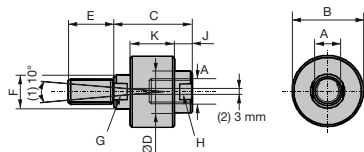
Listed in the order code of the cylinder; the order number applies only for ordering spare parts. Prerequisite is a cylinder rod with external thread.  
<sup>1)</sup> SW: Width across flat (position of the flat is not fixed)

### Alignment Coupler



#### For mounting at the extremity of the cylinder rod

- Balances misalignments
- Enlarges the mounting tolerance
- Simplifies the cylinder mounting
- Increases the service life of the cylinder guidings
- Compensates the offset between components and relieves the guiding from lateral force influences
- The traction/thrust force bearing capacity remains

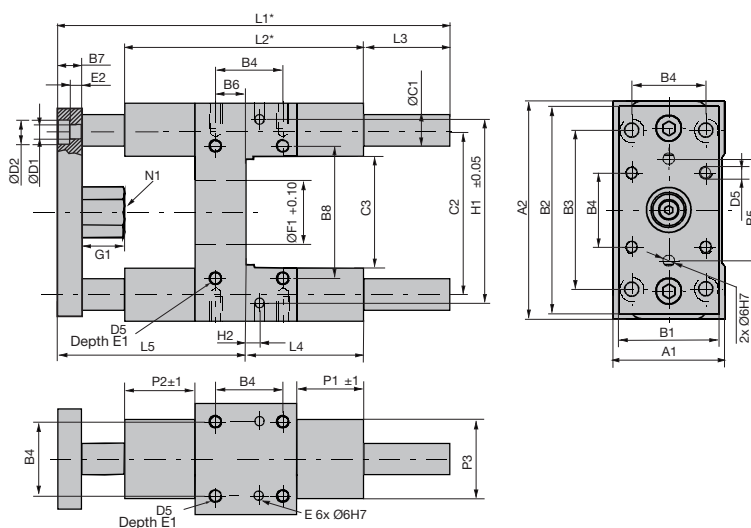
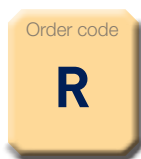


(1): Angle offset  
 (2): Radial offset  
 E: Hole dimension for depth

	Part No.	Weight	A	B	C	ØD	E	F	G	H	J	K
		[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETH032</b>	LC32-1010	0.26	M10x1.25	40	51	19	19	16	13	16	13	26
<b>ETH050</b>	LC50-1616	0.64	M16x1.5	54	59	32	29	25	22	29	14	33
<b>ETH080</b>	LC80-2020	1.30	M20x1.5	54	59	32	29	25	22	29	14	33
<b>ETH100</b>	- <sup>1)</sup>	4.5	M39x2 <sup>2)</sup>	101.6	111.1	57.2	57.2	44.5	38	49	22.2	69.9
<b>ETH125</b>	0152.921	9.0	M48x2	127	142.9	76.2	76.2	57.2	49.3	67	35	85.8

Listed in the order code of the cylinder; the order number applies only for ordering spare parts. Prerequisite is a cylinder rod with external thread.  
 Only available in protection option A (IP54 with galvanized screws).  
<sup>1)</sup> Subsequent conversion from rod end can only be made in our factory.  
<sup>2)</sup> Attention: Thread M39x2 differs from the standard (M42x2).

## Outrigger Bearing - Parallel Guiding



### Function of outrigger bearing:

- Additional stability and precision
- Anti-rotation device for higher torques
- Absorption of lateral forces

### Option R:

#### Outrigger bearing with ball bushings

(available only in protection class option A, "Order Code" see page 52)

- Main casting extruded aluminum
- 2 hardened steel guiding rods
- Linear ball bearings

When sizing the drive train of an ETH electro cylinder with outrigger bearing, increased friction losses must be taken into consideration

#### Note:

<sup>1)</sup> xxxx corresponds to the customized stroke. For information about this value please contact Parker.

<sup>2)</sup> The specified axial traction force on the front flange must not be exceeded

+\* = Measure + Length of desired stroke ("Dimensions" see page 22).

available for ETH032-ETH080.

For the ETH080, the standard pneumatic outrigger bearing modules cannot be used.

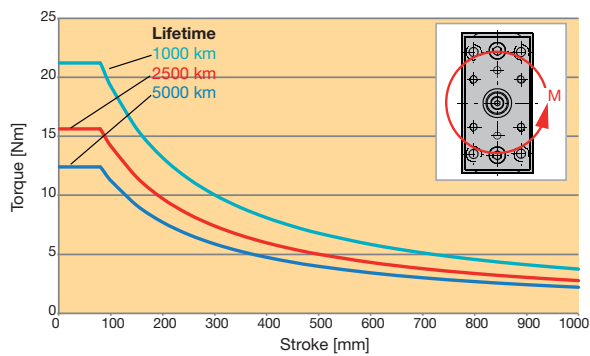
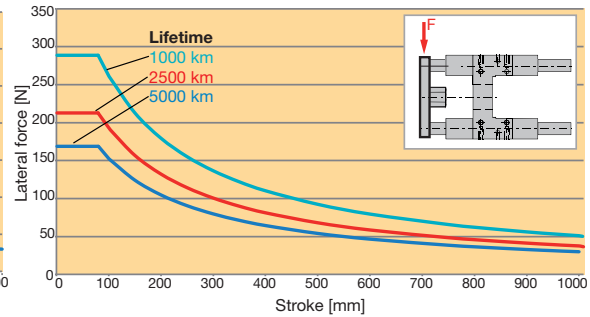
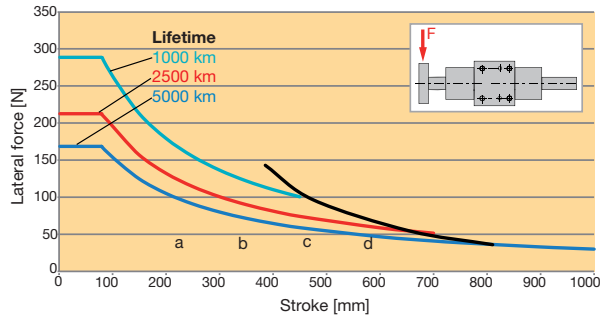
	Unit	ETH032	ETH050	ETH080
<b>Part-No. - Option R <sup>1)</sup></b>		0112.040-xxxx	0122.040-xxxx	0132.040-xxxx
<b>Max. permitted axial traction force <sup>2)</sup></b>	[N]	3700	8000	9500
<b>A1</b>	[mm]	50	70	105
<b>A2</b>	[mm]	97	137	189
<b>B1</b>	[mm]	45	63	100
<b>B2</b>	[mm]	90	130	180
<b>B3</b>	[mm]	78	100	130
<b>B4</b>	[mm]	32.5	46.5	72
<b>B5</b>	[mm]	50	72	106
<b>B6</b>	[mm]	4	19	21
<b>B7</b>	[mm]	12	15	20
<b>B8</b>	[mm]	61	85	130
<b>ØC1</b>	[mm]	12	20	25
<b>C2</b>	[mm]	73.5	103.5	147
<b>C3</b>	[mm]	50	70	105
<b>ØD1</b>	[mm]	6.6	9	11
<b>ØD2</b>	[mm]	11	14	17
<b>D5</b>	[mm]	M6	M8	M10
<b>E (Depth)</b>	[mm]	10	10	10
<b>E1 (Depth)</b>	[mm]	12	16	20
<b>E2 (Depth)</b>	[mm]	7	9	11
<b>ØF1</b>	[mm]	30	40	60
<b>G1</b>	[mm]	17	27	32
<b>H1</b>	[mm]	81	119	166
<b>H2</b>	[mm]	11.7	4.2	15
<b>L1+*</b>	[mm]	150	192	247
<b>L2</b>	[mm]	120	150	200
<b>L3+*</b>	[mm]	15	24	24
<b>L4</b>	[mm]	71	79	113
<b>L5</b>	[mm]	64	89	110
<b>N1</b>	[mm]	17	24	30
<b>P1</b>	[mm]	36	42	50
<b>P2</b>	[mm]	31	44	52
<b>P3</b>	[mm]	40	50	70
<b>Total mass with zero stroke</b>	[kg]	0.97	2.56	6.53
<b>Moving mass zero stroke</b>	[kg]	0.60	1.84	4.36
<b>Additional mass</b>	[kg/m]	1.78	4.93	7.71

ETH - Electro Cylinder  
Cylinder Rod Version

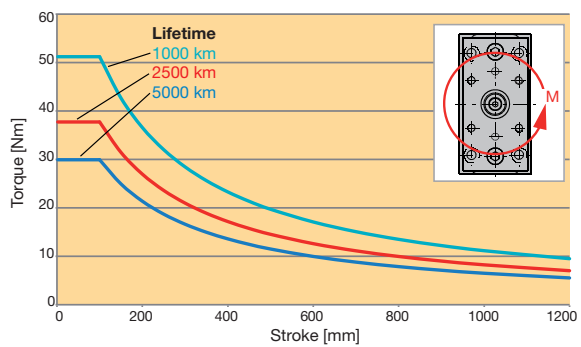
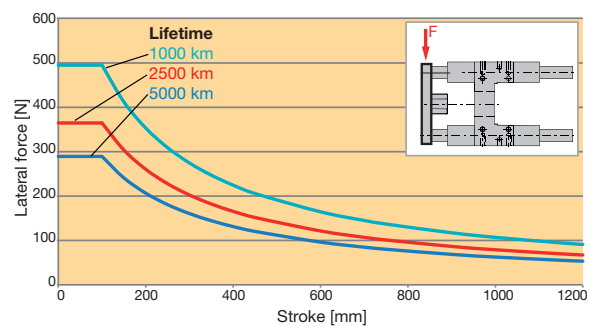
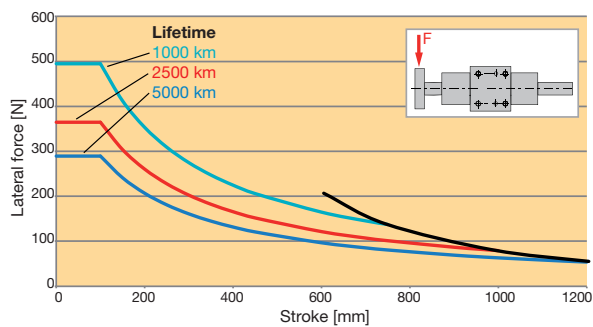
Permitted load / lifetime

Outrigger bearing with ball bushings (Option R)

ETH032



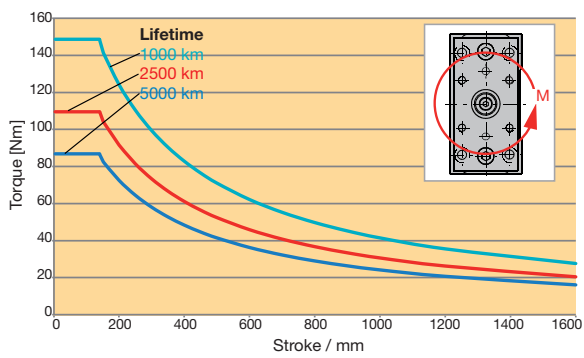
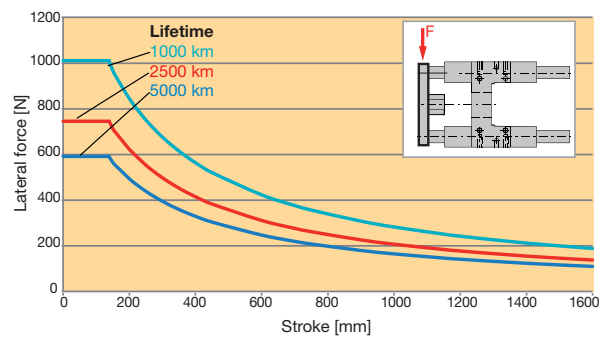
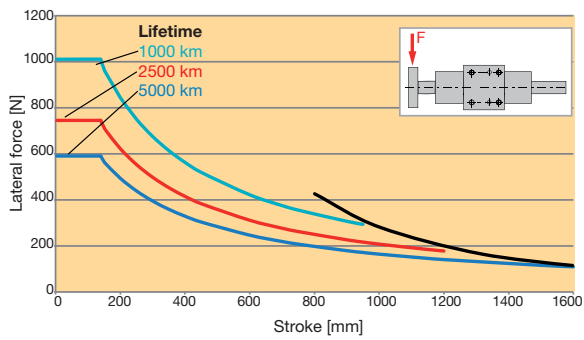
ETH050



The diagrams apply for a medium travel speed of 0.5 m/s, an ambient temperature of 20 °C.

**Outrigger bearing with ball bushings (Option R)**

**ETH080**



The diagrams apply for a medium travel speed of 0.5 m/s, an ambient temperature of 20 °C.

## Accessories

### Force sensors - Spherical rod eye with integrated force sensor

Swivel heads are important construction components with respect to rotary, pivoting and tilting movements. Force measurements are more and more frequently required in applications.

The force transducers are suitable for direct mounting on the cylinder rod.

They can, for example, be used to measure contact forces or overloads. Thanks to the thin film technology, the swivel head force transducers are very robust and reliable. An integrated amplifier emits an output signal of 4...20 mA.

The sensors correspond to the EN 61326 standard for electromagnetic compatibility (EMC) and are sized to pick up traction/thrust forces.



#### Features

- Measuring range:  
Traction/thrust forces up to  $\pm 114$  kN
- Thin film implants (instead of conventional bonded foil strain gauges)
- Corrosion resistant stainless steel version
- Integrated amplifier
- Small temperature drift
- Long term stability
- High shock and vibration resistance
- For dynamic or static measurements
- Good repeatability
- Simple mounting
- Also available in ATEX design <sup>1) 2)</sup>. Authorized for gas atmospheres zone 1 and zone 2.

II 2G Ex ib IIC T4

Connection of the force sensors to Compax3 with Option M21 is possible.

#### Technical Features

	Unit	Spherical rod eye with integrated force sensor							With External Thread						
		ETH032			ETH050			ETH080	ETH100		ETH125				
		M05	M10	M16	M05	M10	M20	M05	M10	M10/M20	M10	M20			
Material	-	Stainless steel													
Protection class	-	IP67													
Ambient temperature	[°C]	-20 to +80													
Measuring range	[kN]	±3.7	±3.7	±2.4	±9.3	±7.0	±4.4	±17.8	±25.1	±56.0	±88.7	±114.0			
Linearity deviation of m.v.	[N]	±20			±68			±44	±90		±2000				
Part N° (standard option).	-	0111.916		0111.917	0121.916		0121.917	0121.918	0131.916		0131.917	0141.916		0141.917	0141.918
Part N° (ATEX option <sup>1) 2)</sup>	-	0111.946		n.a.	0121.946		0121.947	n.a.	0131.946		0131.947	n.a.		n.a.	n.a.

For ETH032-ETH080: Only possible with cylinder rod end "M" (external thread).

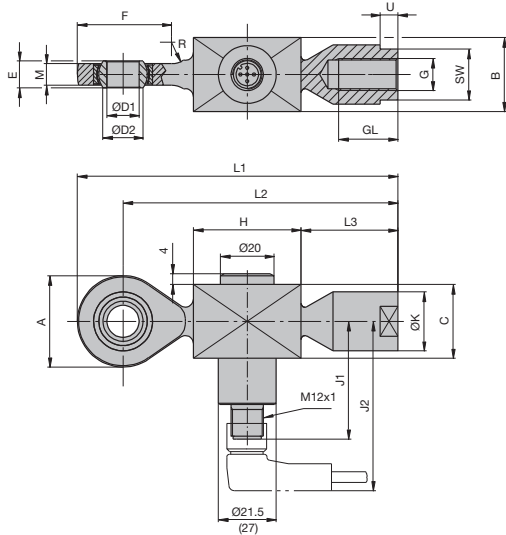
For ETH100, ETH125: Only possible with cylinder rod end "K".

A subsequent conversion from another rod end to M or K is generally **NOT** possible.

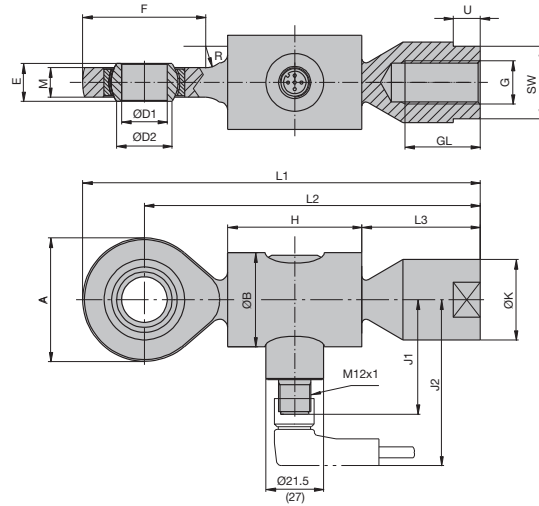
<sup>1)</sup> The ATEX approval of the force sensors is only met, if the sensor is operating with an ATEX authorized isolated switch amplifiers and an ATEX authorized cable.

<sup>2)</sup> Please refer to the installation and operating instructions in the supplied operating manual.

Version for ETH032



Version for ETH050 & ETH080



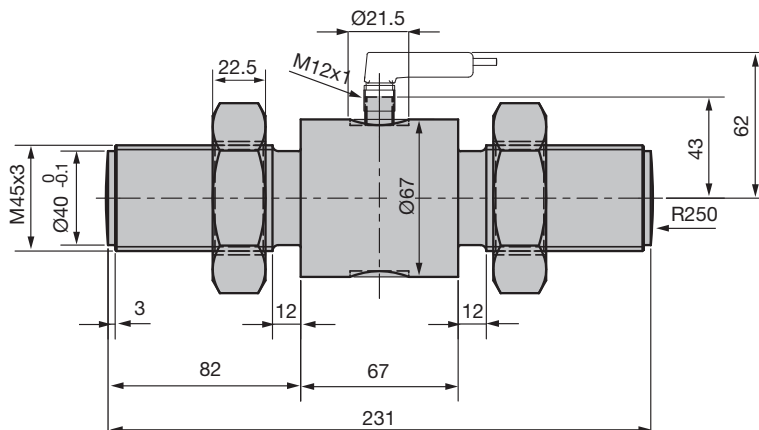
Dimensions [mm]

Dimensions - Non ATEX design (ATEX design)

	A	B	ØB	C	ØD1	ØD2 0.008	E	F	G	GL	H	J1	J2	ØK	L1	L2	L3	M	SW <sup>1)</sup>	U
for ETH032	34	27	-	27	12	15	10	35	M10x1.25	21	40	44 (70)	63 (89)	22	119	102	36	8	19	8
for ETH050	46	-	35	-	17	20.7	14	46	M16x1.5	28	50	44 (70)	63 (89)	30	148	125	44	11	27	12
for ETH080	53	-	54	-	20	24.2	16	54	M20x1.5	33	54	44 (78)	63 (97)	35	171	144.5	54	13	32	13

<sup>1)</sup> SW: Width across flat

Version for ETH100 & ETH125

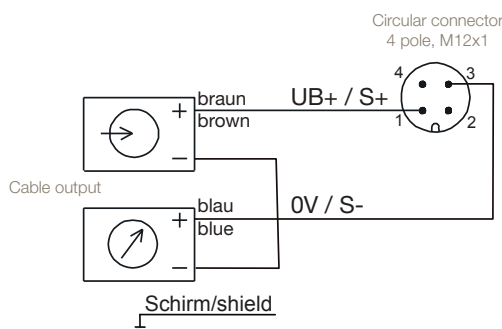
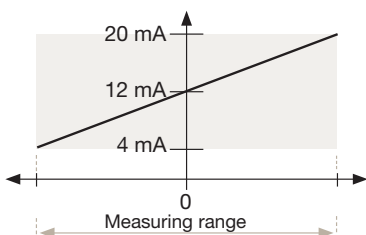


Dimensions [mm]

## ETH - Electro Cylinder Accessories

### Electrical connection

Power supply  $U_B = 10 \dots 30$  VDC  
Analog output 4...20 mA (two-wire technology)

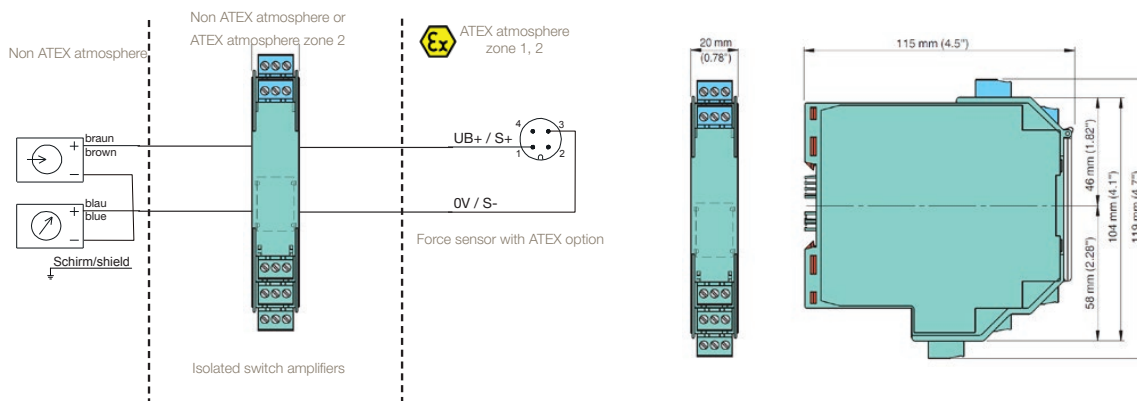


### ATEX option

Technical data, isolated switch amplifiers <sup>1)2)</sup>

<b>Part No.</b>	KFD2-STC4-Ex1
<b>Technical Characteristics</b>	"1-channel (Operation of 1 force sensor maximum), transmits the analogue measurement sign to the Non-EX-zone"
<b>ATEX Classification</b>	"II (1)GD [Ex ia] IIC [electrical circuit(s) in zone 0/1/2] II 3G EEx nA II T4 [device/installation site in zone 2]" The device is approved for safe circuits up to Ex-zone 0 (gas). Suitable for installation in zone 2
<b>Supply voltage</b>	20 ... 35 V DC
<b>Power consumption</b>	1,9 W
<b>Analog output</b>	0/4 ... 20 mA
<b>Ambient temperature</b>	-20°C ... +60°C
<b>Protection class</b>	IP20

### Dimensions, isolated switch amplifiers



Part No.	Cable for force sensor
080-900446	Force sensor cable (PUR), straight connector, M12 with flying leads, 2 m
080-900447	Force sensor cable (PUR), straight connector, M12 with flying leads, 5 m
080-900456	Force sensor cable (PUR), angle connector, M12 with flying leads, 2 m
080-900457	Force sensor cable (PUR), angle connector, M12 with flying leads, 5 m
Part No.	Cable for force sensor with ATEX design
080-900464	Force sensor cable ATEX, straight plug, M12 flying leads, 5 m
080-900465	Force sensor cable ATEX, angle plug, M12 flying leads, 5 m

<sup>1)</sup> The ATEX approval of the force sensors is only met if the sensor is operating with an ATEX authorized isolated switch amplifiers and an ATEX authorized cable.

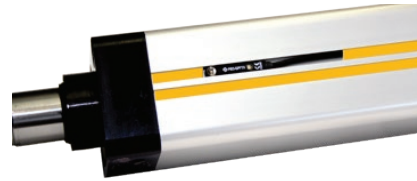
<sup>2)</sup> Please refer to the installation and operating instructions in the supplied manual.

## Initiators / Limit Switches

### Sensors for non-explosive atmospheres

The position sensors can be mounted in the longitudinal grooves of the cylinder body and are flush to the body; eliminating protruding edges. The initiator cable is hidden under the yellow cover. The permanent

magnet integrated into the screw nut actuates the initiators. Fitting sensors are available as optional accessories.

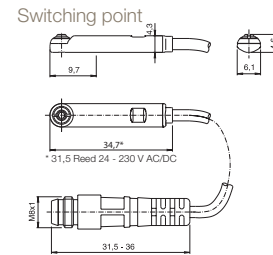


ETH032, ETH050 2 grooves each on 2 opposite sides.  
ETH080, ETH100 2 grooves each on all sides.

The following initiator types are available for the ETH cylinder series:



Info: Only use PNP types for ETH with Compax3.



### Magnetic cylinder sensors

Dimensions [mm]

Type	Function	LED	Logic	Cable	Continuous current	Current consumption	Supply voltage	Switching frequency	compatible with Compax3, SLVD-N, TPD-M
P8S-GPFLX	N.O.	yes	PNP	3 m	max. 100 mA	max. 10 mA	10-30 VDC	1 kHz	yes
P8S-GNFLX			NPN						No
P8S-GPSHX			PNP	0.3 m cable with M8 connector					yes
P8S-GNSHX			NPN						No
P8S-GQFLX	N.C.	yes	PNP	3 m	max. 100 mA	max. 10 mA	10-30 VDC	1 kHz	yes
P8S-GMFAX			NPN						No
P8S-GQSHX			PNP	0.3 m cable with M8 connector					yes
P8S-GMSHX			NPN						No

## ETH - Electro Cylinder Accessories

### Sensors for explosive atmospheres (ATEX) <sup>1)</sup>


In explosive atmospheres ATEX approved sensors must be used exclusively.

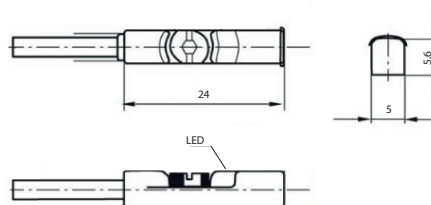
Parker magnetic cylinder sensors are rated as intrinsically safe electrical equipment. They must be used with isolated switch amplifiers with

certificates of conformity for explosive atmospheres.

These sensors are not completely flush with the profile: the initiators protrude by about 1 mm.


#### Technical data

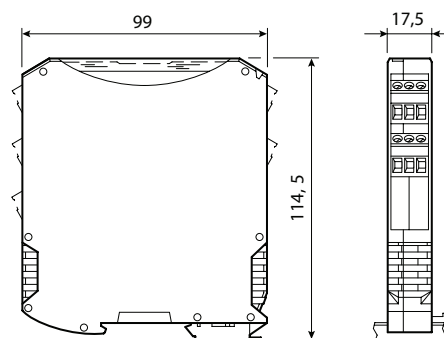
Order code	MZT8-2V8-N-KWB
ATEX Classification	 "II 1G Ex ia IIC T4 II 1D Ex ia IIIC T135°C Da"
	Authorized for the operation in ATEX atmosphere Zones 0, 1 and 2.
Supply voltage	max. 20 V
Short-circuit current	max. 60 mA
Output	max. 100 mA
Effective internal inductance	max. 30 µH
Effective internal capacitance	max. 130 nF
Ambient temperature	-25°C ... +80°C
Protection class	IP67
Cable	5 m
LED	yes



Dimensions [mm]

#### Technical data - Isolated switch amplifiers

Order code	EN2-2EX1
Technical Characteristics	2-channel (operating with max 2 limit switches possible), Exchange-relay (NO / NC-behavior), Line fault detection
ATEX Classification	 "II (1)G [Ex ia Ga] IIC II (1)D [Ex ia Da] IIIC II 3(1)G Ex nA nC [ia Ga] IIC t4 Gc X"
	The device is approved for intrinsically safe (Ex i) circuits up to Ex zone 0 (gas) and Ex zone 20 (dust).
Supply voltage	24 V DC ... 230 V AC/DC
Current consumption	"42 mA (24V DC), < 80 mA (230 V AC/DC)"
Max. voltage OUTPUT	9,6 V
Max. current OUTPUT	10,3 mA
Max. power OUTPUT	25 mW
Non-load voltage	8 VDC +/-10%
Switching points	"> 2,1 mA (conducting) < 1,2 mA (blocking)"
Max. switching frequency	20 Hz
Ambient temperature	-20°C ... +60°C
Protection class	IP20



Dimensions [mm]

<sup>1)</sup> Please refer to the installation and operating instructions in the supplied manual.

# Drive Train Selection <sup>1)</sup>

## Example for Sizing with Predefined Drive Trains

In order to simplify the dimensioning process for a complete drive train, We have prepared an overview of predefined electro cylinders, gearboxes, motors and servo drives, which can be found on the following pages.

With a few parameters, you can directly find the order code for the required components.

Note the boundary conditions!

### The following application parameters are required:

- The equivalent axial force.  
(Calculation page 13 formula 3 with the forces determined as described on page 11).
- The maximum speed.



### Working with the drive train table

- Select the drive trains providing the required axial force (e.g. by drawing a vertical line).
- Then select from this choice the drive trains, that are able to travel at the required speed (e.g. by drawing a second vertical line).
- The suitable drive train can then be selected from the remaining choice, if necessary by comparing additional characteristics.

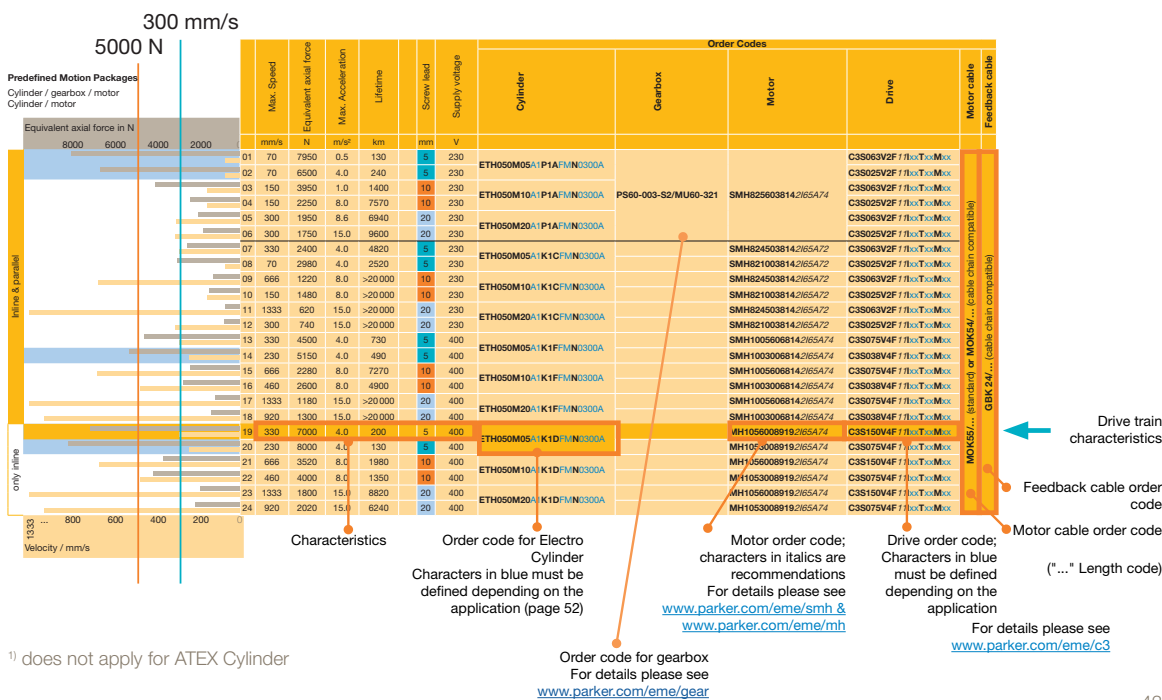
Please check if all given characteristics (such as max. acceleration, supply voltage etc.) are suitable for your application.

### Example:

Required data

Equivalent axial force: 5000 N

Speed: 300 mm/s



ETH - Electro Cylinder  
Predefined Motion Packages for ETH032

## Predefined Motion Packages ETH032 <sup>1)</sup>

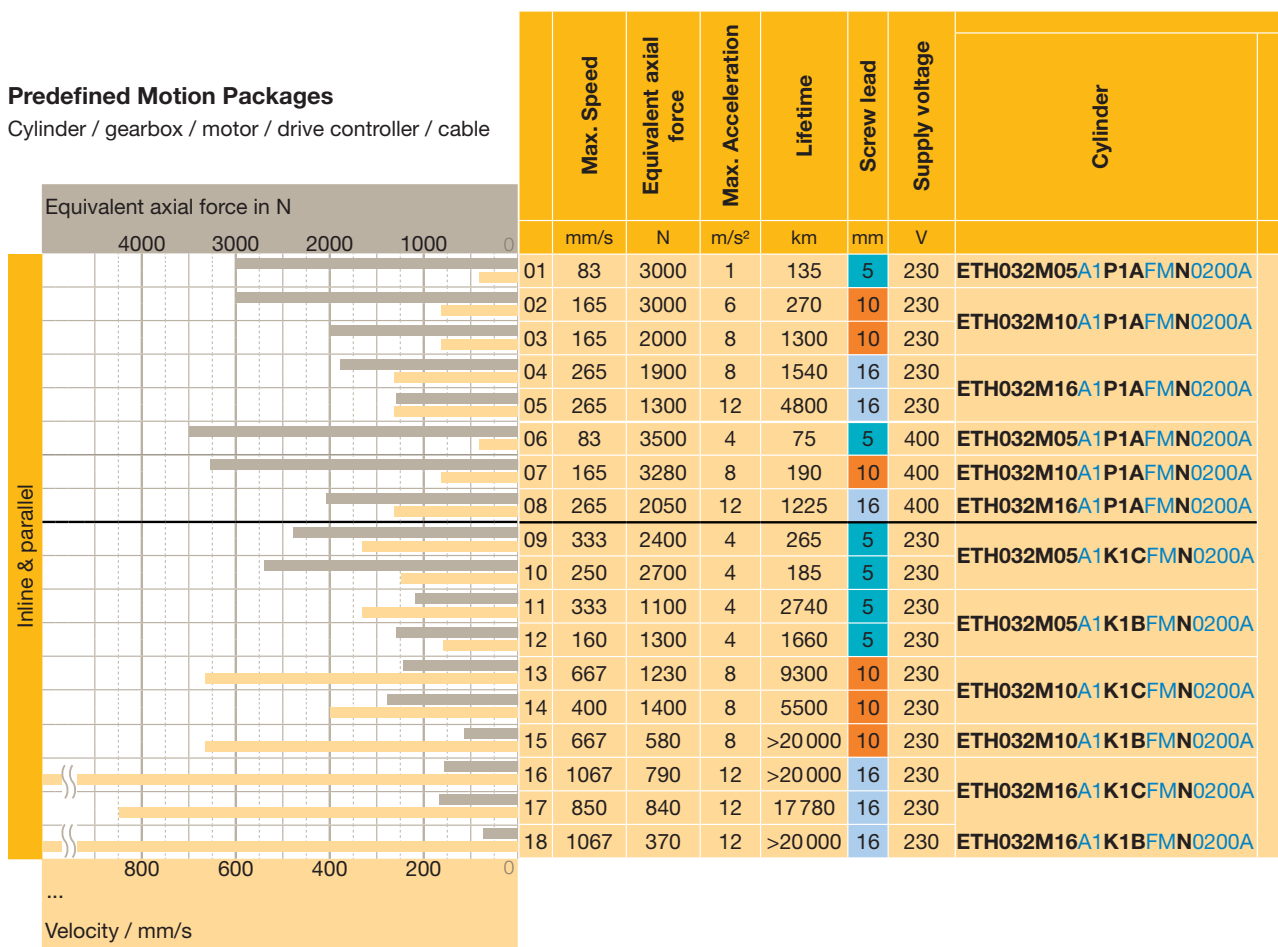
### with Compax3, PSD1

In order to simplify the representation, we assumed boundary conditions which must be adhered to without exception in your application, otherwise the product combinations suggested here might not work. In this case, the application must be dimensioned conventionally.

<sup>1)</sup> does not apply for ATEX Cylinder

### Predefined Motion Packages

Cylinder / gearbox / motor / drive controller / cable



#### Basic Application Assumptions:

- Stroke from 50 to 400 mm
- Horizontal movement
- The characteristics of the individual components are not to be exceeded
  - with parallel motor: respect transmissible torque depending on the motor speed n
  - permissible axial thrust forces must be respected
  - Ambient conditions
  - ...
- Linear acceleration
- Maximum acceleration given = deceleration times
- Application factor = 1.0
- The calculation is based on the assumption: without standstill time (i.e. if there are standstill times in the application, only the power reserve is increased)
- 40 °C ambient temperature, with gearbox 20 °C ambient temperature
- up to 1000 m above sea level

Order Codes						
Gearbox	Motor	Drive Compax3	Motor Cable	Feedback cable	Drive PSD1	Cable
	xx : choose the right feedback depending of the application and drive used					
PE3-003-10M060/075/11/23	SMH60601,45112165xx4	C3S025V2F 11lxxTxxMxx			PSD1SW1200...	CBM....
PE3-003-10M080/100/14/30	SMH8260038142165xx4	C3S025V2F 11lxxTxxMxx			PSD1SW1200...	
PE3-003-10M060/075/11/23	SMH60601,45112165xx4	C3S015V4F 11lxxTxxMxx			PSD1MW1200....	
PE3-003-10M080/100/14/30	SMH8260038142165xx4	C3S038V4F 11lxxTxxMxx			PSD1MW1300...	
without gearbox	SMH8245038142165xx2	C3S063V2F 11lxxTxxMxx	MOK55/... (standard) or MOK54/... (cable chain compatible)	GBK 24/... (cable chain compatible)	PSD1SW1300...	
	SMH8260038142165xx4	C3S025V2F 11lxxTxxMxx			PSD1SW1200...	
	SMH60451,45112165xx2	C3S025V2F 11lxxTxxMxx			PSD1SW1300...	
	SMH60601,45112165xx4	C3S063V2F 11lxxTxxMxx			PSD1SW1200...	
	SMH8245038142165xx2	C3S063V2F 11lxxTxxMxx			PSD1SW1300...	
	SMH8260038142165xx4	C3S025V2F 11lxxTxxMxx			PSD1SW1200...	
	SMH60451,45112165xx2	C3S063V2F 11lxxTxxMxx			PSD1SW1300...	
	SMH8260038142165xx4	C3S025V2F 11lxxTxxMxx			PSD1SW1200...	

Order codes:

**bold:** mandatory so that the package is combinable

*italics:* recommended/standard

**blue:** must be selected depending on the application

Hint: The examples shown here are meant to help with the dimensioning process. As many parameters interact in this kind of drive package, the examples make no claim to be complete.

ETH - Electro Cylinder  
Predefined Motion Packages for ETH050

## Predefined Motion Packages ETH050 <sup>1)</sup>

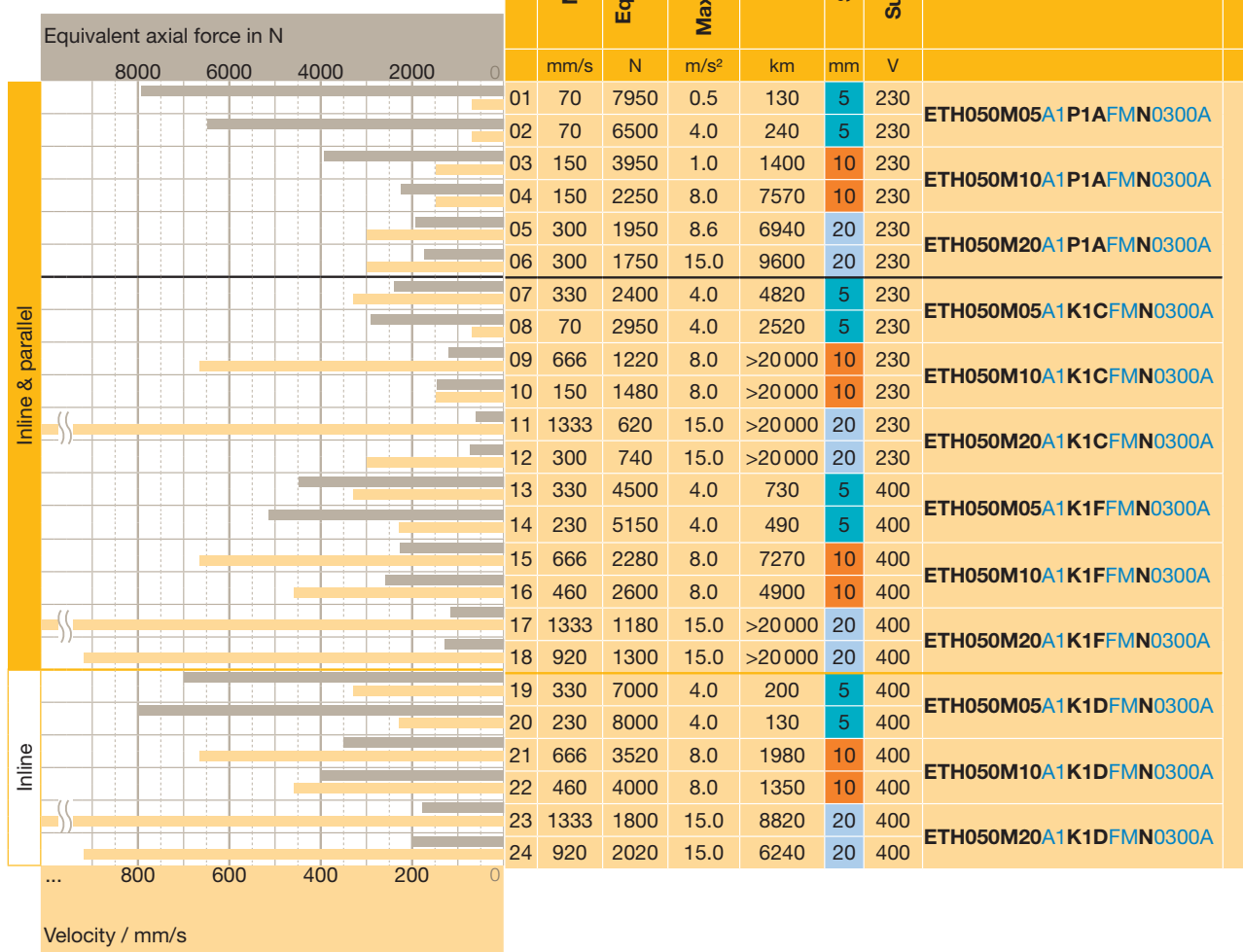
### with Compax3, PSD1

In order to simplify the representation, we assumed boundary conditions which must be adhered to without exception in your application, otherwise the product combinations suggested here might not work. In this case, the application must be dimensioned conventionally.

<sup>1)</sup> does not apply for ATEX Cylinder

### Predefined Motion Packages

Cylinder / gearbox / motor / drive controller / cable



#### Basic Application Assumptions:

- Stroke from 50 to 600 mm
- Horizontal movement
- The characteristics of the individual components are not to be exceeded
  - with parallel motor: respect transmissible torque depending on the motor speed n
  - permissible axial thrust forces must be respected
- Ambient conditions
- ...
- Linear acceleration
- Maximum acceleration given = deceleration times
- Application factor = 1.0
- The calculation is based on the assumption: without standstill time (i.e. if there are standstill times in the application, only the power reserve is increased)
- 40 °C ambient temperature, with gearbox 20 °C ambient temperature
- up to 1000 m above sea level

Order Codes						
Gearbox	Motor	Drive Compax3	Motor Cable Feedback cable	Drive PSD1M	Cable	
PE3-003-10M080/100/14/30	SMH8256038142165xx4	C3S063V2F 11lxxTxxMxx	MOK55/... (standard) or MOK54/... (cable chain compatible) GBK 24/... (cable chain compatible)	PSD1SW1300...	CBM...	
		C3S025V2F 11lxxTxxMxx		PSD1SW1200...		
		C3S063V2F 11lxxTxxMxx		PSD1SW1300...		
		C3S025V2F 11lxxTxxMxx		PSD1SW1200...		
		C3S063V2F 11lxxTxxMxx		PSD1SW1300...		
		C3S025V2F 11lxxTxxMxx		PSD1SW1200...		
without gearbox	SMH8245038142165xx2	C3S063V2F 11lxxTxxMxx		PSD1SW1300...		
	SMH8210038142165xx2	C3S025V2F 11lxxTxxMxx		PSD1SW1200...		
	SMH8245038142165xx2	C3S063V2F 11lxxTxxMxx		PSD1SW1300...		
	SMH8210038142165xx2	C3S025V2F 11lxxTxxMxx		PSD1SW1200...		
	SMH8245038142165xx2	C3S063V2F 11lxxTxxMxx		PSD1SW1300...		
	SMH8210038142165xx2	C3S025V2F 11lxxTxxMxx		PSD1SW1200...		
	SMH10056065ET 2165xx4	C3S075V4F 11lxxTxxMxx	PSD1MW1300...			
	SMH10030065ET 2165xx4	C3S038V4F 11lxxTxxMxx	PSD1MW1300...			
	SMH10056065ET 2165xx4	C3S075V4F 11lxxTxxMxx	PSD1MW1300...			
	SMH10030065ET 2165xx4	C3S038V4F 11lxxTxxMxx	PSD1MW1300...			
	SMH10056065ET 2165xx4	C3S075V4F 11lxxTxxMxx	PSD1MW1300...			
	SMH10030065ET 2165xx4	C3S038V4F 11lxxTxxMxx	PSD1MW1300...			
without gearbox	MH10560089192165xx4	C3S150V4F 11lxxTxxMxx	PSD1MW1600...			
	MH10530089192165xx4	C3S075V4F 11lxxTxxMxx	PSD1MW1300...			
	MH10560089192165xx4	C3S150V4F 11lxxTxxMxx	PSD1MW1600...			
	MH10530089192165xx4	C3S075V4F 11lxxTxxMxx	PSD1MW1300...			
	MH10560089192165xx4	C3S150V4F 11lxxTxxMxx	PSD1MW1600...			
	MH10530089192165xx4	C3S075V4F 11lxxTxxMxx	PSD1MW1300...			

Order codes:

**bold:** mandatory so that the package is combinable

*italics:* recommended/standard

**blue:** must be selected depending on the application

Hint: The examples shown here are meant to help with the dimensioning process. As many parameters interact in this kind of drive package, the examples make no claim to be complete.

ETH - Electro Cylinder  
Predefined Motion Packages for ETH080

## Predefined Motion Packages ETH080 <sup>1)</sup>

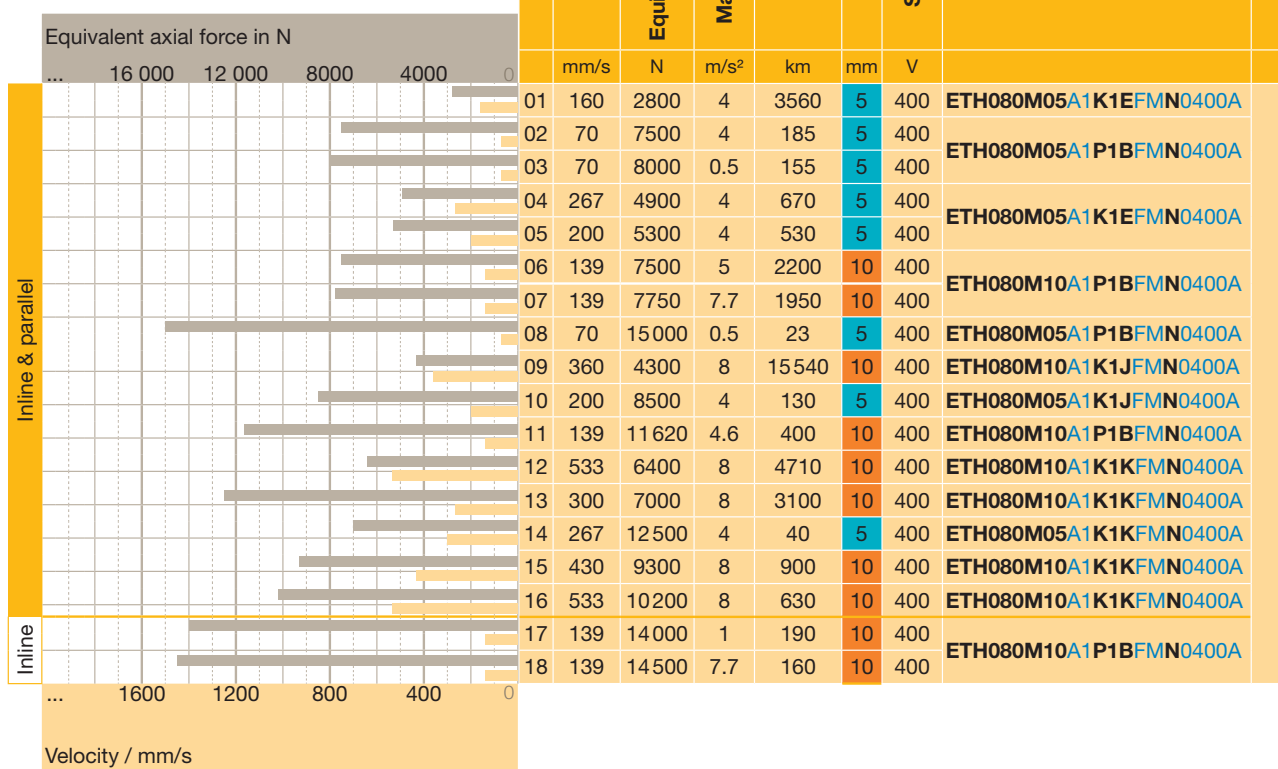
### with Compax3, PSD1

In order to simplify the representation, we assumed boundary conditions which must be adhered to without exception in your application, otherwise the product combinations suggested here might not work. In this case, the application must be dimensioned conventionally.

<sup>1)</sup> does not apply for ATEX Cylinder

### Predefined Motion Packages

Cylinder / gearbox / motor / drive controller / cable



#### Basic Application Assumptions:

- Stroke from 50 to 800 mm
- Horizontal movement
- The characteristics of the individual components are not to be exceeded
  - with parallel motor: respect transmissible torque depending on the motor speed n
  - permissible axial thrust forces must be respected
  - Ambient conditions
  - ...
- Linear acceleration
- Maximum acceleration given = deceleration times
- Application factor = 1.0
- The calculation is based on the assumption: without standstill time (i.e. if there are standstill times in the application, only the power reserve is increased)
- 40 °C ambient temperature, with gearbox  
20 °C ambient temperature
- up to 1000 m above sea level

Order Codes						
Gearbox	Motor	Drive Compax3	Motor Cable	Feedback cable	Drive PSD1M	Cable
without gearbox	SMH8230035192165xx4	C3S038V4F 11lxTxxMxx			PSD1MW1300...	CBM...
PE4-003-10M080/100/19/40	SMH8256038192165xx4	C3S038V4F 11lxTxxMxx			PSD1MW1300...	
	SMH8230038192165xx4	C3S038V4F 11lxTxxMxx			PSD1MW1200...	
without gearbox	SMH10056065192165xx4	C3S075V4F 11lxTxxMxx			PSD1MW1400...	
	SMH10030065192165xx4	C3S038V4F 11lxTxxMxx			PSD1MW1300...	
PE4-003-10M095/115/19/40	SMH10030065192165xx4	C3S038V4F 11lxTxxMxx	①	GBK 24/... (cable chain compatible)	PSD1MW1300...	
	SMH10056065192165xx4	C3S075V4F 11lxTxxMxx			PSD1MW1400...	
	SMH10030065192165xx4	C3S038V4F 11lxTxxMxx			PSD1MW1300...	
without gearbox	SMH11530107242165xx4	C3S075V4F 11lxTxxMxx			PSD1MW1400...	
	SMH11530108192165xx4	C3S075V4F 11lxTxxMxx			PSD1MW1400...	
PE4-003-10M095/130/19/40	SMH14256155242165xx4	C3S150V4F 11lxTxxMxx			PSD1MW1600...	
	SMH14230155242165xx4	C3S150V4F 11lxTxxMxx			PSD1MW1600...	
without gearbox	SMH14256155242165xx4	C3S150V4F 11lxTxxMxx			PSD1MW1600...	
	MH14530225242165xx4	C3S150V4F 11lxTxxMxx			PSD1MW1600...	
	MH14545285243165xx4	C3S300V4F 11lxTxxMxx			PSD1MW1800...	
PE4-003-10M095/130/19/40	SMH11530108192165xx4	C3S075V4F 11lxTxxMxx	②	PSD1MW1400...		
	SMH11556108192165xx4	C3S150V4F 11lxTxxMxx		PSD1MW1600...		

- ① MOK55/... (standard) or MOK54/... (cable chain compatible)
- ② MOK56/... (standard) or MOK57/... (cable chain compatible)
- ③ MOK59/... (standard) or MOK64/... (cable chain compatible)

Order codes:

**bold:** mandatory so that the package is combinable

*italics:* recommended/standard

**blue:** must be selected depending on the application

Hint: The examples shown here are meant to help with the dimensioning process. As many parameters interact in this kind of drive package, the examples make no claim to be complete.

ETH - Electro Cylinder  
Predefined Motion Packages for ETH100

## Predefined Motion Packages ETH100, ETH125 <sup>1)</sup>

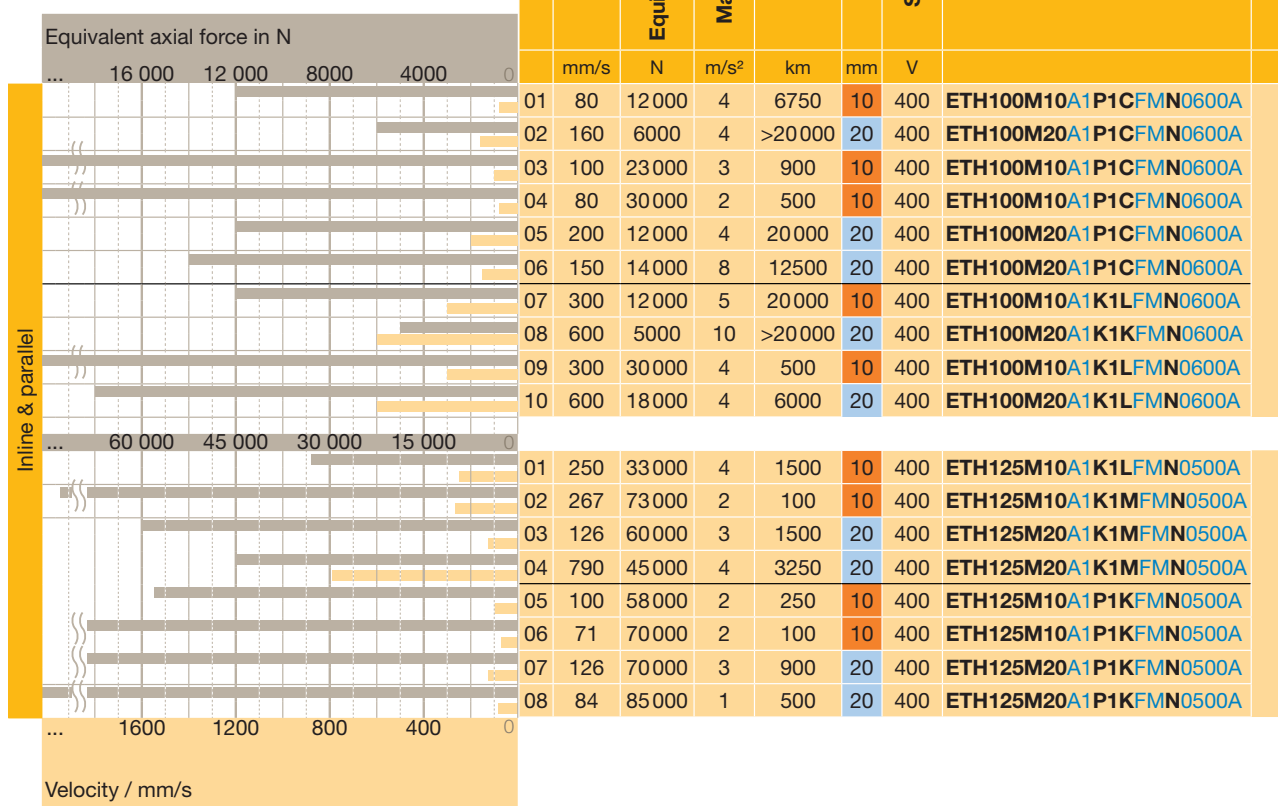
### with Compax3, PSD1

In order to simplify the representation, we assumed boundary conditions which must be adhered to without exception in your application, otherwise the product combinations suggested here might not work. In this case, the application must be dimensioned conventionally.

<sup>1)</sup> does not apply for ATEX Cylinder

### Predefined Motion Packages

Cylinder / gearbox / motor / drive controller / cable



#### Basic Application Assumptions:

- Stroke from 100 to 600 mm
- Horizontal movement
- The characteristics of the individual components are not to be exceeded
  - with parallel motor: respect transmissible torque depending on the motor speed n
  - permissible axial thrust forces must be respected
- Ambient conditions
- ...
- Linear acceleration
- Maximum acceleration given = deceleration times
- Application factor = 1.0
- The calculation is based on the assumption: without standstill time (i.e. if there are standstill times in the application, only the power reserve is increased)
- 40 °C ambient temperature, with gearbox  
20 °C ambient temperature
- up to 1000 m above sea level

Order Codes						
Gearbox	Motor	Drive Compax3	Motor Cable	Feedback cable	Drive PSD1M	Cable
PE5-005-10M095/115/24/50	SMH10056065242/65xx4	C3S075V4F11IxxTxxMxx	①	⑥	PSD1MW1400...	CBM
PE5-005-10M095/115/24/50	SMH10030065242/65xx4	C3S038V4F11IxxTxxMxx	①		PSD1MW1300...	
PE5-004-10M130/185/24/50	SMH14230155242/65xx4	C3S150V4F11IxxTxxMxx	②		PSD1MW1600...	
PE5-005-10M130/185/24/50	SMH14230155242/65xx4	C3S150V4F11IxxTxxMxx	②		PSD1MW1600...	
PE5-004-10M130/185/24/50	SMH14230155242/65xx4	C3S150V4F11IxxTxxMxx	②		PSD1MW1600...	
PE5-005-10M130/185/24/50	SMH14230155242/65xx4	C3S150V4F11IxxTxxMxx	②		PSD1MW1600...	
without gearbox	SMH17030355382/65xx4	C3S150V4F11IxxTxxMxx	②		PSD1MW1600...	
	MH14545285242/65xx4	C3S300V4F11IxxTxxMxx	③		PSD1MW1800...	
	MH20530905382/65xx4	C3H050V4F11IxxTxxMxx	④		--	
	MH20530905382/65xx4	C3H050V4F11IxxTxxMxx	④		--	
without gearbox	MH20530705383/65xx4	C3H090V4F11IxxTxxMxx	⑤	⑥	--	
	MH265301505483/65xx4	C3H090V4F10IxxTxxMxx	⑤	⑦	--	
	MH265302205483/65xx4	C3H125V4F10IxxTxxMxx	⑤	⑦	--	
	MH265302205483/65xx4	C3H125V4F10IxxTxxMxx	⑤	⑦	--	
PE7-004-10M180/215/38/80	MH20530285383/65xx4	C3S300V4F11IxxTxxMxx	④	⑥	--	
PE7-005-10M180/215/38/80	MH20530285383/65xx4	C3S300V4F11IxxTxxMxx	④	⑥	--	
PE7-004-10M180/215/38/80	MH20530705383/65xx4	C3H050V4F11IxxTxxMxx	⑤	⑥	--	
PE7-005-10M180/215/38/80	MH20530705383/65xx4	C3H050V4F11IxxTxxMxx	⑤	⑥	--	

- ① MOK55/... (standard) or MOK54/... (cable chain compatible)
- ② MOK56/... (standard) or MOK57/... (cable chain compatible)
- ③ MOK59/... (standard) or MOK64/... (cable chain compatible)
- ④ MOK61/...,
- ⑤ MOK62/...
- ⑥ GBK24/... (cable chain compatible)
- ⑦ REK42/... (standard) or REK41/... (cable chain compatible)

Order codes:

**bold:** mandatory so that the package is combinable

*italics:* recommended/standard

**blue:** must be selected depending on the application

Hint: The examples shown here are meant to help with the dimensioning process. As many parameters interact in this kind of drive package, the examples make no claim to be complete.

ETH - Electro Cylinder  
Order Code

## Order Code

	1	2	3	4	5	6	7	8	9	10	11	12
Example	ETH	050	M05	A	1	K1B	F	M	N	0200	A	Uxx

### 1 Series

**ETH** Electro Cylinder

### 2 Frame size

<b>032</b>	ISO 32
<b>050</b>	ISO 50
<b>080</b>	ISO 80
<b>100</b>	ISO 100
<b>125</b>	ISO 125

### 3 Screw lead Mxx in mm

<b>M05</b>	for ETH032, ETH050, ETH080
<b>M10</b>	for ETH032, ETH050, ETH080, ETH100, ETH125
<b>M16</b>	for ETH032
<b>M20</b>	for ETH050, ETH100, ETH125

### 4 Motor mounting position, housing orientation, groove orientation <sup>1)</sup>

<b>A</b>		Inline + groove for initiator 3 & 9 o'clock (standard)
<b>B</b>		Inline + groove for initiator 6 & 12 o'clock
<b>C</b>		Parallel 12 o'clock / groove for initiator 3 & 9 o'clock
<b>D</b>		Parallel 12 o'clock / groove for initiator 6 & 12 o'clock
<b>E</b>		Parallel 3 o'clock / groove for initiator 3 & 9 o'clock
<b>G</b>		Parallel 6 o'clock / groove for initiator 3 & 9 o'clock
<b>J</b>		Parallel 9 o'clock / groove for initiator 3 & 9 o'clock
<b>K</b>		Parallel 9 o'clock / groove for initiator 6 & 12 o'clock

### 5 Relubrication option <sup>2), 3)</sup>

in combination with motor mounting position, housing orientation, groove orientation

<b>1</b>	No additional relubrication hole (standard) (not with 3 o'clock motor mounting)		
	<b>ETH032</b>	<b>ETH050</b>	<b>ETH080/ETH100/ETH125</b>
	A, B, C, D, G, J, K	A, B, C, D, G, J, K	A, C, E, G, J
<b>2</b>	Relubricating hole in the profile 12 o'clock		
	<b>ETH032</b>	<b>ETH050</b>	<b>ETH080/ETH100/ETH125</b>
	A, C, E, G, J	B, D, K	A, C, E, G, J
<b>3</b>	Relubricating hole in the profile 3 o'clock		
	<b>ETH032</b>	<b>ETH050</b>	<b>ETH080/ETH100/ETH125</b>
	B, D, K	A, C, E, G, J	A, C, E, G, J
<b>4</b>	Relubricating hole in the profile 6 o'clock		
	<b>ETH032</b>	<b>ETH050</b>	<b>ETH080/ETH100/ETH125</b>
	A, C, E, G, J	B, D, K	A, C, E, G, J
<b>5</b>	Relubricating hole in the profile 9 o'clock		
	<b>ETH032</b>	<b>ETH050</b>	<b>ETH080/ETH100/ETH125</b>
	B, D, K	A, C, E, G, J	A, C, E, G, J

### 6 Motor flange <sup>4)</sup>

For ETH ATEX version use only ATEX certified motors/gearboxes (e.g. EX motor series)  
ETH032/ETH050/ETH080: Motors always with key groove on the output shaft.  
ETH100/ETH125: Motors always without key groove on the output shaft

	ETH032	ETH050	ETH080	ETH100	ETH125	
						With motor flange for Parker motor:
<b>K1B</b>	•	•				SMH60-B5/11, NX3 or EX3 (only for ETH032)
<b>K1C</b>	•	•				SMH82-B8/14
<b>K1D</b>	•	•				SMH82-B8/19, MH105-B9/19 (old HJ96 Motor), NX4 or EX4 (only for ETH050)
<b>K1E</b>	•	•				SMH82-B5/19, SMH100-B5/19, MH105-B5/19
<b>K1F</b>	•					SMH100-B5/14 <sup>5)</sup>
<b>K1J</b>	•	•				SMH115-B7/24, MH105-B6/24, NX6 or EX6
<b>K1K</b>	•	•				SMH142-B5/24, MH145-B5/24
<b>K1L</b>	•	•				MH205-B5/38, SMH170-B5/38
<b>K1M</b>	•	•				MH265-B5/48
						With gearbox flange for Parker gearbox:
<b>P1A</b>	•	•				Pilot Ø50*11, PCD 70mm with Ø5,5mm fixing holes, shaft Ø16x40mm
<b>P1B</b>	•	•				Pilot Ø80*15, PCD 100mm with Ø6,5mm fixing holes, shaft Ø22x52mm
<b>P1C</b>	•	•				Pilot Ø110*16, PCD 130mm with Ø8,5mm fixing holes, shaft Ø32x68mm
<b>P1D</b>	•	•				Pilot Ø130*20, PCD 165mm with Ø11mm fixing holes, shaft Ø40x102mm
<b>P1G</b>	•	•				PE3
<b>P1H</b>	•	•				PE4
<b>P1J</b>	•	•				PE5
<b>P1K</b>	•	•				PE7
<b>1xx</b>						Special flange one-piece (customized)
<b>2xx</b>						Special flange two-piece (customized)
<b>3xx</b>						Cylinder inclusive overhung load adapter (customized) ETH032-080 & Parallel motor mount only

Additional motor mounting options on request.  
Before mounting a motor not listed above, please consult the Parker support team at em-motion@parker.com.

### 7 Mounting type

<b>F</b>	Thread on the cylinder body ( <b>standard</b> ) (ETH100, ETH125 does not have a mounting thread on the underside)
<b>B</b>	Foot mounting <sup>6), 7)</sup> (For ETH100, ETH125 only available in protection class option A)
<b>C</b>	Rear Clevis <sup>6)</sup>
<b>D</b>	Centre trunnion mounting (not with motor mounting positions E, F, J, K), for lubricating option "1", the lubrication port is always in 6 o'clock position
<b>G</b>	Mounting Flanges <sup>7)</sup> (only with motor mounting positions A, B, C, D) (For ETH100, ETH125 only available in protection class option A)
<b>J</b>	Front plate <sup>7)</sup> (For ETH125 only available in protection class option A)
<b>X</b>	customized - please contact us

### 8 Thrust rod

<b>M</b>	External thread ( <b>standard</b> )
<b>F</b>	Internal Thread
<b>K</b>	Internal thread (for the reception of the force sensor with external thread) (only for ETH100, ETH125)
<b>S</b>	Spherical Rod Eye (stainless steel with protection class "B" and "C"; standard with protection class "A") (For ETH125 only available in protection class option A)
<b>R</b>	Parallel guiding with ball bushing <sup>8)</sup> (not with motor mounting positions E, F, J, K) (available only in protection class option A)
<b>L</b>	Alignment Coupler (available only in protection class option A)
<b>X</b>	customized - please contact us

### 9 Option

<b>N</b>	Standard
<b>A</b>	Designation for ATEX Cylinder <sup>9) 9)</sup>

### 10 Stroke in mm

	ETH032	ETH050	ETH080	ETH100/ ETH125
<b>XXXX</b>	50...1000	50...1200	100.1600	200...2000
	customized in steps of 1 mm			
<b>0100</b>	Preferred Stroke Lengths (see page 54)			
<b>0200</b>				
<b>0300</b>				
<b>0400</b>				

### 11 Protection class

<b>A</b>	IP54 with galvanized screws
<b>B</b>	IP 54 stainless version with VA screws
<b>C</b>	IP 65 like B + protective lacquer and specially sealed

### 12 Optional

<b>Uxx</b>	Unique Version
	Here, a number for customized cylinders is assigned, please contact us
	with ATEX Cylinders <sup>9)</sup>
<b>000</b>	Standard ATEX Cylinder
<b>xxx</b>	ATEX release xxx ATEX Applications-Identification No. xxx

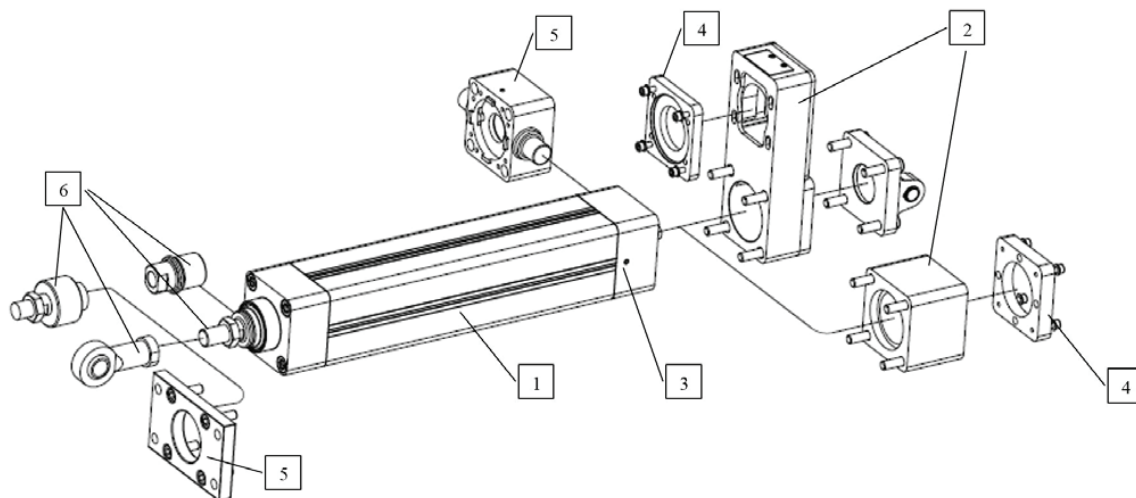
- <sup>1)</sup> ETH080-ETH125 features 2 grooves each on all 4 sides (i.e. Code B=A or D=C, K=J), therefore codes A, C, E, G, J are possible for ETH080-ETH125.
- <sup>2)</sup> With parallel configuration, the motor may block access to the sensors and the lubrication port.
- <sup>3)</sup> Relubrication options 2-5:  
The standard lubrication port is without function.  
In case of actuators with very short strokes, the position of the lubrication port in the center of the profile may not be possible. For more information see mounting instructions.
- <sup>4)</sup> Please check cylinder motor/gearbox combination with the aid of the table "Motor Mounting Options" see page 23).
- <sup>5)</sup> Order Code SMH100-B5/14: "SMH100...ET..." (the motor shaft diameter is replaced by the term "ET") (not in the motors catalog) only with feedback: Resolver, A7
- <sup>6)</sup> Not with motor mounting options A & B.
- <sup>7)</sup> Not for thrust rod R
- <sup>8)</sup> On request for ETH100, ETH125. Please observe the maximum permitted axial traction of the parallel guiding ("parallel guiding" see page 35)
- <sup>9)</sup> Please observe the explanations "ETH - Electro Thrust Cylinder for ATEX Environment" see page 12, "000" for ETH032/050/080, "xxx" for applications specific ATEX release, please contact us.

## Software & Tools

- Actuator database
  - A special actuator database is available in the Compax3 ServoManager. You can simply enter the ETH type code for automatic controller parameterization.
- CAD-Configurator
  - Configure your electro cylinder CAD data online.  
[www.parker.com/eme/eth](http://www.parker.com/eme/eth)



ETH - Electro Cylinder  
Preferred Order Code



ETH032 Preferred cylinder order code with reduced lead time.

	Size	Pitch	Motor orientation	Re-lubrication	Motor mounting	Cylinder mounting	Rod end	ATEX	Stroke	IP protection		
	1	2	3	4	5	6	7	8	9	10	11	
<b>Example</b>	<b>ETH</b>	<b>032</b>	<b>M05</b>	<b>A</b>	<b>1</b>	<b>K1B</b>	<b>F</b>	<b>M</b>	<b>N</b>	<b>0200</b>	<b>A</b>	
										M05	M10	M16
	<b>032</b>	<b>M05</b>	<b>A</b>	<b>1</b>	<b>K1B</b>	<b>F</b>	<b>M</b>	<b>N</b>	<b>0050</b>			<b>A</b>
		<b>M10</b>	<b>B</b>	<b>2</b>	<b>K1C</b>	<b>B</b>	<b>F</b>	<b>A</b>	<b>0100</b>	<b>0100</b>	<b>0100</b>	<b>B</b>
		<b>M16</b>	<b>C</b>	<b>3</b>	<b>K1D</b>	<b>C</b>	<b>K</b>		<b>0150</b>			<b>C</b>
			<b>D</b>	<b>4</b>	<b>K1E</b>	<b>D</b>	<b>S</b>		<b>0200</b>	<b>0200</b>		
			<b>E</b>	<b>5</b>	<b>K1F</b>	<b>G</b>	<b>R</b>		<b>0300</b>	<b>0300</b>		
			<b>G</b>		<b>K1J</b>	<b>J</b>	<b>L</b>		<b>0400</b>	<b>0400</b>		
			<b>J</b>		<b>K1K</b>				others			
			<b>K</b>		<b>K1L</b>							
					<b>K1M</b>							
					<b>P1A</b>							
					<b>P1B</b>							
					<b>P1C</b>							
					<b>P1D</b>							
					<b>P1G</b>							
					<b>P1H</b>							
					<b>P1J</b>							
					<b>P1K</b>							

**Black** Options with reduced lead time. Only ETH cylinders with 100% of "black" options will be shipped within reduced lead time.

**Grey** Options with standard lead time. ETH cylinders including one or more "grey" options will be shipped within standard lead time.

**Examples:** **ETH032M05A1K1BFMN0200A** Reduced lead time (all options are "black")

**ETH032M05A1K1BFRN0200A** Standard lead time

**ETH050 Preferred cylinder order code with reduced lead time.**

	1	2	3	4	5	6	7	8	9	10	11
	Size	Pitch	Motor orientation	Re-lubrication	Motor mounting	Cylinder mounting	Rod end	ATEX	Stroke	IP protection	
<b>Example</b>	<b>ETH</b>	<b>050</b>	<b>M05</b>	<b>A</b>	<b>1</b>	<b>K1B</b>	<b>F</b>	<b>M</b>	<b>N</b>	<b>0100</b>	<b>A</b>
									M05	M10	
	<b>050</b>	<b>M05</b>	<b>A</b>	<b>1</b>	<b>K1B</b>	<b>F</b>	<b>M</b>	<b>N</b>	<b>0050</b>		<b>A</b>
		<b>M10</b>	<b>B</b>	<b>2</b>	<b>K1C</b>	<b>B</b>	<b>F</b>	<b>A</b>	<b>0100</b>	<b>0100</b>	<b>B</b>
			<b>C</b>	<b>3</b>	<b>K1D</b>	<b>C</b>	<b>K</b>		<b>0150</b>		<b>C</b>
			<b>D</b>	<b>4</b>	<b>K1E</b>	<b>D</b>	<b>S</b>		<b>0200</b>	<b>0200</b>	
			<b>E</b>	<b>5</b>	<b>K1F</b>	<b>G</b>	<b>R</b>			<b>0250</b>	
			<b>G</b>		<b>K1J</b>	<b>J</b>	<b>L</b>		<b>0300</b>	<b>0300</b>	
			<b>J</b>		<b>K1K</b>				<b>0400</b>	<b>0400</b>	
			<b>K</b>		<b>K1L</b>					<b>0600</b>	
					<b>K1M</b>				others		
					<b>P1A</b>						
					<b>P1B</b>						
					<b>P1C</b>						
					<b>P1D</b>						
					<b>P1G</b>						
					<b>P1H</b>						
					<b>P1J</b>						
					<b>P1K</b>						

**Black** Options with reduced lead time. Only ETH cylinders with 100% of "black" options will be shipped within reduced lead time.

**Grey** Options with standard lead time. ETH cylinders including one or more "grey" options will be shipped within standard lead time.

**Examples:** **ETH050M05A1K1BFMN0100A** Reduced lead time (all options are "black")

**ETH050M05A1K1BFRN0100A** Standard lead time

ETH - Electro Cylinder  
Preferred Order Code

### ETH080 Preferred cylinder order code with reduced lead time.

	1	2	3	4	5	6	7	8	9	10	11
	Size	Pitch	Motor orientation	Re-lubrication	Motor mounting	Cylinder mounting	Rod end	ATEX	Stroke	IP protection	
<b>Example</b>	<b>ETH</b>	<b>080</b>	<b>M05</b>	<b>A</b>	<b>1</b>	<b>K1E</b>	<b>F</b>	<b>M</b>	<b>N</b>	<b>0100</b>	<b>A</b>

	080	M05	A	1	K1B	F	M	N	0100	0100	A
		<b>M10</b>	B	<b>2</b>	K1C	B	F	A	<b>0150</b>	<b>0150</b>	B
			<b>C</b>	3	K1D	<b>C</b>	K		<b>0200</b>	<b>0200</b>	C
			D	4	<b>K1E</b>	<b>D</b>	<b>S</b>		<b>0300</b>	<b>0300</b>	
			E	5	K1F	G	R			<b>0350</b>	
			G		<b>K1J</b>	<b>J</b>	L		<b>0400</b>	<b>0400</b>	
			J		<b>K1K</b>				<b>0600</b>		
			K		K1L					<b>0700</b>	
					K1M				others		
					P1A						
					<b>P1B</b>						
					P1C						
					P1D						
					P1G						
					<b>P1H</b>						
					P1J						
					P1K						

**Black** Options with reduced lead time. Only ETH cylinders with 100% of "black" options will be shipped within reduced lead time.

**Grey** Options with standard lead time. ETH cylinders including one or more "grey" options will be shipped within standard lead time.

**Examples:** **ETH080M05A1K1EFMN0100A** Reduced lead time (all options are "black")

**ETH080M05A1K1EFRN0100A** Standard lead time







# Parker's Motion & Control Technologies

At Parker, we're guided by a relentless drive to help our customers become more productive and achieve higher levels of profitability by engineering the best systems for their requirements. It means looking at customer applications from many angles to find new ways to create value. Whatever the motion and control technology need, Parker has the experience, breadth of product and global reach to consistently deliver. No company knows more about motion and control technology than Parker. For further info call 00800 27 27 5374



## Aerospace

### Key Markets

Aftermarket services  
Commercial transports  
Engines  
General & business aviation  
Helicopters  
Launch vehicles  
Military aircraft  
Missiles  
Power generation  
Regional transports  
Unmanned aerial vehicles

### Key Products

Control systems & actuation products  
Engine systems & components  
Fluid conveyance systems & components  
Fluid metering, delivery & atomization devices  
Fuel systems & components  
Fuel tank inerting systems  
Hydraulic systems & components  
Thermal management  
Wheels & brakes



## Climate Control

### Key Markets

Agriculture  
Air conditioning  
Construction Machinery  
Food & beverage  
Industrial machinery  
Life sciences  
Oil & gas  
Precision cooling  
Process  
Refrigeration  
Transportation

### Key Products

Accumulators  
Advanced actuators  
CO<sub>2</sub> controls  
Electronic controllers  
Filter driers  
Hand shut-off valves  
Heat exchangers  
Hose & fittings  
Pressure regulating valves  
Refrigerant distributors  
Safety relief valves  
Smart pumps  
Solenoid valves  
Thermostatic expansion valves



## Electromechanical

### Key Markets

Aerospace  
Factory automation  
Life science & medical  
Machine tools  
Packaging machinery  
Paper machinery  
Oil & gas  
Primary metals  
Semiconductor & electronics  
Textile  
Wire & cable

### Key Products

AC/DC drives & systems  
Electric actuators, gantry robots & slides  
Electrohydraulic actuation systems  
Electromechanical actuation systems  
Human machine interface  
Linear motors  
Stepper motors, servo motors, drives & controls  
Structural extrusions



## Filtration

### Key Markets

Aerospace  
Food & beverage  
Industrial plant & equipment  
Life sciences  
Marine  
Mobile equipment  
Oil & gas  
Power generation & renewable energy  
Process  
Transportation  
Water Purification

### Key Products

Analytical gas generators  
Compressed air filters & dryers  
Engine air, coolant, fuel & oil filtration systems  
Fluid condition monitoring systems  
Hydraulic & lubrication filters  
Hydrogen, nitrogen & zero air generators  
Instrumentation filters  
Membrane & fiber filters  
Microfiltration  
Sterile air filtration  
Water desalination & purification filters & systems



## Fluid & Gas Handling

### Key Markets

Aerial lift  
Agriculture  
Bulk chemical handling  
Construction machinery  
Food & beverage  
Fuel & gas delivery  
Industrial machinery  
Life sciences  
Marine  
Mining  
Mobile  
Oil & gas  
Renewable energy  
Transportation

### Key Products

Check valves  
Connectors for low pressure fluid conveyance  
Deep sea umbilicals  
Diagnostic equipment  
Hose couplings  
Industrial hose  
Mooring systems & power cables  
PTFE hose & tubing  
Quick couplings  
Rubber & thermoplastic hose  
Tube fittings & adapters  
Tubing & plastic fittings



## Hydraulics

### Key Markets

Aerial lift  
Agriculture  
Alternative energy  
Construction machinery  
Forestry  
Industrial machinery  
Machine tools  
Marine  
Material handling  
Mining  
Oil & gas  
Power generation  
Refuse vehicles  
Renewable energy  
Truck hydraulics  
Turf equipment

### Key Products

Accumulators  
Cartridge valves  
Electrohydraulic actuators  
Human machine interfaces  
Hybrid drives  
Hydraulic cylinders  
Hydraulic motors & pumps  
Hydraulic systems  
Hydraulic valves & controls  
Hydrostatic steering  
Integrated hydraulic circuits  
Power take-offs  
Power units  
Rotary actuators  
Sensors



## Pneumatics

### Key Markets

Aerospace  
Conveyor & material handling  
Factory automation  
Life science & medical  
Machine tools  
Packaging machinery  
Transportation & automotive

### Key Products

Air preparation  
Brass fittings & valves  
Manifolds  
Pneumatic accessories  
Pneumatic actuators & grippers  
Pneumatic valves & controls  
Quick disconnects  
Rotary actuators  
Rubber & thermoplastic hose & couplings  
Structural extrusions  
Thermoplastic tubing & fittings  
Vacuum generators, cups & sensors



## Process Control

### Key Markets

Alternative fuels  
Biopharmaceuticals  
Chemical & refining  
Food & beverage  
Marine & shipbuilding  
Medical & dental  
Microelectronics  
Nuclear Power  
Offshore oil exploration  
Oil & gas  
Pharmaceuticals  
Power generation  
Pulp & paper  
Steel  
Water/wastewater

### Key Products

Analytical instruments  
Analytical sample conditioning products & systems  
Chemical injection fittings & valves  
Fluoropolymer chemical delivery fittings, valves & pumps  
High purity gas delivery fittings, valves, regulators & digital flow controllers  
Industrial mass flow meters/controllers  
Permanent no-weld tube fittings  
Precision industrial regulators & flow controllers  
Process control double block & bleeds  
Process control fittings, valves, regulators & manifold valves



## Sealing & Shielding

### Key Markets

Aerospace  
Chemical processing  
Consumer  
Fluid power  
General industrial  
Information technology  
Life sciences  
Microelectronics  
Military  
Oil & gas  
Power generation  
Renewable energy  
Telecommunications  
Transportation

### Key Products

Dynamic seals  
Elastomeric o-rings  
Electro-medical instrument design & assembly  
EMI shielding  
Extruded & precision-cut, fabricated elastomeric seals  
High temperature metal seals  
Homogeneous & inserted elastomeric shapes  
Medical device fabrication & assembly  
Metal & plastic retained composite seals  
Shielded optical windows  
Silicone tubing & extrusions  
Thermal management  
Vibration dampening

## Parker Worldwide

### Europe, Middle East, Africa

**AE – United Arab Emirates, Dubai**  
Tel: +971 4 8127100  
parker.me@parker.com

**AT – Austria, St. Florian**  
Tel: +43 (0)7224 66201  
parker.austria@parker.com

**AZ – Azerbaijan, Baku**  
Tel: +994 50 2233 458  
parker.azerbaijan@parker.com

**BE/NL/LU – Benelux, Hendrik Ido Ambacht**  
Tel: +31 (0)541 585 000  
parker.nl@parker.com

**BG – Bulgaria, Sofia**  
Tel: +359 2 980 1344  
parker.bulgaria@parker.com

**BY – Belarus, Minsk**  
Tel: +48 (0)22 573 24 00  
parker.poland@parker.com

**CH – Switzerland, Etoy**  
Tel: +41 (0)21 821 87 00  
parker.switzerland@parker.com

**CZ – Czech Republic, Klecany**  
Tel: +420 284 083 111  
parker.czechrepublic@parker.com

**DE – Germany, Kaarst**  
Tel: +49 (0)2131 4016 0  
parker.germany@parker.com

**DK – Denmark, Ballerup**  
Tel: +45 43 56 04 00  
parker.denmark@parker.com

**ES – Spain, Madrid**  
Tel: +34 902 330 001  
parker.spain@parker.com

**FI – Finland, Vantaa**  
Tel: +358 (0)20 753 2500  
parker.finland@parker.com

**FR – France, Contamine s/Arve**  
Tel: +33 (0)4 50 25 80 25  
parker.france@parker.com

**GR – Greece, Piraeus**  
Tel: +30 210 933 6450  
parker.greece@parker.com

**HU – Hungary, Budaörs**  
Tel: +36 23 885 470  
parker.hungary@parker.com

**IE – Ireland, Dublin**  
Tel: +353 (0)1 466 6370  
parker.ireland@parker.com

**IL – Israel**  
Tel: +39 02 45 19 21  
parker.israel@parker.com

**IT – Italy, Corsico (MI)**  
Tel: +39 02 45 19 21  
parker.italy@parker.com

**KZ – Kazakhstan, Almaty**  
Tel: +7 7273 561 000  
parker.easteurope@parker.com

**NO – Norway, Asker**  
Tel: +47 66 75 34 00  
parker.norway@parker.com

**PL – Poland, Warsaw**  
Tel: +48 (0)22 573 24 00  
parker.poland@parker.com

**PT – Portugal**  
Tel: +351 22 999 7360  
parker.portugal@parker.com

**RO – Romania, Bucharest**  
Tel: +40 21 252 1382  
parker.romania@parker.com

**RU – Russia, Moscow**  
Tel: +7 495 645-2156  
parker.russia@parker.com

**SE – Sweden, Borås**  
Tel: +46 (0)8 59 79 50 00  
parker.sweden@parker.com

**SK – Slovakia, Banská Bystrica**  
Tel: +421 484 162 252  
parker.slovakia@parker.com

**SL – Slovenia, Novo Mesto**  
Tel: +386 7 337 6650  
parker.slovenia@parker.com

**TR – Turkey, Istanbul**  
Tel: +90 216 4997081  
parker.turkey@parker.com

**UA – Ukraine, Kiev**  
Tel: +48 (0)22 573 24 00  
parker.poland@parker.com

**UK – United Kingdom, Warwick**  
Tel: +44 (0)1926 317 878  
parker.uk@parker.com

**ZA – South Africa, Kempton Park**  
Tel: +27 (0)11 961 0700  
parker.southafrica@parker.com

### North America

**CA – Canada, Milton, Ontario**  
Tel: +1 905 693 3000

**US – USA, Cleveland**  
Tel: +1 216 896 3000

### Asia Pacific

**AU – Australia, Castle Hill**  
Tel: +61 (0)2-9634 7777

**CN – China, Shanghai**  
Tel: +86 21 2899 5000

**HK – Hong Kong**  
Tel: +852 2428 8008

**IN – India, Mumbai**  
Tel: +91 22 6513 7081-85

**JP – Japan, Tokyo**  
Tel: +81 (0)3 6408 3901

**KR – South Korea, Seoul**  
Tel: +82 2 559 0400

**MY – Malaysia, Shah Alam**  
Tel: +60 3 7849 0800

**NZ – New Zealand, Mt Wellington**  
Tel: +64 9 574 1744

**SG – Singapore**  
Tel: +65 6887 6300

**TH – Thailand, Bangkok**  
Tel: +662 186 7000

**TW – Taiwan, Taipei**  
Tel: +886 2 2298 8987

### South America

**AR – Argentina, Buenos Aires**  
Tel: +54 3327 44 4129

**BR – Brazil, Sao Jose dos Campos**  
Tel: +55 800 727 5374

**CL – Chile, Santiago**  
Tel: +56 2 623 1216

**MX – Mexico, Toluca**  
Tel: +52 72 2275 4200



### EMEA Product Information Centre

Free phone: 00 800 27 27 5374

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### US Product Information Centre

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